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# **Logic and Computer Design Fundamentals**

## **Chapter 7 – Registers and Register Transfers**

### **Part 1 – Registers, Microoperations and Implementations**

**Charles Kime & Thomas Kaminski**

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# Overview

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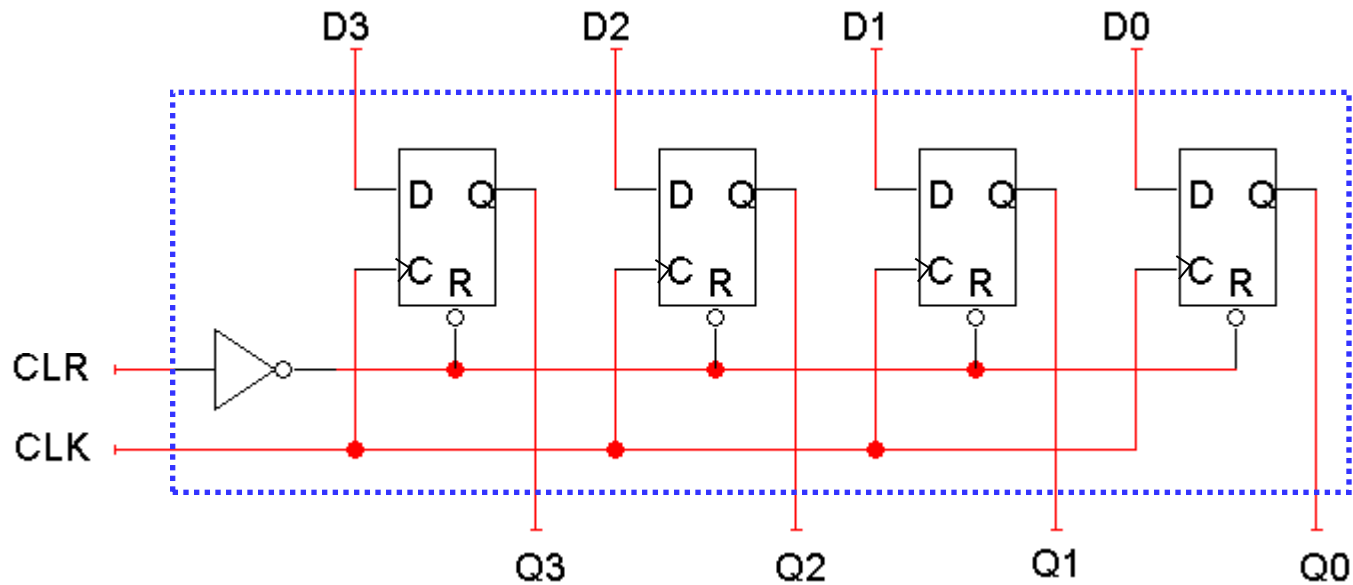
- **Part 1 - Registers, Microoperations and Implementations**
  - **Registers and load enable**
  - **Register transfer operations**
  - **Microoperations - arithmetic, logic, and shift**
  - **Microoperations on a single register**
    - **Multiplexer-based transfers**
    - **Shift registers**
- **Part 2 - Counters, Register Cells, Buses, & Serial Operations**
- **Part 3 – Control of Register Transfers**

# Registers

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- **Register** – a collection of binary storage elements
- In theory, a register is sequential logic which can be defined by a state table
- More often, think of a register as storing a vector of binary values
- Frequently used to perform simple data storage and data movement and processing operations

# Registers



# Example: 2-bit Register

- How many states are there?  $2^2=4$
- How many input combinations?  $2^2=4$
- How many output combinations?  $2^2=4$
- What is the output function?

$$Y_1 = A_1$$

$$Y_0 = A_0$$

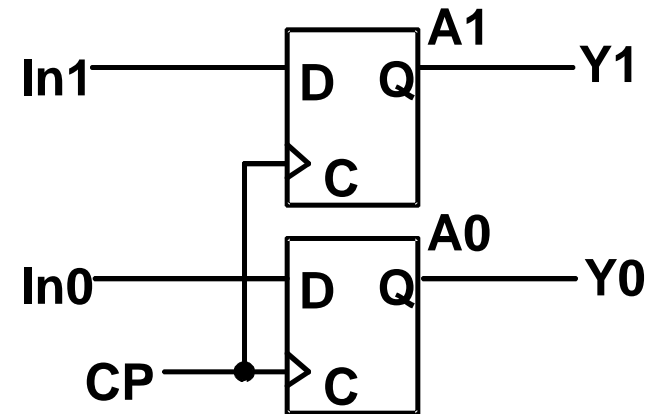
- What is the next state function?

$$A_1(t+1) = IN_1$$

$$A_0(t+1) = IN_0$$

- Moore or Mealy?

**Moore**



State Table

Current State  $A_1 A_0$	Next State $A_1(t+1) A_0(t+1)$ For $IN_1 IN_0 =$				Output (= $A_1 A_0$ )	
	00	01	10	11	$Y_1$	$Y_0$
	0	0	1	1		
0 0	00	01	10	11	0	0
0 1	00	01	10	11	0	1
1 0	00	01	10	11	1	0
1 1	00	01	10	11	1	1

- What are the quantities above for an  $n$ -bit register? **States =  $2^n$**   
**Input Combinations =  $2^n$**   
**Output Combinations =  $2^n$**

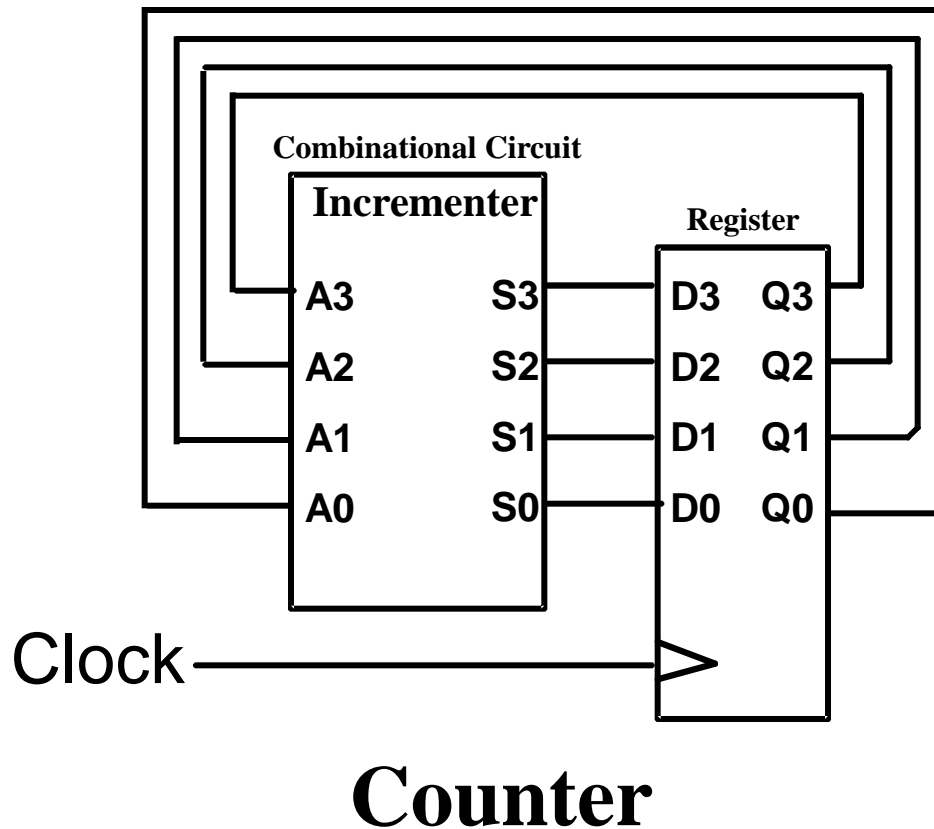
# Register Design Models

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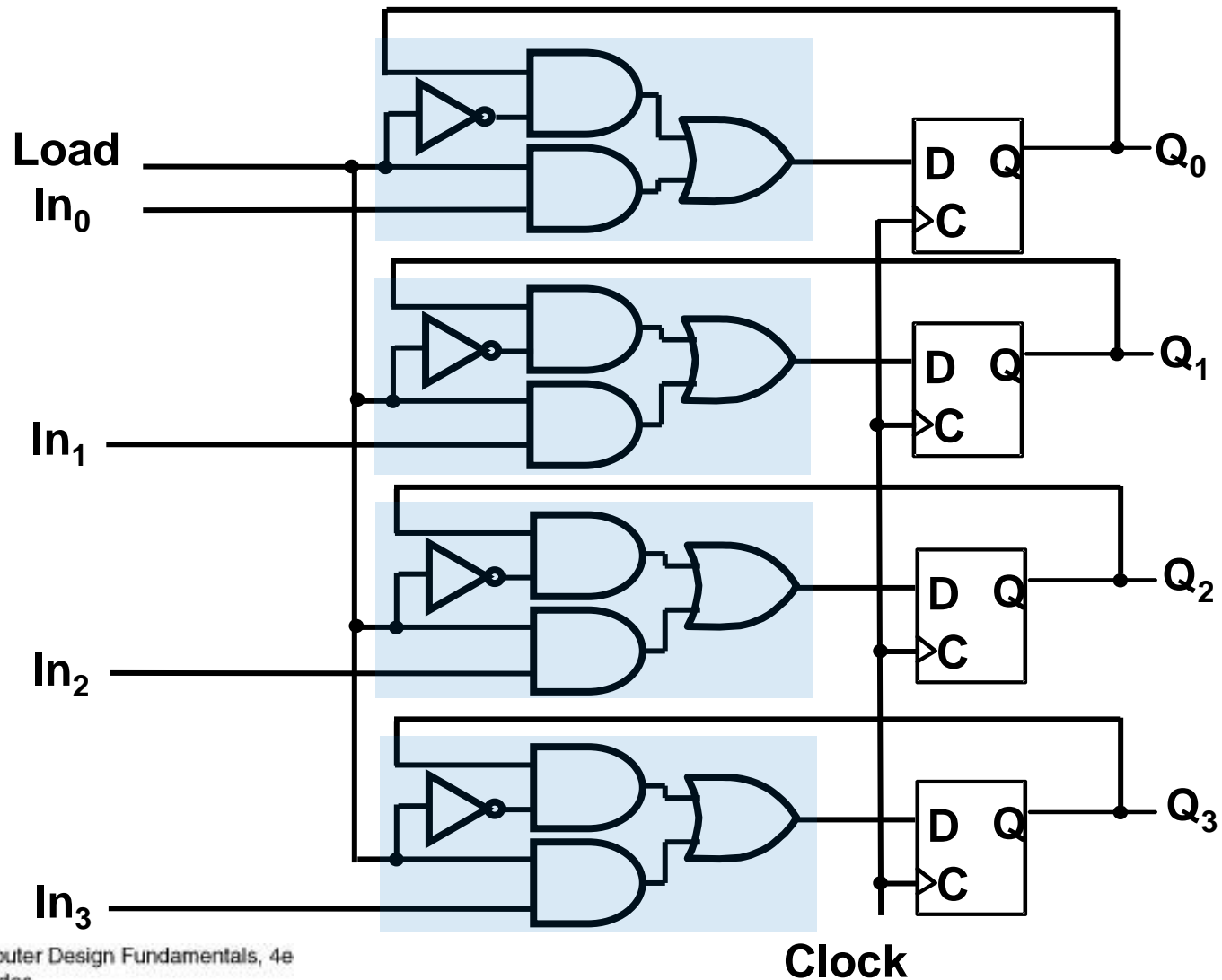
- Due to the large numbers of states and input combinations as  $n$  becomes large, the state diagram/state table model is not feasible!
- What are methods we can use to design registers?
  - Add predefined combinational circuits to registers
    - Example: To count up, connect the register flip-flops to an incrementer
  - Design individual cells using the state diagram/state table model and combine them into a register
    - A 1-bit cell has just two states
    - Output is usually the state variable

# Add Combinational Circuits to Registers

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# Design Individual Cells





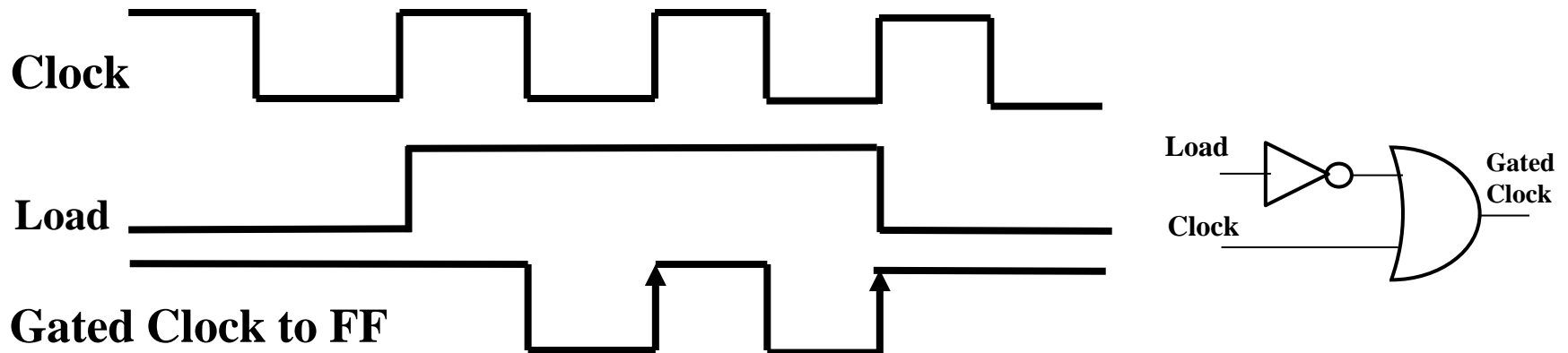
# Register Storage

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- **Expectations:**
  - **A register can store information for multiple clock cycles**
  - **To “store” or “load” information should be controlled by a signal**
- **Reality:**
  - **A D flip-flop register loads information on every clock cycle**
- **Realizing expectations:**
  1. **Use a signal to block the clock to the register,**
  2. **Use a signal to control feedback of the output of the register back to its inputs, or**
  3. **Use other SR or JK flip-flops, that for (0,0) applied, store their state**
- **Load is a frequent name for the signal that controls register storage and loading**
  - **Load = 1: Loads input values (load new values)**
  - **Load = 0: Loads register contents (hold current values)**

