

Math 244-Syllabus

Textbook: Elementary Linear Algebra with Supplemental Applications, 11th Edition

By Howard Anton and Chris Rorres

Chapter 1

1.1 Introduction to Systems of Linear Equations

1.2 Gaussian Elimination

1.3 Matrices and Matrix Operations

1.4 Inverses and Algebraic Properties of Matrices (Proofs of Theorems 1.4.4, 1.4.6, and 1.4.9 are included)

1.5 Elementary Matrices and a Method for Finding A^{-1}

1.6 More on Linear Systems and Invertible Matrices

1.7 Diagonal, Triangular and Symmetric Matrices

Chapter 2

2.1 Determinants by Cofactor Expansion

2.2 Evaluating Determinants by Row Reduction

2.3 Properties of the Determinants and Cramer's Rule

Chapter 3

3.1 Vectors in 2-Space, 3-Space and n-Space (From Definition1, Page 136).

3.2 Norm, Dot Product and Distance in R^n (The proof of Theorem 3.2.6 and Theorem 3.2.7 is included). **Example 7 is NOT included.**

3.3 Orthogonality (Definition1+ orthogonal and orthonormal set definition, Example1 (a), Theorem 3.3.3, Example 6)

Chapter 4

4.1 Real Vector Spaces (Exercise 11 is solved in the lecture)

4.2 Subspaces (All except Example 12, the proof of Theorem 4.2.4 is included)

4.3 Linear Independence (Proof of Theorem 4.3.3 is included)

4.4 Coordinates and Basis (From Definition 1)

4.5 Dimension (Exercise 7 (d) is solved in the lecture)

4.7 Row Space, Column Space and Null space

4.8 Rank, Nullity and the Fundamental Matrix Spaces (The proof of theorem 4.8.5 is included). (The concept of orthogonal complement is NOT included).

4.9 Matrix Transformations from R^n to R^m (Expansion and Compressions, Shears and Orthogonal projections on lines through the origin are NOT included)

4.10 Properties of Matrix Transformations

Chapter 5

5.1 Eigenvalues and Eigenvectors