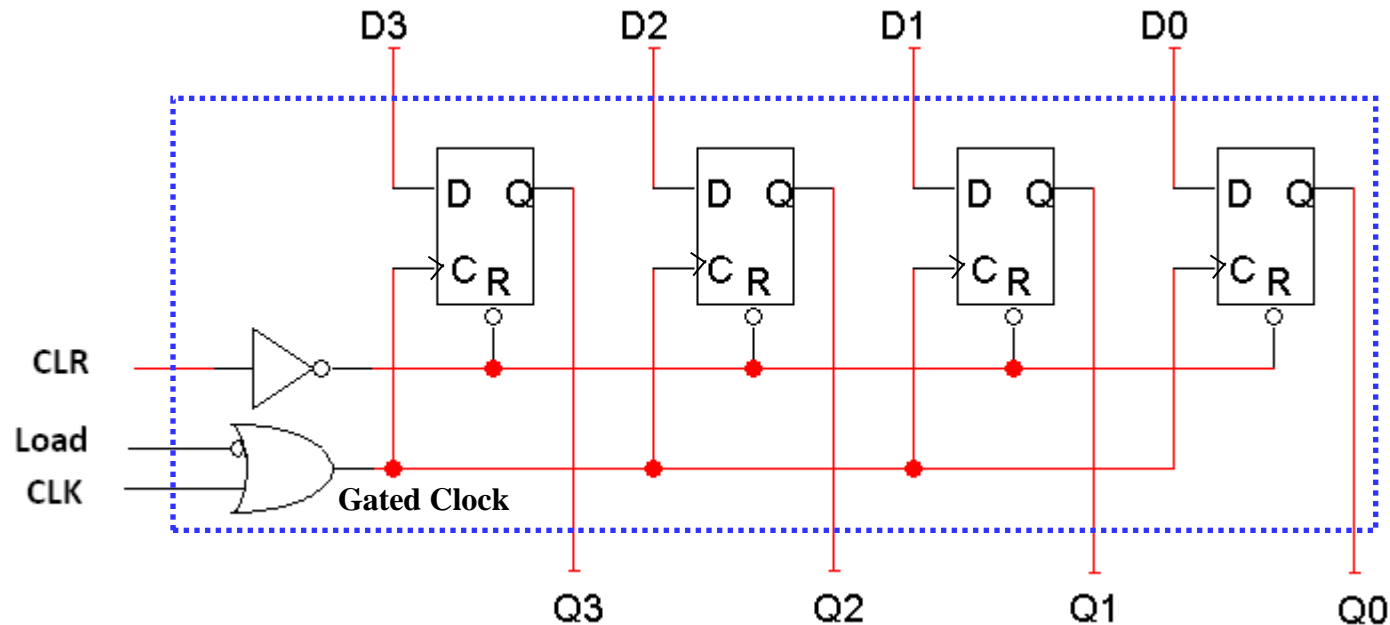
# Registers with Clock Gating

- The ***Load*** signal enables the clock signal to pass through if 1 and prevents the clock signal from passing through if 0.
- **Example:** For Positive Edge-Triggered or Negative Pulse Master-Slave Flip-flop:



- What logic is needed for gating?  **$\text{Gated Clock} = \text{Clock} + \overline{\text{Load}}$**
- What is the problem? **Clock Skew of gated clocks with respect to clock or each other**

# Registers with Clock Gating



# Registers with Load-Controlled Feedback

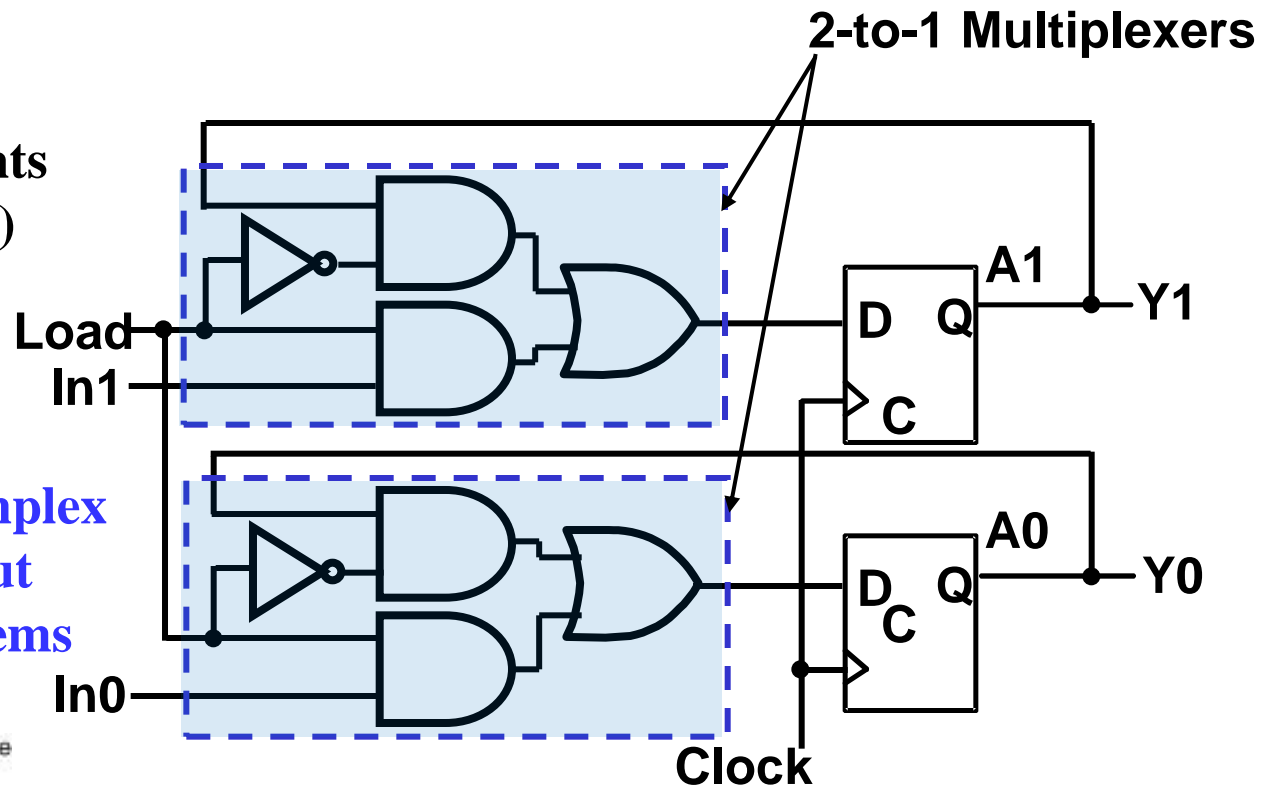
- A more reliable way to selectively load a register:
  - Run the clock continuously, and
  - Selectively use a load control to change the register contents.

- Example: 2-bit register with Load Control:

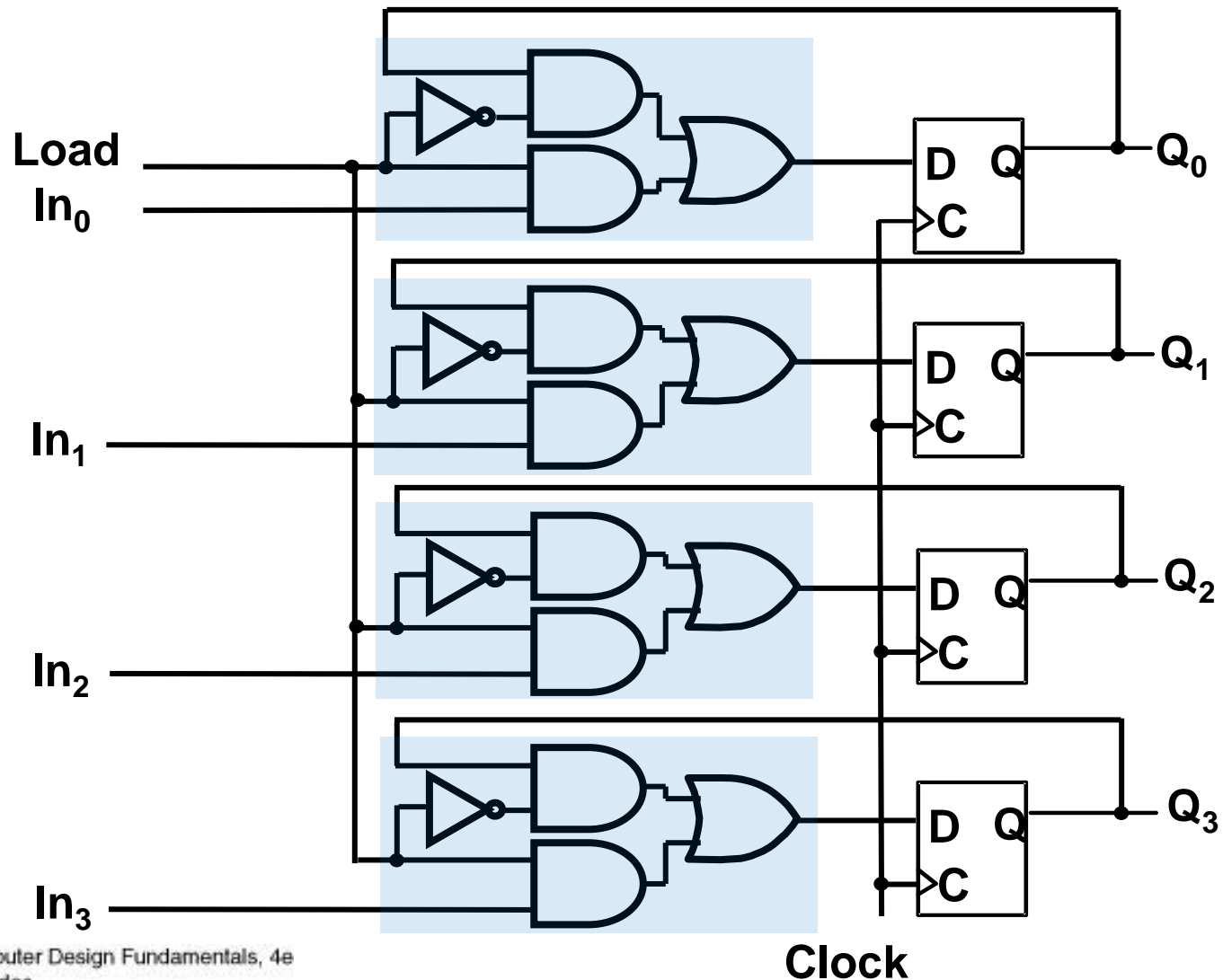
- For **Load = 0**, loads register contents (hold current values)

- For **Load = 1**, loads input values (load new values)

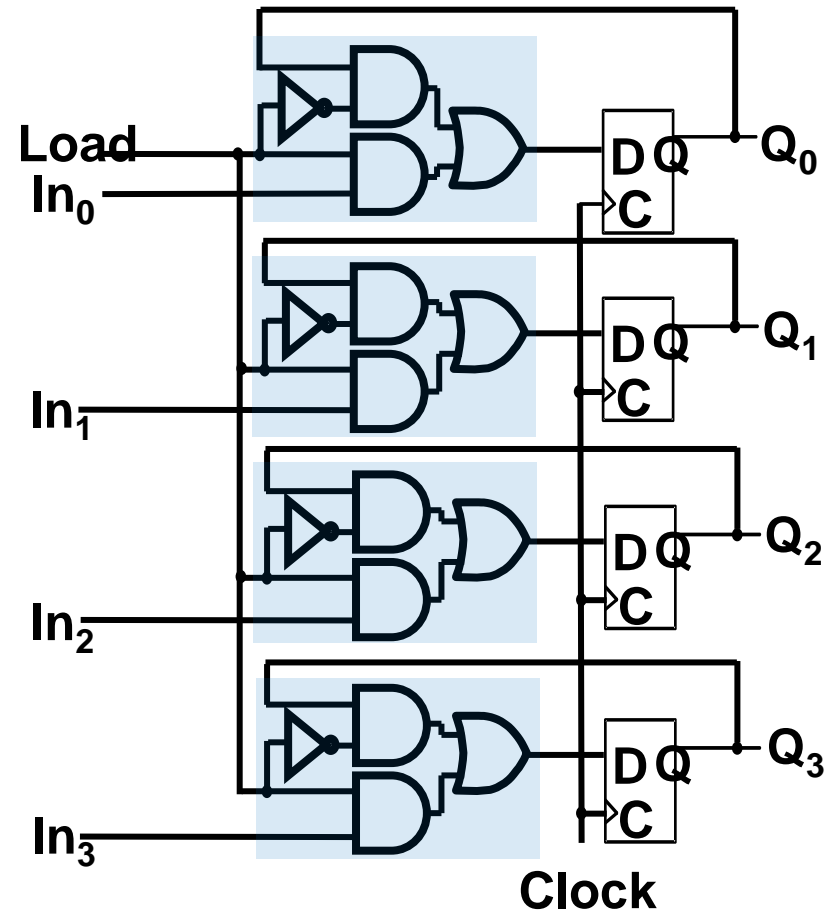
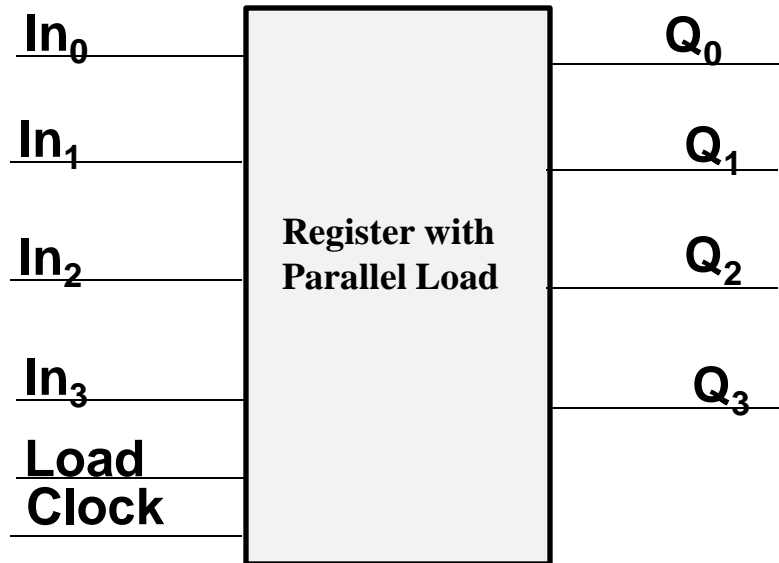
- Hardware more complex than clock gating, but free of timing problems



# Registers with Load-Controlled Feedback



# Registers with Load-Controlled Feedback

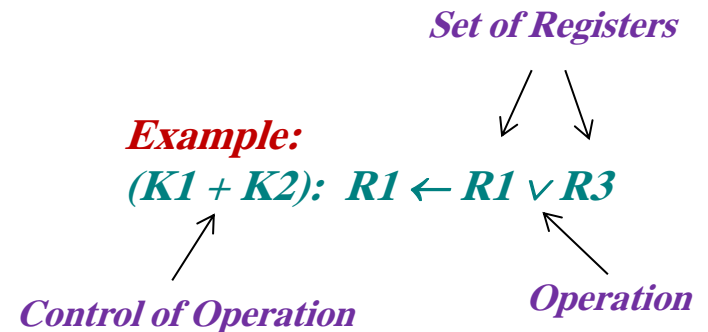


# Register Transfer Operations

- **Register Transfer Operations** – **The movement and processing of data stored in registers**

- **Three basic components:**

- Set of Registers
- Operations
- Control of Operations



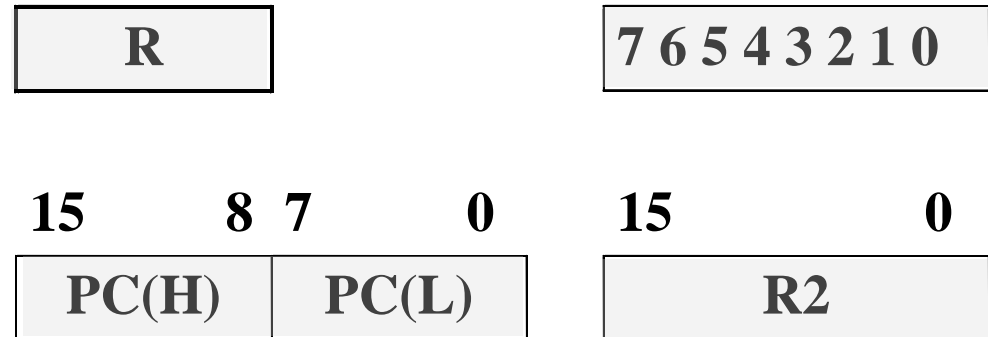
- **Elementary Operations:**

- load, count, shift, add, bitwise "OR", etc.

- Elementary operations called ***microoperations***

# Register Notation

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- **Letters and numbers** – denotes a register (ex. R2, PC, IR)
- **Parentheses ( )** – denotes a range of register bits

**Example:** R1(1), PC(7:0), PC(L)

- **Arrow ( $\leftarrow$ )** – denotes data transfer

**Example:** R1  $\leftarrow$  R2, PC(L)  $\leftarrow$  R0

- **Comma** – separates parallel operations
- **Brackets [ ]** – Specifies a memory address

**Example:** R0  $\leftarrow$  M[AR], R3  $\leftarrow$  M[PC]



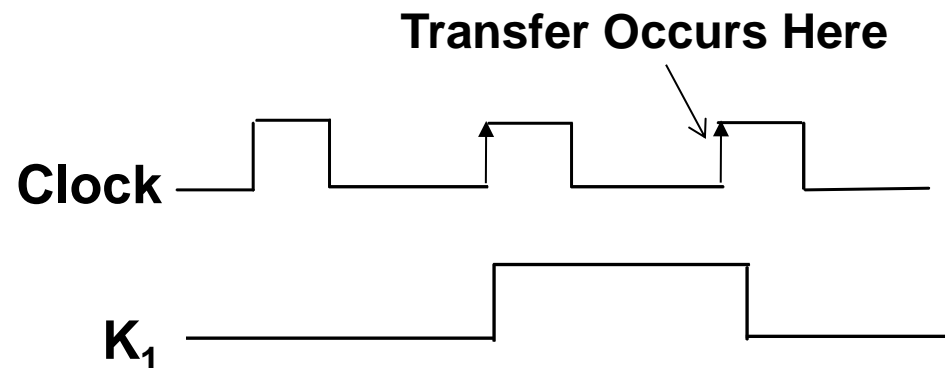
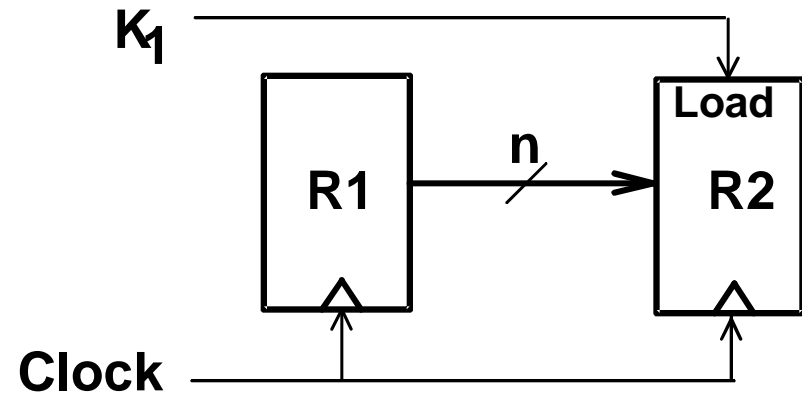
# Conditional Transfer

- If ( $K_1 = 1$ ) then ( $R2 \leftarrow R1$ )

is shortened to

$K_1: (R2 \leftarrow R1)$

*where  $K_1$  is a control variable specifying a conditional execution of the microoperation.*



# Microoperations

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## ▪ Logical Groupings:

- **Transfer** - move data from one register to another
- **Arithmetic** - perform arithmetic on data in registers
- **Logic** - manipulate data or use bitwise logical operations
- **Shift** - shift data in registers

### Arithmetic operations

+ Addition  
– Subtraction  
\* Multiplication  
/ Division

### Logical operations

∨ Logical OR  
∧ Logical AND  
⊕ Logical Exclusive OR  
– Not

# Example Microoperations

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- **Add** the content of R1 to the content of R2 and place the result in R1.

$$R1 \leftarrow R1 + R2$$

- **Multiply** the content of R1 by the content of R6 and place the result in PC.

$$PC \leftarrow R1 * R6$$

- **Exclusive OR** the content of R1 with the content of R2 and place the result in R1.

$$R1 \leftarrow R1 \oplus R2$$

# Example Microoperations (Continued)

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- Take the **1's Complement** of the contents of R2 and place it in the PC.

$$PC \leftarrow \overline{R2}$$

- On condition  $K_1$  OR  $K_2$ , the content of R1 is Logic **bitwise Ored** with the content of R3 and the result placed in R1.

$$(K1 + K2): R1 \leftarrow R1 \vee R3$$

- **NOTES:**

"+" (as in  $K_1 + K_2$ ) and means "OR."

In  $R1 \leftarrow R1 + R3$ , + means "plus."

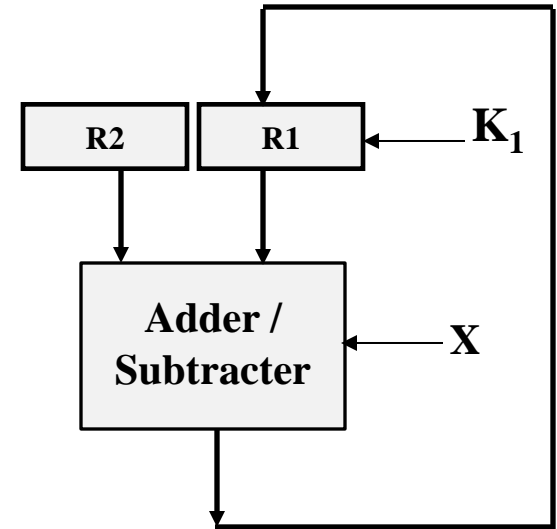
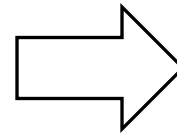
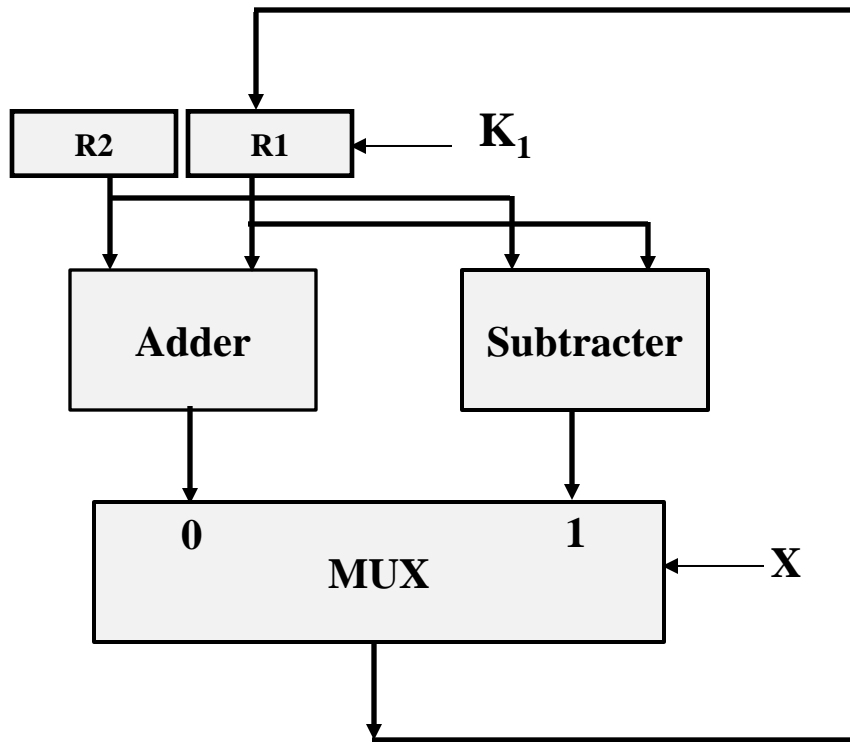
# Control Expressions

- The **control expression** for an operation **appears to the left of the operation and is separated from it by a colon**
- Control expressions specify the **logical condition** for the operation to occur
- Control expression values of:
  - **Logic "1" -- the operation occurs.**
  - **Logic "0" -- the operation is does not occur.**
- **Example:**  
 $\overline{X} K_1 : R1 \leftarrow R2 + R1$   
 $X K_1 : R1 \leftarrow R2 + \overline{R1} + 1$
- Variable  $K_1$  enables the add or subtract operation.
- If  $\underline{X} = 0$ , then  $\overline{X} = 1$  so  $\overline{X} K_1 = 1$ , activating the addition of  $R1$  and  $R2$ .
- If  $X = 1$ , then  $X K_1 = 1$ , activating the addition of  $R2$  and the two's complement of  $R1$  (subtract).

# Arithmetic Microoperations

$\overline{X} K_1: R1 \leftarrow R2 + R1$

$X K_1: R1 \leftarrow R2 + \overline{R1} + 1$

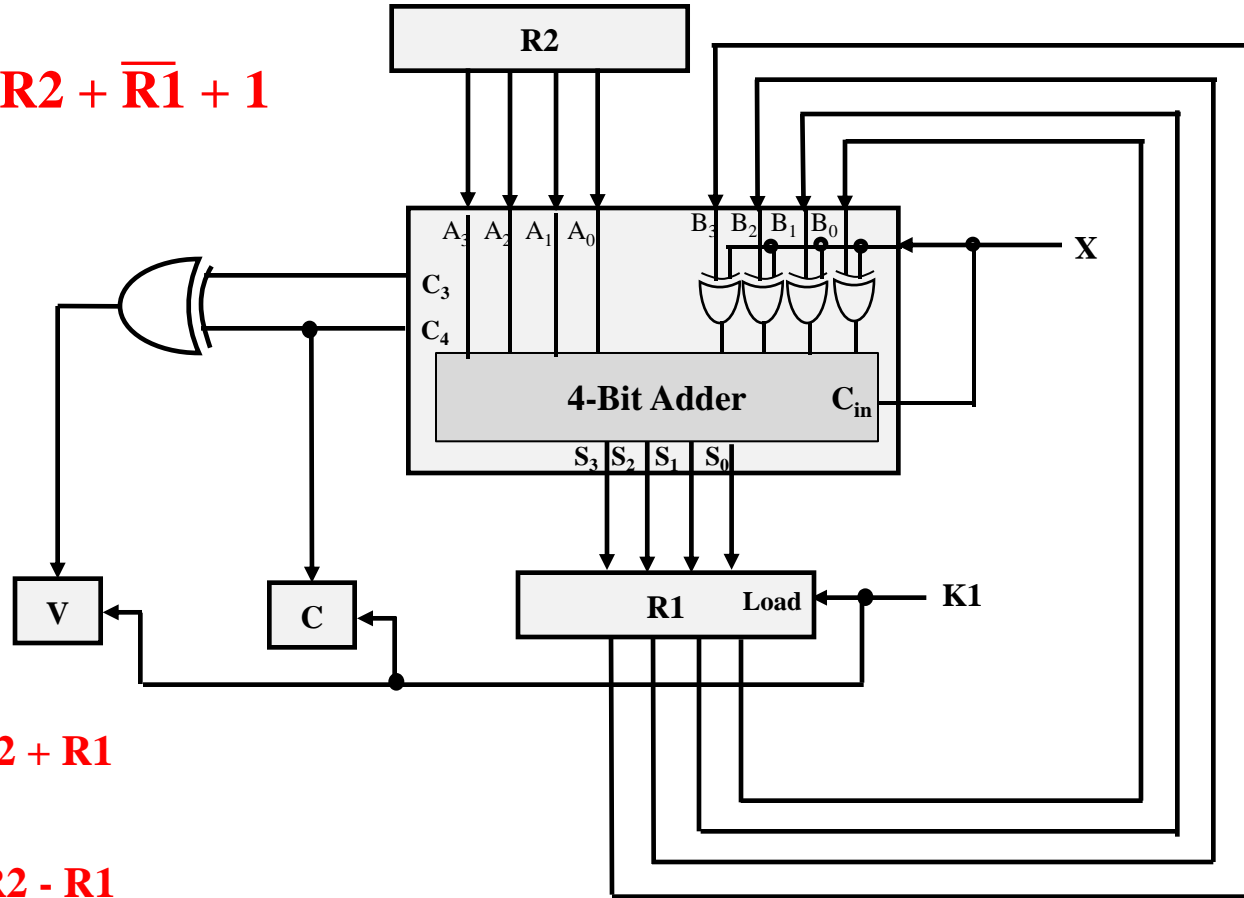




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**$\bar{X} K_1$ :  $R1 \leftarrow R2 + R1$**

**X K<sub>1</sub>:**    **R1 ← R2 +  $\overline{\text{R1}}$  + 1**


$$\mathbf{X} = \begin{cases} 0 & \blacktriangleright \mathbf{R1} \leftarrow \mathbf{R2} + \mathbf{R1} \\ 1 & \blacktriangleright \mathbf{R1} \leftarrow \mathbf{R2} - \mathbf{R1} \end{cases}$$



# Two's Complement Arithmetic

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$$(9)_{10} = (0\ 1001)_2 \rightarrow (-9)_{10} = (1\ 0111)_2$$

$$(4)_{10} = (0\ 0100)_2 \rightarrow (-4)_{10} = (1\ 1100)_2$$

$$9 - 4 = 9 + (-4) = (0\ 1001)_2 + (1\ 1100)_2$$

1 1 0 0 0

0 1001

+

1 1100

---

0 0101  $\rightarrow (5)_{10}$

# Two's Complement Arithmetic

---

$$(9)_{10} = (0\ 1001)_2 \rightarrow (-9)_{10} = (1\ 0111)_2$$

$$(4)_{10} = (0\ 0100)_2 \rightarrow (-4)_{10} = (1\ 1100)_2$$

$$4 - 9 = 4 + (-9) = (0\ 0100)_2 + (1\ 0111)_2$$

0 0 1 0 0

0 0100

+

1 0111

---

1 1011  $\rightarrow (-5)_{10}$

# Two's Complement Arithmetic

---

$$(9)_{10} = (0\ 1001)_2 \rightarrow (-9)_{10} = (1\ 0111)_2$$

$$(8)_{10} = (0\ 1000)_2 \rightarrow (-8)_{10} = (1\ 1000)_2$$

$$9 + 8 = (0\ 1001)_2 + (0\ 1000)_2$$

0 1 0 0 0

0 1001

+

0 1000

---

1 0001 → OVERFLOW

$$-2^4 \leq \text{Number} \leq 2^4 - 1 \rightarrow -16 \leq \text{Number} \leq +15$$

# Two's Complement Arithmetic

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$$(9)_{10} = (0\ 1001)_2 \rightarrow (-9)_{10} = (1\ 0111)_2$$

$$(8)_{10} = (0\ 1000)_2 \rightarrow (-8)_{10} = (1\ 1000)_2$$

$$(-9) + (-8) = (1\ 0111)_2 + (1\ 1000)_2$$

1 0 0 0 0

1 0111

+

1 1000

---

0 1111 → OVERFLOW

$$-2^4 \leq \text{Number} \leq 2^4 - 1 \rightarrow -16 \leq \text{Number} \leq +15$$

# Arithmetic Microoperations

- From Table 7-3:

Symbolic Designation	Description
$R0 \leftarrow R1 + R2$	Addition
$R0 \leftarrow \overline{R1}$	Ones Complement
$R0 \leftarrow \overline{R1} + 1$	Two's Complement
$R0 \leftarrow R2 + \overline{R1} + 1$	R2 minus R1 (2's Comp)
$R1 \leftarrow R1 + 1$	Increment (count up)
$R1 \leftarrow R1 - 1$	Decrement (count down)

- Note that any register may be specified for source 1, source 2, or destination.
- These simple microoperations operate on the whole word

# Logical Microoperations

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Symbolic Designation	Description
$R0 \leftarrow \overline{R1}$	<b>Bitwise NOT</b>
$R0 \leftarrow R1 \vee R2$	<b>Bitwise OR (sets bits)</b>
$R0 \leftarrow R1 \wedge R2$	<b>Bitwise AND (clears bits)</b>
$R0 \leftarrow R1 \oplus R2$	<b>Bitwise EXOR (complements bits)</b>

# Logical Microoperations

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## Example:

- Let **R1 = 10101010**,  
and **R2 = 11110000**
- Then after the operation, **R0 becomes:**

R0	Operation
01010101	$R0 \leftarrow \overline{R1}$
11111010	$R0 \leftarrow R1 \vee R2$
10100000	$R0 \leftarrow R1 \wedge R2$
01011010	$R0 \leftarrow R1 \oplus R2$

# Shift Microoperations

- From Table 7-5:
- Let R2 = 11001001
- Then after the operation, R1 becomes:

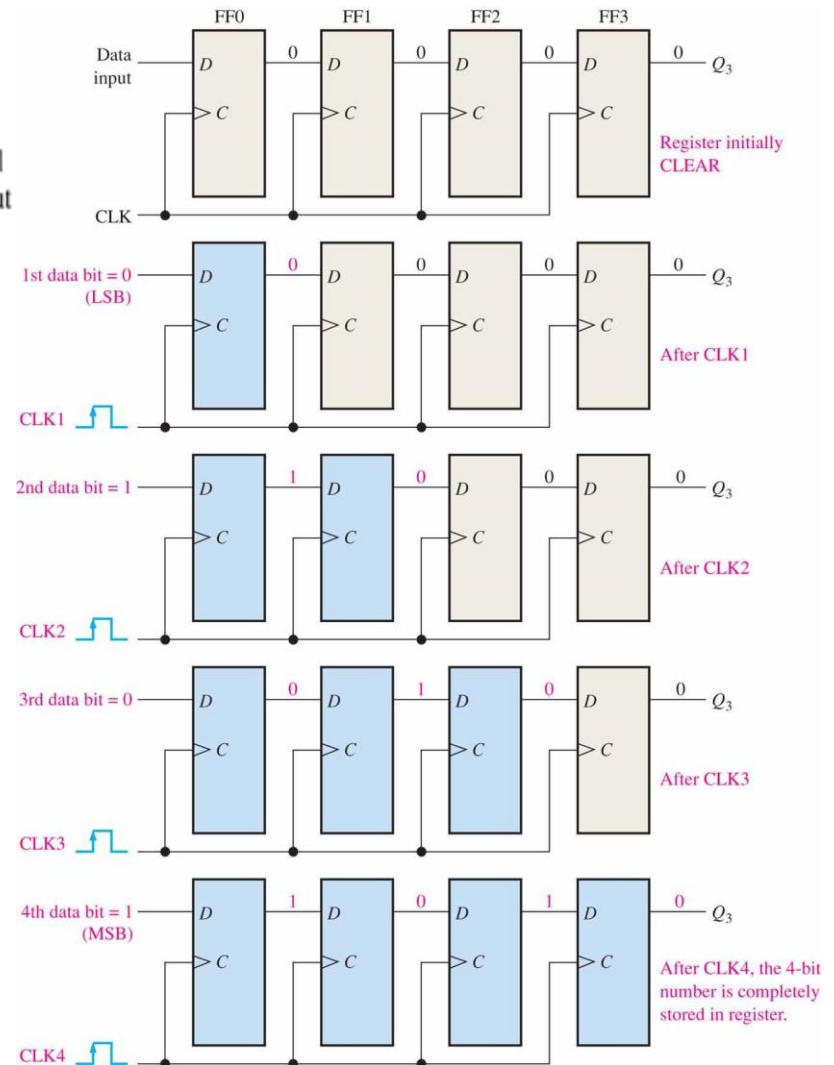
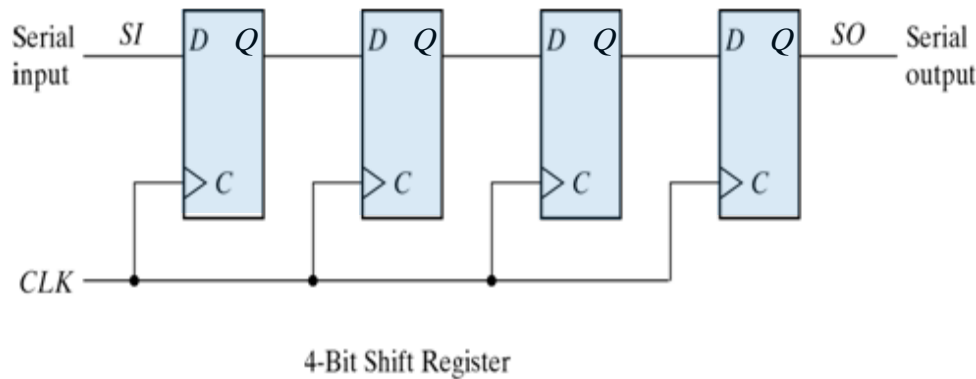
Symbolic Designation	Description
$R1 \leftarrow sl\ R2$	Shift Left
$R1 \leftarrow sr\ R2$	Shift Right

R1	Operation
10010010	$R1 \leftarrow sl\ R2$
01100100	$R1 \leftarrow sr\ R2$

- **Note:** These shifts "zero fill". Sometimes a **separate flip-flop is used** to provide the data shifted in, or to "catch" the data shifted out.
- Other shifts are possible (rotates, arithmetic) (see Chapter 10).

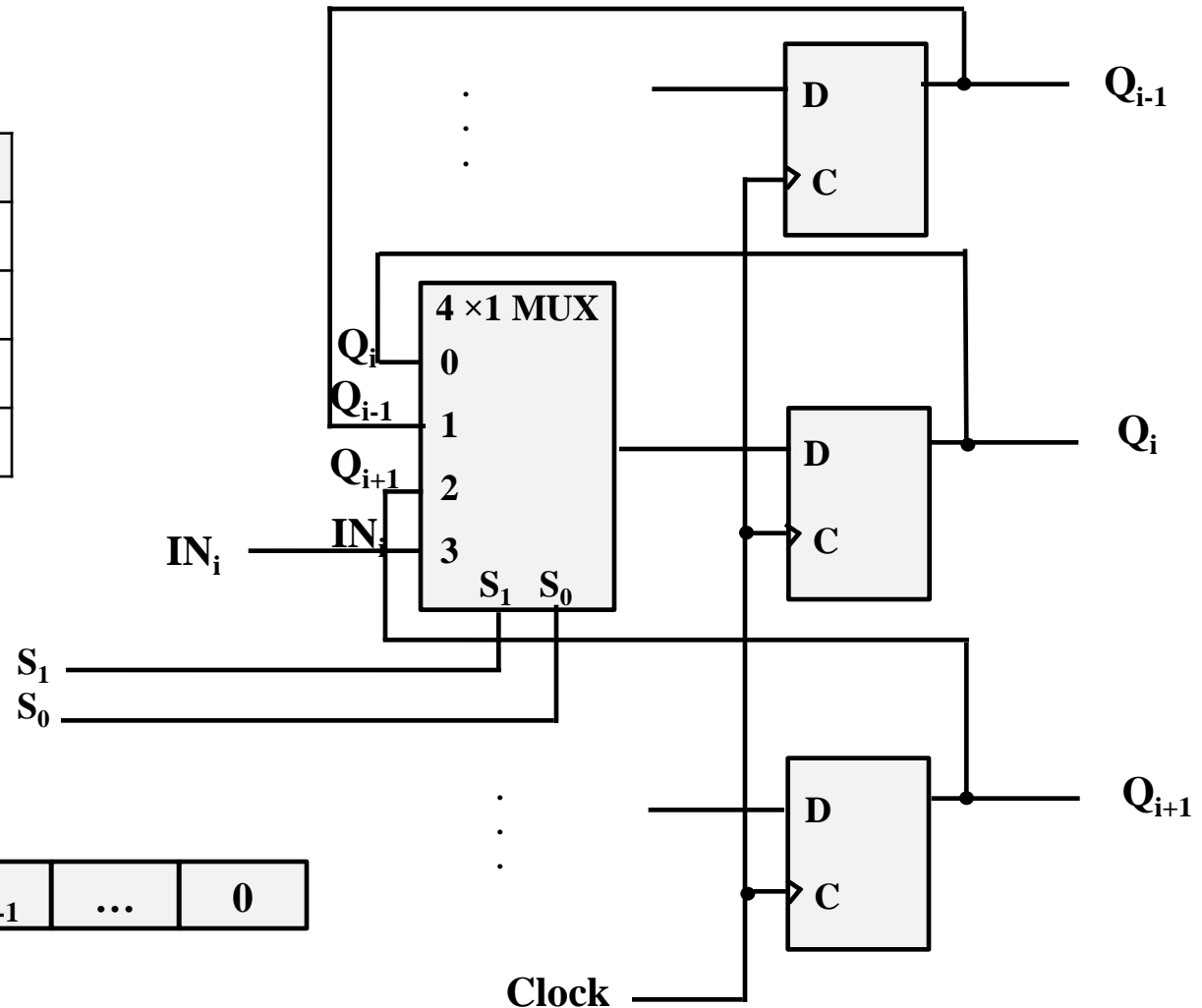
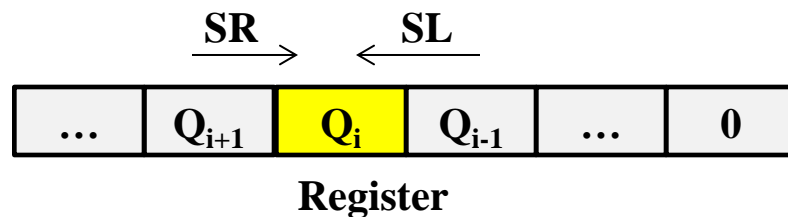


# Shift Registers



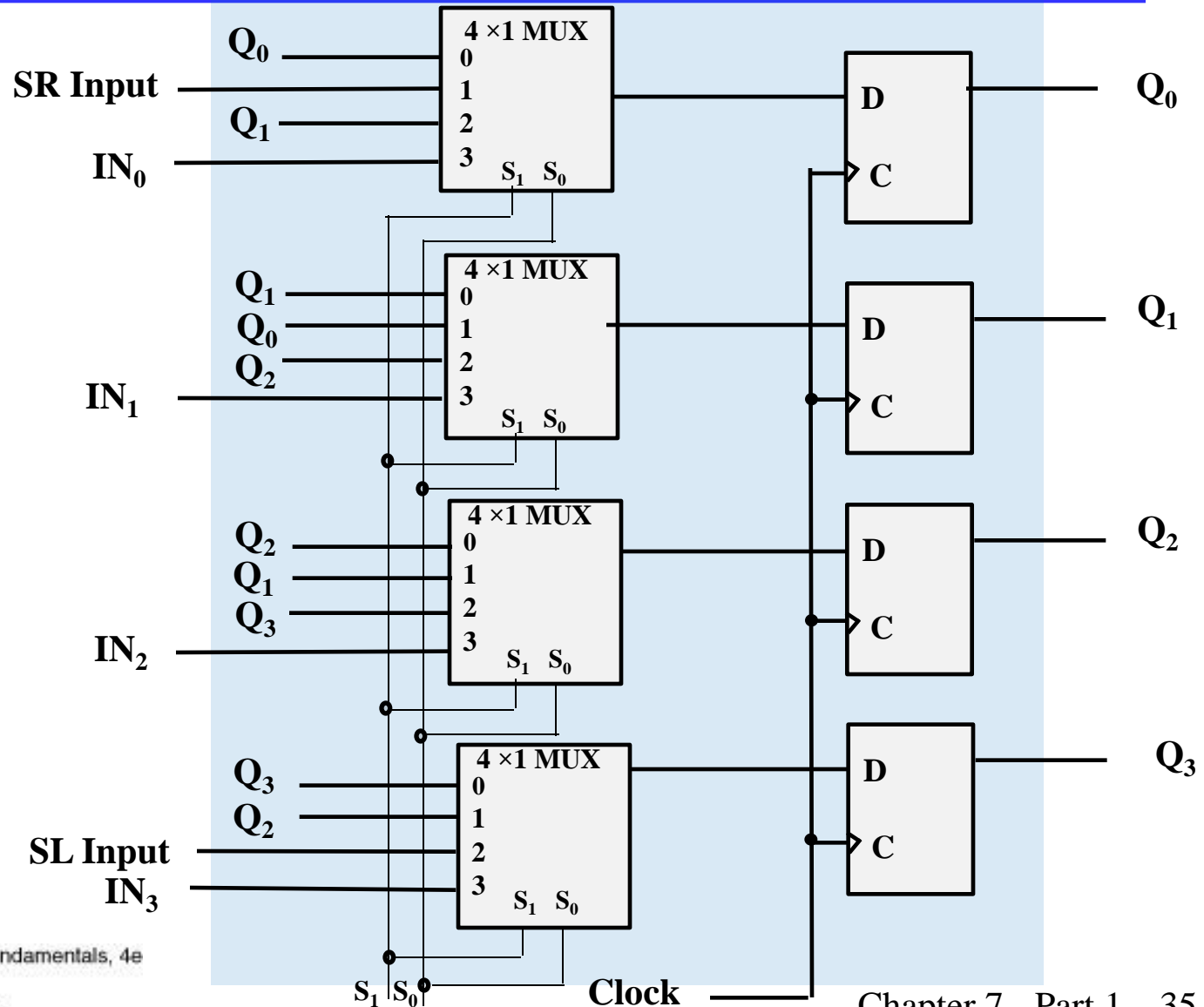
# Bidirectional Shift Register with Parallel Load

$S_1$	$S_0$	Register Operation
0	0	No Change
0	1	Shift Left
1	0	Shift Right
1	1	Parallel Load



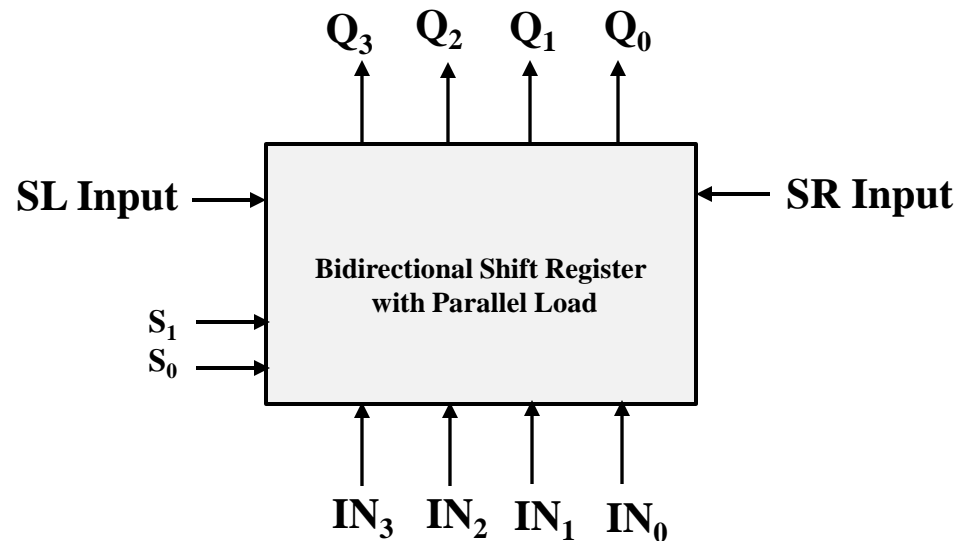
# Bidirectional Shift Register with Parallel Load

$S_1$	$S_0$	Register Operation
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0	1	Shift Left
1	0	Shift Right
1	1	Parallel Load

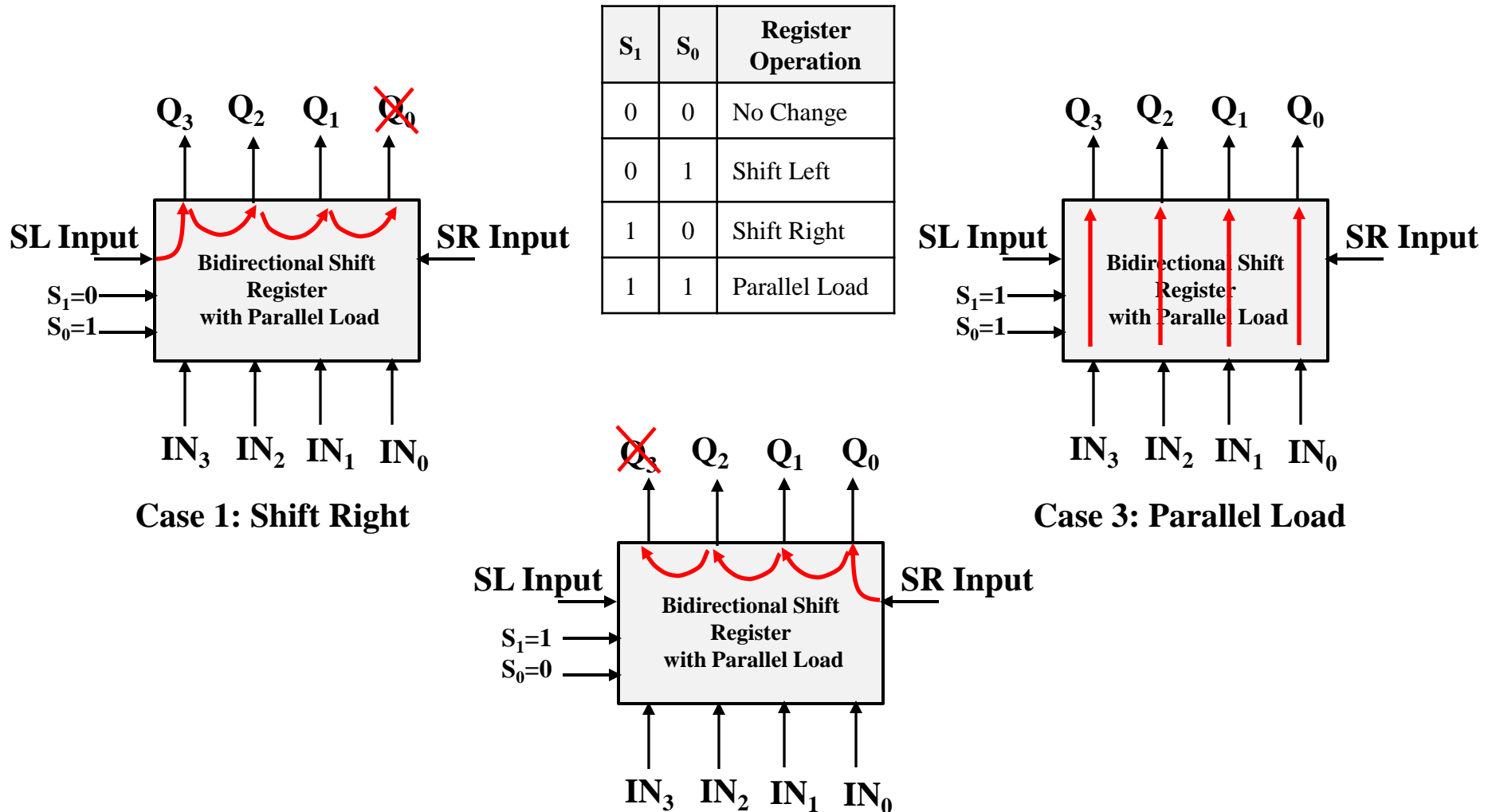


# Bidirectional Shift Register with Parallel Load

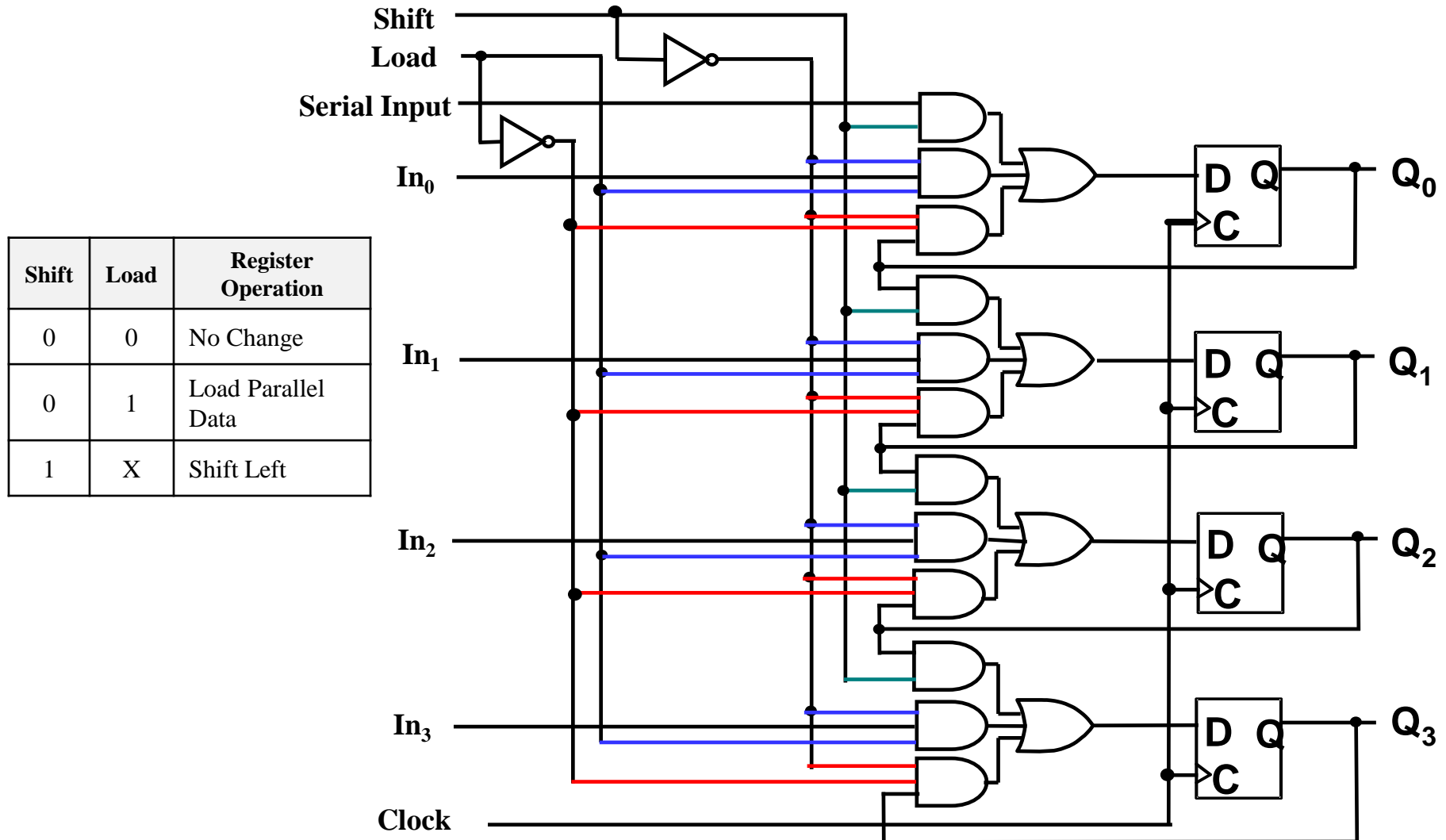
$S_1$	$S_0$	Register Operation
0	0	No Change
0	1	Shift Left
1	0	Shift Right
1	1	Parallel Load



# Bidirectional Shift Register with Parallel Load



# Shift Register with Parallel Load



# Register Transfer Structures

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- **Multiplexer-Based Transfers** - Multiple inputs are selected by a multiplexer dedicated to the register
- **Bus-Based Transfers** - Multiple inputs are selected by a shared multiplexer driving a bus that feeds inputs to multiple registers
- **Three-State Bus** - Multiple inputs are selected by 3-state drivers with outputs connected to a bus that feeds multiple registers
- **Other Transfer Structures** - Use multiple multiplexers, multiple buses, and combinations of all the above

# Multiplexer-Based Transfers

- Multiplexers connected to register inputs produce flexible transfer structures (Note: Clocks are omitted for clarity)

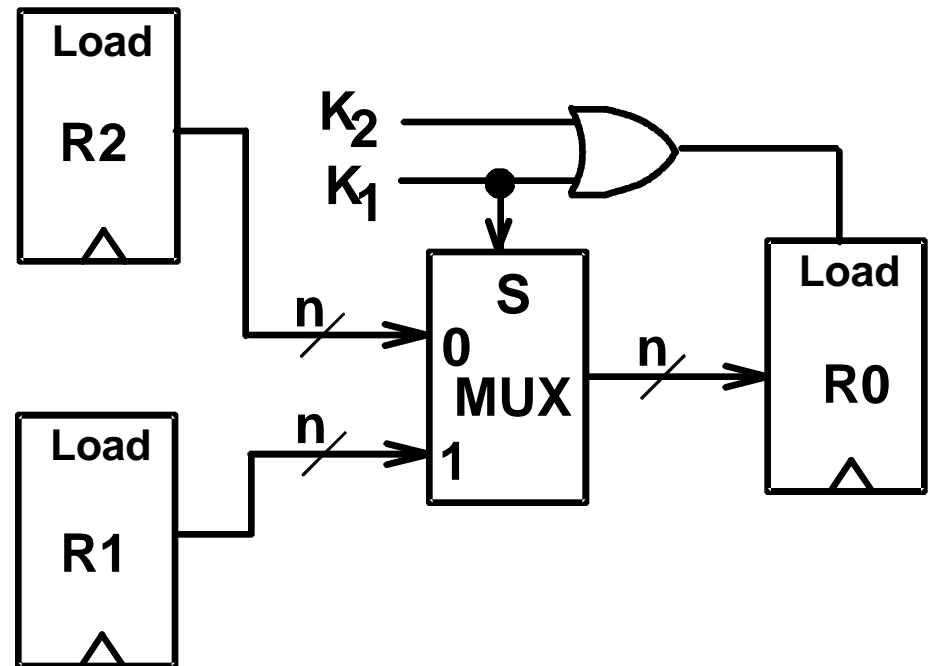
## Example:

- The transfers are:

$K_1$ :  $R0 \leftarrow R1$

$\overline{K_1} \cdot K_2$ :  $R0 \leftarrow R2$

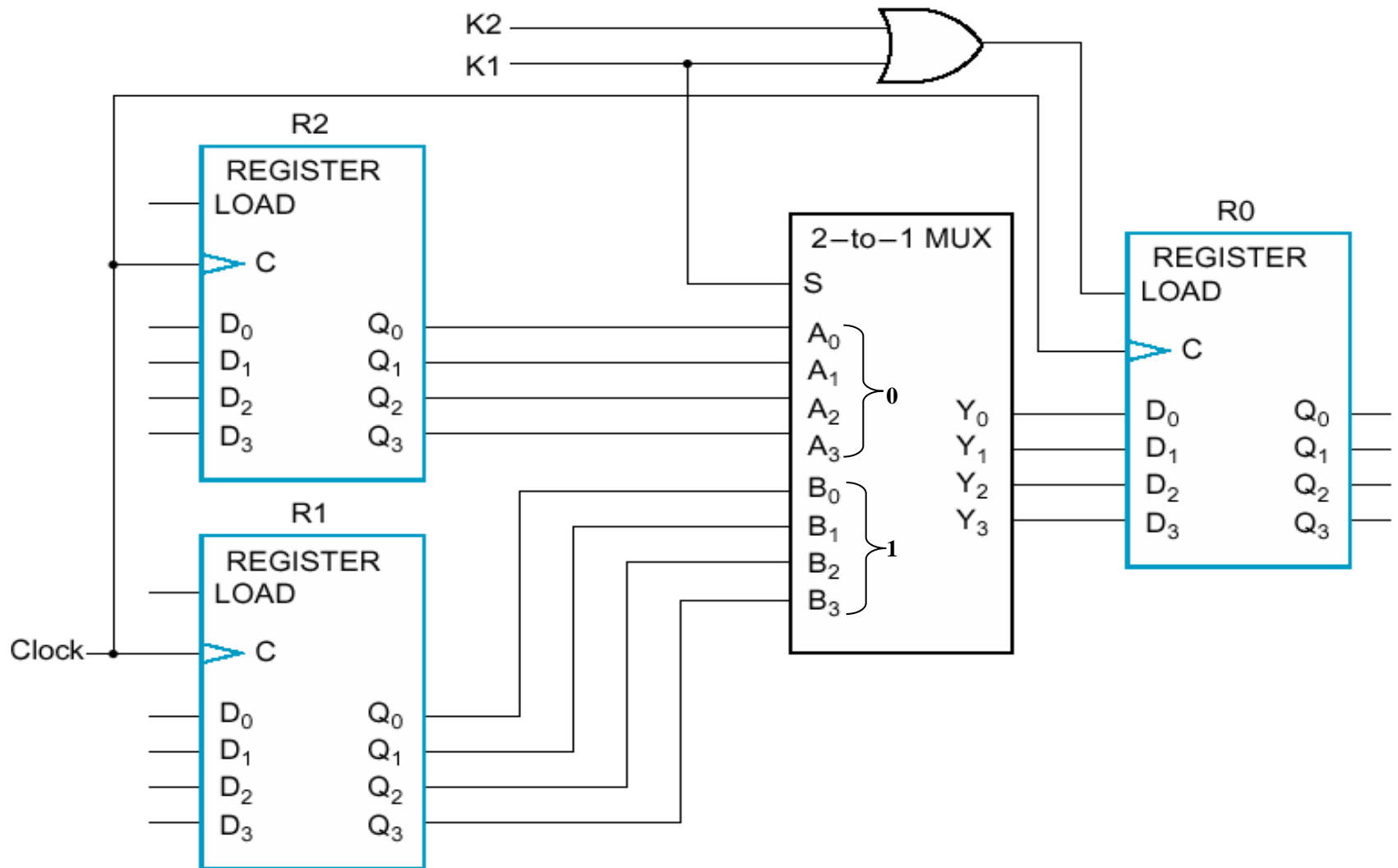
$$K_1 + \overline{K_1} K_2 = K_1 + K_2$$





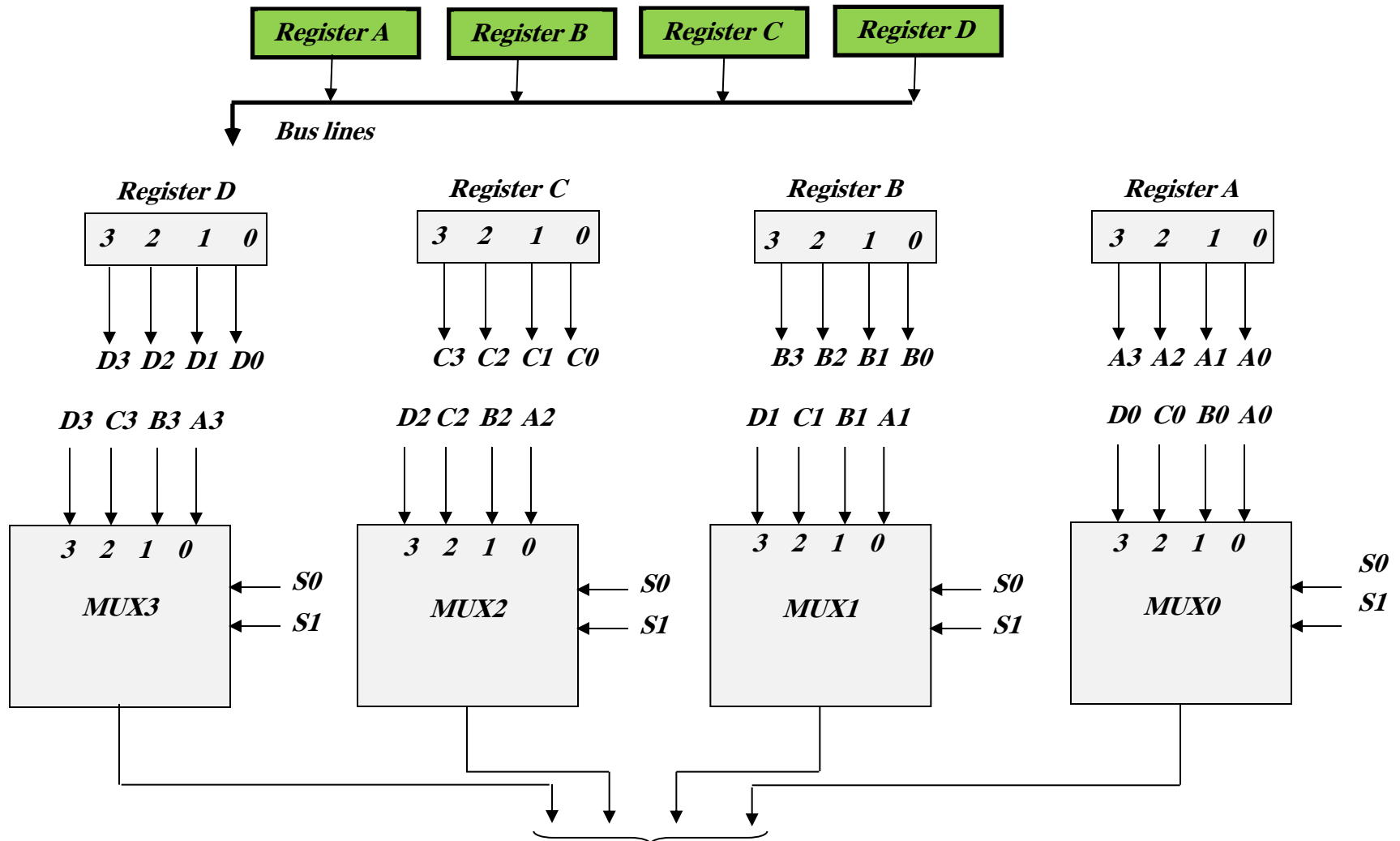
# Multiplexer-Based Transfer

## Example: **Two** 4-bit registers



(b) Detailed logic

# Bus Transfers

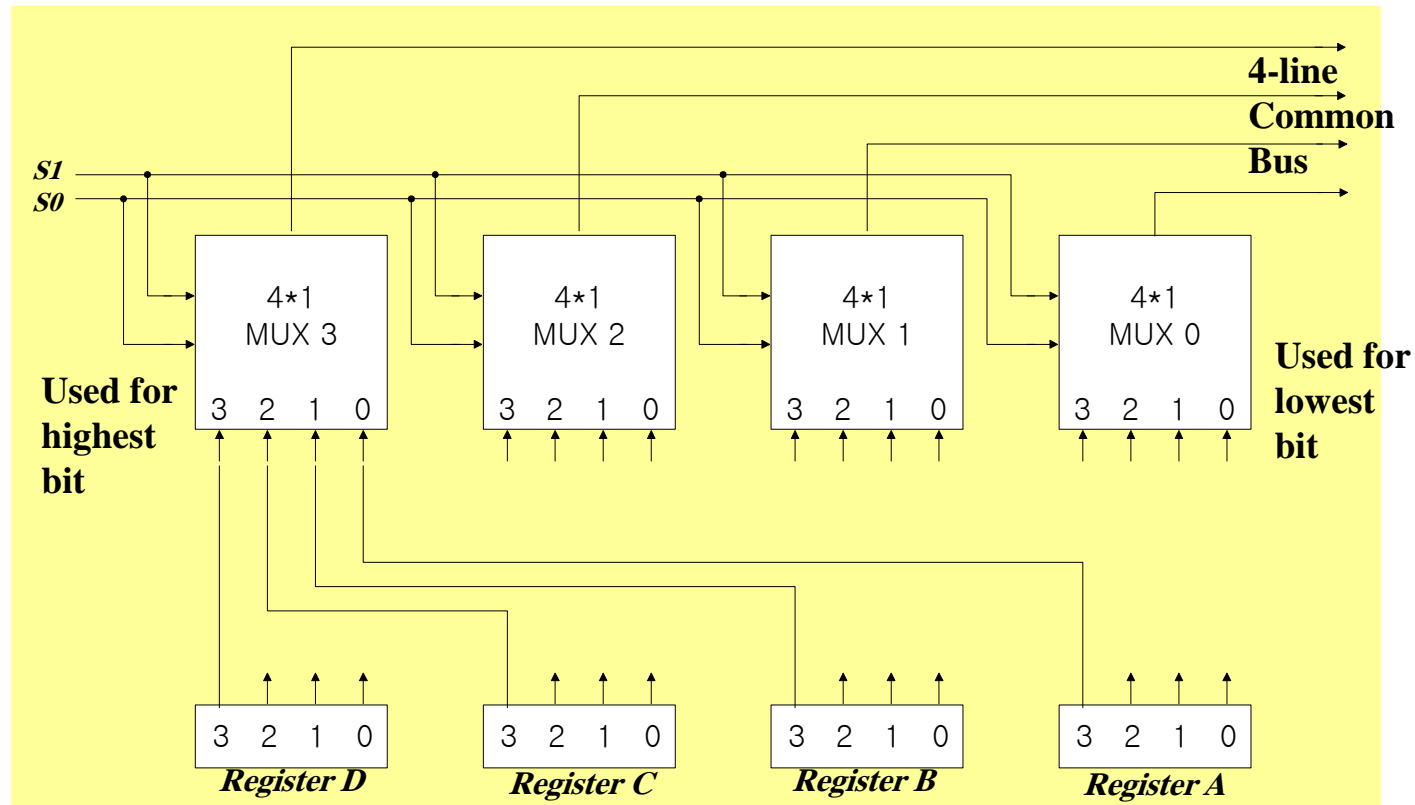


# Bus Transfer

## Example:

For register R0 to R3 in a 4 bit system

S1	S0	Register selected
0	0	A
0	1	B
1	0	C
1	1	D



# Bus Transfer

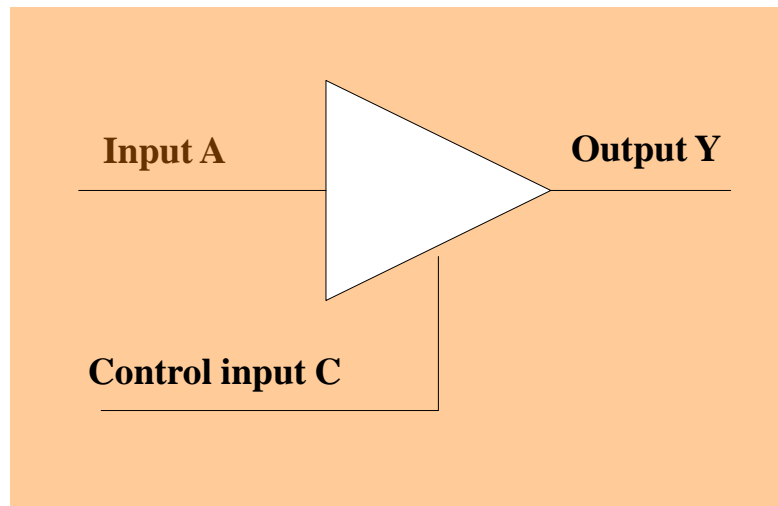
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- **For register R0 to R63 in a 16 bit system:**
  - **What is the MUX size we use?  $64 \times 1$  MUX**
  - **How many MUX we need? 16 MUXs**
  - **How many select bit? 6 bits**

# Tri-State Buffers

## ■ Tri-state buffer gate:

- When control input =1 : The output is nabled (output  $Y$  = input  $A$ )
- When control input =0 : The output is disabled (output  $Y$  = high-impedance)



If  $C=1$ , Output  $Y = A$

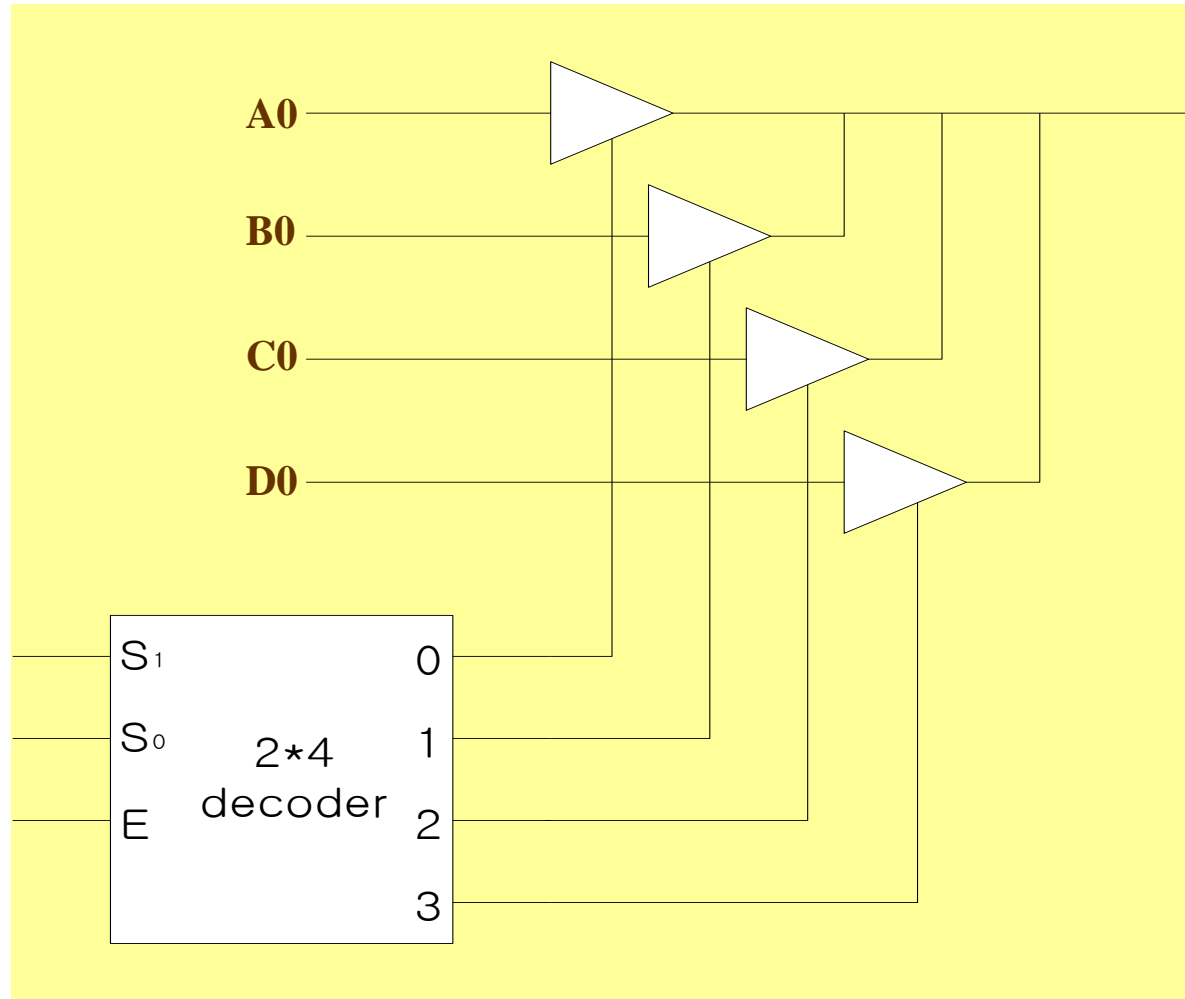
If  $C=0$ , Output = High-impedance

# Bus system with tri-state buffer

S1	S0	Register selected
0	0	A
0	1	B
1	0	C
1	1	D

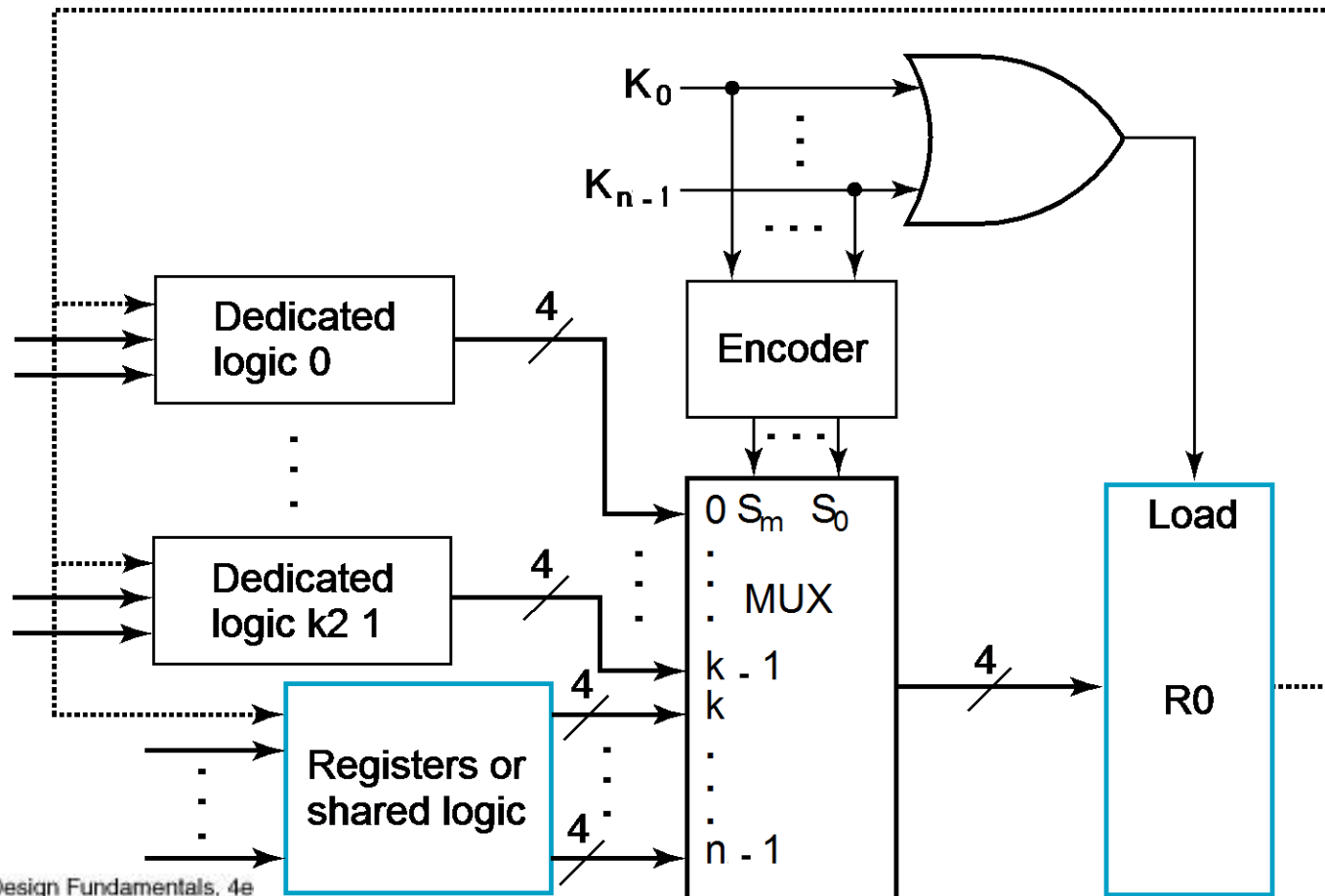
Select input

Enable input



# Multiplexer Approach

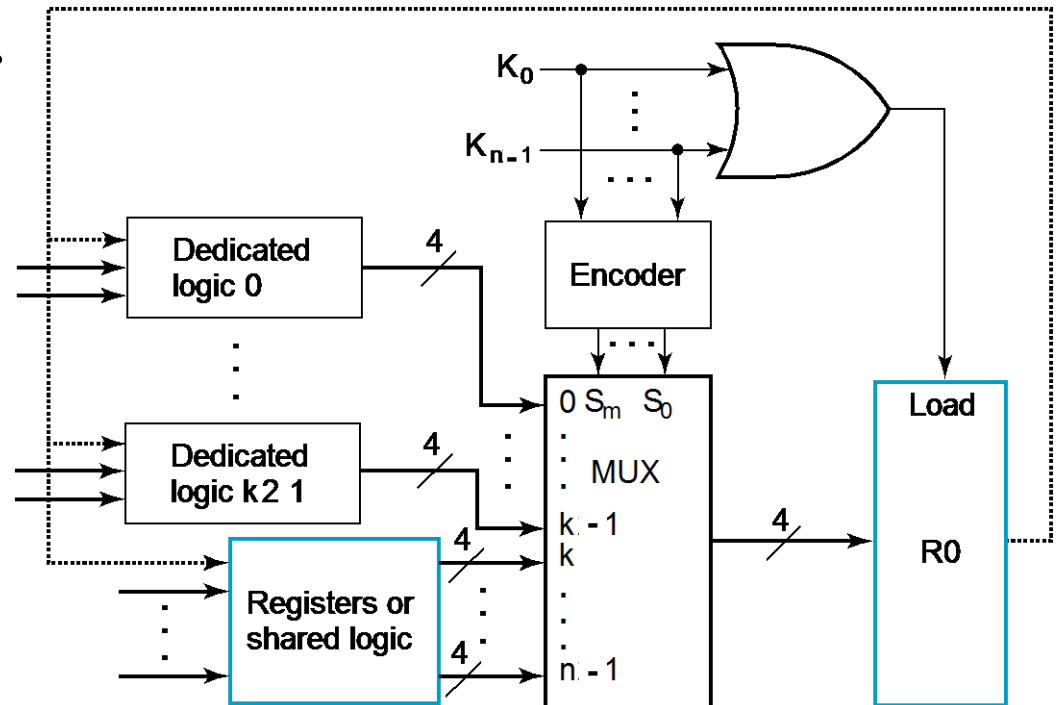
- Uses an n-input multiplexer with a variety of transfer sources and functions



# Multiplexer Approach

- Load enable by OR of control signals  $K_0, K_1, \dots, K_{n-1}$ 
  - Assumes no load for 00...0
- Use:
  - Encoder + Multiplexer (shown) or
  - $n \times 2$  AND-OR

to select sources and/or transfer functions





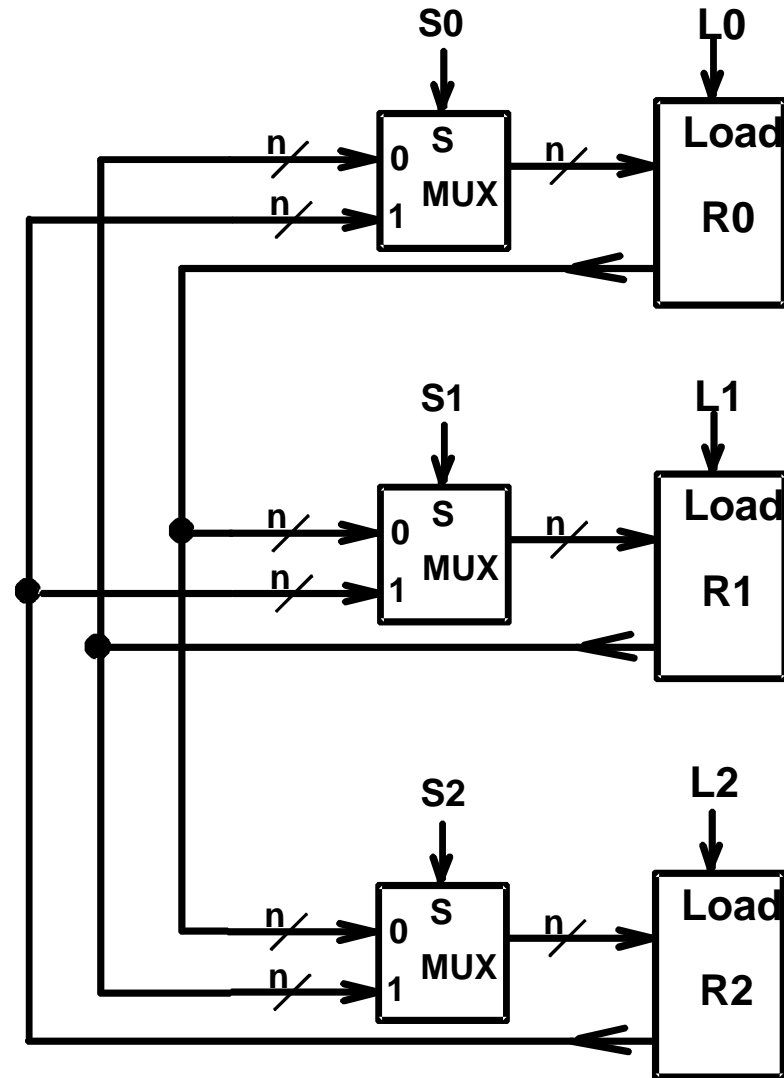
# Multiplexer and Bus-Based Transfers for Multiple Registers

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- Multiplexer dedicated to each register
- Shared transfer paths for registers
  - A shared transfer object is called a *bus*  
(Plural: *buses*)
- Bus implementation using:
  - multiplexers
  - three-state nodes and drivers
- In most cases, the number of bits is the length of the receiving register

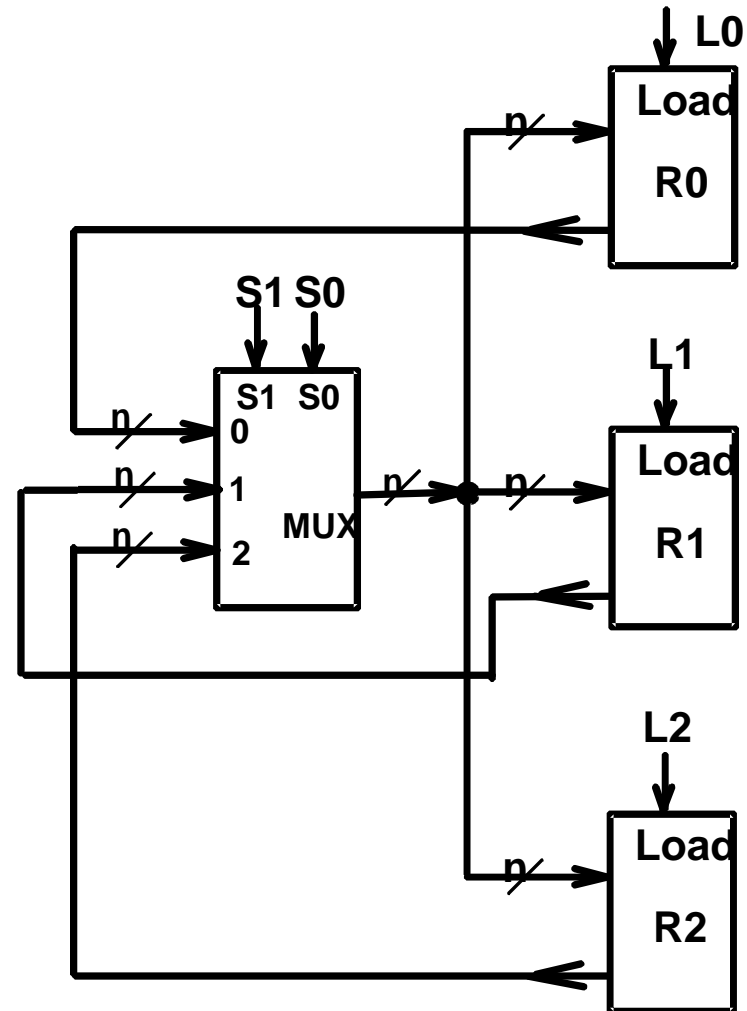
# Dedicated MUX-Based Transfers

- Multiplexer connected to each register input produces a very flexible transfer structure =>
- Characterize the simultaneous transfers possible with this structure.



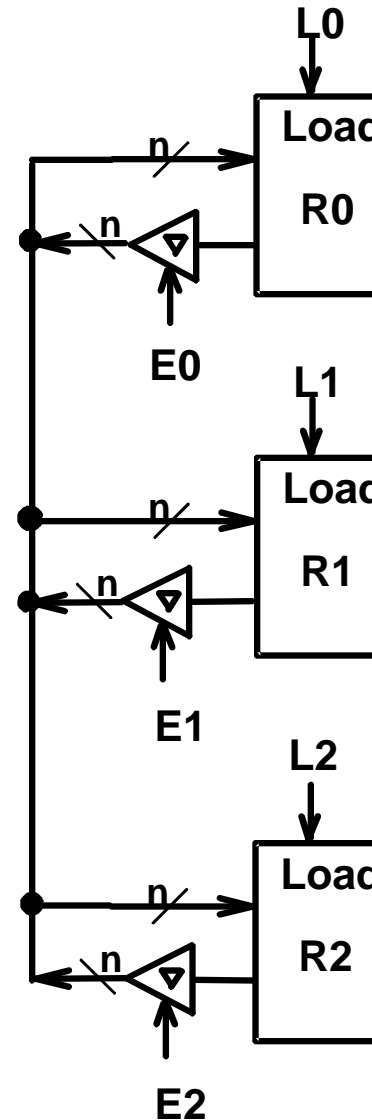
# Multiplexer Bus

- A single bus driven by a multiplexer lowers cost, but limits the available transfers.
- Characterize the simultaneous transfers possible with this structure.
- Characterize the cost savings compared to dedicated multiplexers



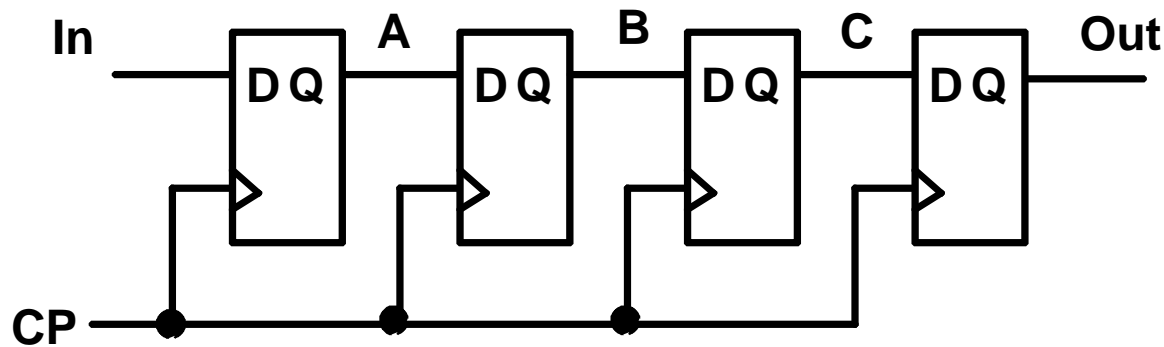
# Three-State Bus

- **The 3-input MUX can be replaced by a 3-state node (bus) and 3-state buffers.**
- **Cost is further reduced, but transfers are limited**
- **Characterize the simultaneous transfers possible with this structure.**
- **Characterize the cost savings and compare**
- **Other advantages?**



# Shift Registers

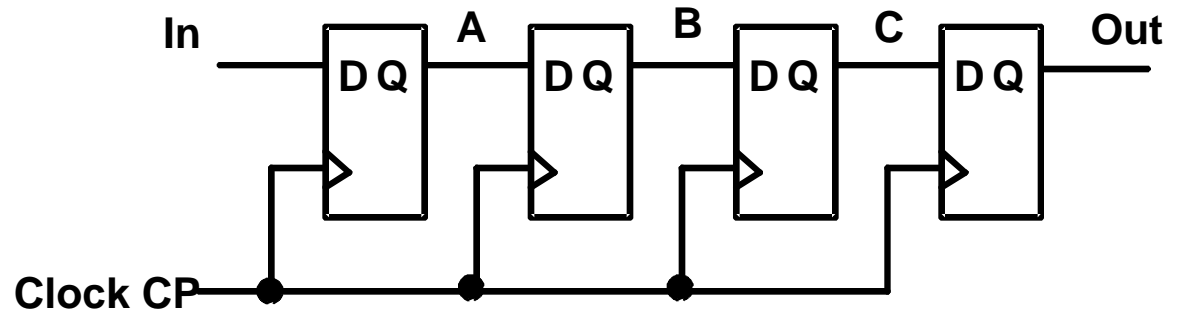
- Shift Registers move data laterally within the register toward its MSB or LSB position
- In the simplest case, the shift register is simply a set of D flip-flops connected in a row like this:



- Data input, In, is called a *serial input* or the *shift right input*.
- Data output, Out, is often called the *serial output*.
- The vector (A, B, C, Out) is called the *parallel output*.

# Shift Registers (continued)

- The behavior of the serial shift register is given in the listing on the lower right

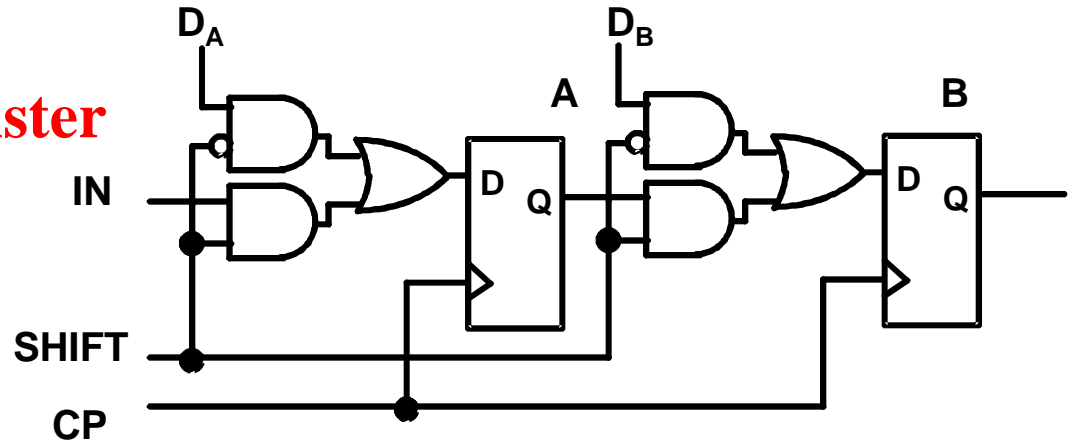


- T0 is the register state just before the first clock pulse occurs
- T1 is after the first pulse and before the second.
- Initially unknown states are denoted by “?”

CP	In	A	B	C	Out
T0	0	?	?	?	?
T1	1	0	?	?	?
T2	1	1	0	?	?
T3	0	1	1	0	?
T4	1	0	1	1	0
T5	1	1	0	1	1
T6	1	1	1	0	1

# Parallel Load Shift Registers

- **By adding a mux between each shift register stage, data can be shifted or loaded**
- **If SHIFT is low, A and B are replaced by the data on  $D_A$  and  $D_B$  lines, else data shifts right on each clock.**
- **By adding more bits, we can make  $n$ -bit parallel load shift registers.**



## Note:

- **A parallel load shift register with an added “hold” operation that stores data unchanged is given in Figure 7-10 of the text.**

# Shift Registers with Additional Functions

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- By placing a **4-input multiplexer** in front of each D flip-flop in a shift register, we can implement a circuit with **shifts right, shifts left, parallel load, hold**.
- Shift registers can also be designed to shift more than a single bit position right or left
- Shift registers can be designed to shift a variable number of bit positions specified by a variable called a *shift amount*.



# Serial Transfers and Microoperations

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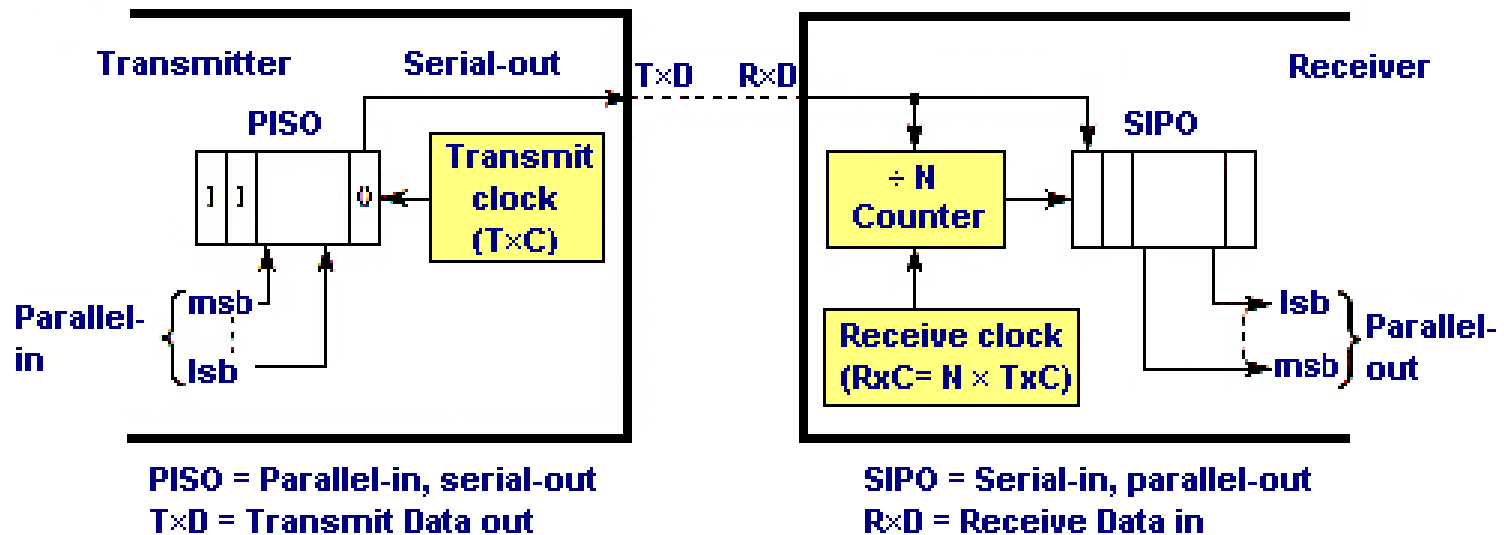
## ■ Serial Transfers

- Used for “narrow” transfer paths
- **Example 1: Telephone or cable line**
  - **Parallel-to-Serial conversion at source**
  - **Serial-to-Parallel conversion at destination**
- **Example 2: Initialization and Capture of the contents of many flip-flops for test purposes**
  - Add shift function to all flip-flops and form large shift register
  - Use shifting for simultaneous Initialization and Capture operations

## ■ Serial microoperations

- **Example 1: Addition**
- **Example 2: Error-Correction for CDs**

# Parallel-to-Serial / Serial-to-Parallel



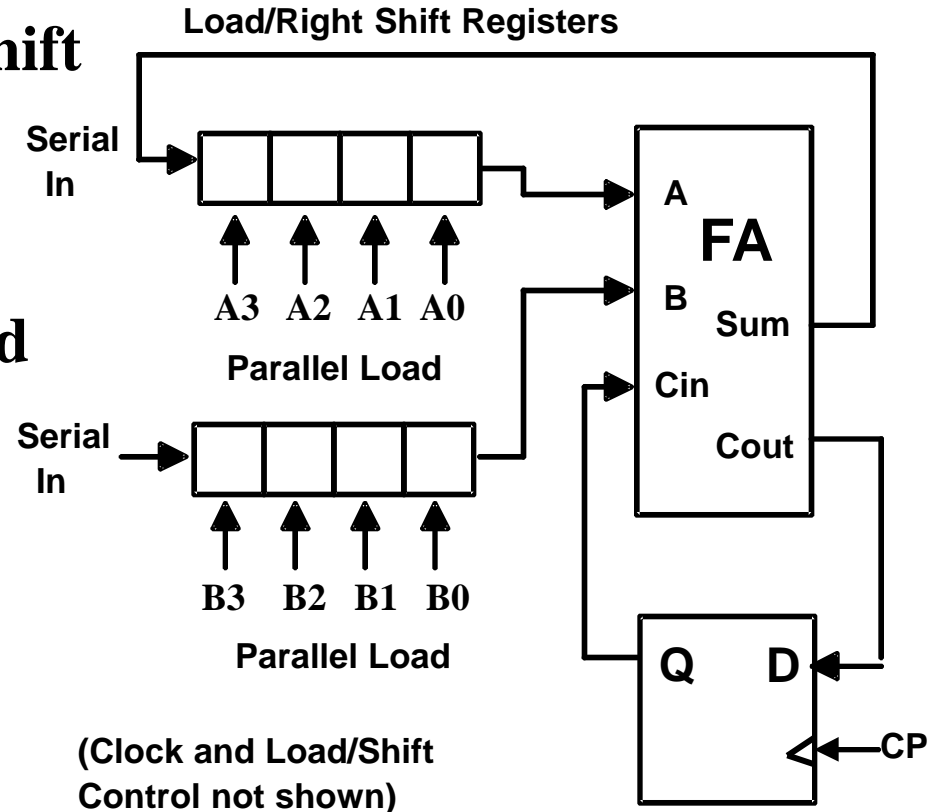
# Serial Microoperations

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- By using two shift registers for operands, a full adder, and a flip flop (for the carry), we can add two numbers serially, starting at the least significant bit.
- Serial addition is a low cost way to add large numbers of operands, since a “tree” of full adder cells can be made to any depth, and each new level doubles the number of operands.
- Other operations can be performed serially as well, such as parity generation/checking or more complex error-check codes.
- **Shifting a binary number left is equivalent to multiplying by 2.**
- **Shifting a binary number right is equivalent to dividing by 2.**

# Serial Adder

- The circuit shown uses two shift registers for operands A(3:0) and B(3:0).
- A full adder, and one more flip flop (for the carry) is used to compute the sum.
- The result is stored in the A register and the final carry in the flip-flop
- With the operands and the result in shift registers, a tree of full adders can be used to add a large number of operands. Used as a common digital signal processing technique.



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