Eigenvalues and Eigenvectors Linear Algebra and Vector Analysis

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Definition: A nonzero vector **x** is an *eigenvector* (or *characteristic vector*) of a square matrix **A** if there exists a scalar λ such that $Ax = \lambda x$. Then λ is an *eigenvalue* (or *characteristic value*) of **A**.

Note: The zero vector can not be an eigenvector even though $A0 = \lambda 0$. But $\lambda = 0$ can be an eigenvalue.

Example:

Show
$$x = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$
 is an eigenvector for $A = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$
Solution : $Ax = \begin{bmatrix} 2 & -4 \\ 3 & -6 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
But for $\lambda = 0$, $\lambda x = 0 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

Dr. Abdul GT hus, x is an eigenvector of A, and x = 0 is an eigenvalue.

Geometric interpretation of Eigenvalues and Eigenvectors

An $n \times n$ matrix **A** multiplied by $n \times 1$ vector **x** results in another $n \times 1$ vector **y=Ax**. Thus **A** can be considered as a transformation matrix.

In general, a matrix acts on a vector by changing both its magnitude and its direction. However, a matrix may act on certain vectors by changing only their magnitude, and leaving their direction unchanged (or possibly reversing it). These vectors are the **eigenvectors** of the matrix.

A matrix acts on an eigenvector by multiplying its magnitude by a factor, which is positive if its direction is unchanged and negative if its direction is reversed. This factor is the **eigenvalue** associated with that eigenvector.

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Eigenvalues: examples

Example 1: Find the eigenvalues of

$$\begin{vmatrix} \lambda I - A \end{vmatrix} = \begin{vmatrix} \lambda - 2 & 12 \\ -1 & \lambda + 5 \end{vmatrix} = (\lambda - 2)(\lambda + 5) + 12$$
$$= \lambda^2 + 3\lambda + 2 \Longrightarrow (\lambda + 1)(\lambda + 2)$$

two eigenvalues: -1, -2

Note: The roots of the characteristic equation can be repeated. That is, $\lambda_1 = \lambda_2 = ... = \lambda_k$. If that happens, the eigenvalue is said to be of multiplicity k.

 $A = \begin{vmatrix} 2 & -12 \\ 1 & -5 \end{vmatrix}$

Example 2: Find the eigenvalues of

$$A = \begin{bmatrix} 2 & 1 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$
$$\lambda I - A = \begin{bmatrix} \lambda - 2 & -1 & 0 \\ 0 & \lambda - 2 & 0 \\ 0 & 0 & \lambda - 2 \end{bmatrix} = (\lambda - 2)^3 = 0$$
$$\lambda = 2 \text{ is an eigenvector of multiplicity 3.}$$

Eigenvectors

To each distinct eigenvalue of a matrix A there will correspond at least one eigenvector which can be found by solving the appropriate set of homogenous equations. If λ_i is an eigenvalue then the corresponding eigenvector \mathbf{x}_i is the solution of $(A - \lambda_i I)\mathbf{x}_i = \mathbf{0}$

Example 1 (cont.):

$$\lambda = -1: (-1)I - A = \begin{bmatrix} -3 & 12 \\ -1 & 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -4 \\ 0 & 0 \end{bmatrix}$$
$$x_1 - 4x_2 = 0 \Rightarrow x_1 = 4t, x_2 = t$$
$$\mathbf{x}_1 = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = t \begin{bmatrix} 4 \\ 1 \end{bmatrix}, t \neq 0$$
$$\lambda = -2: (-2)I - A = \begin{bmatrix} -4 & 12 \\ -1 & 3 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -3 \\ 0 & 0 \end{bmatrix}$$

 $\mathbf{x}_2 = \begin{vmatrix} x_1 \\ x_2 \end{vmatrix} = s \begin{vmatrix} 5 \\ 1 \end{vmatrix}, s \neq 0 \quad \text{29-Dec-}$

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Eigenvectors

Example 2 (cont.): Find the eigenvectors of

- Recall that $\lambda = 2$ is an eigenvector of multiplicity 3.
- Solve the homogeneous linear system represented by

$$(2I - A)\mathbf{x} = \begin{bmatrix} 0 & -1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
$$x_1 = s, x_3 = t$$

The eigenvectors of $\lambda = 2$ are of the form

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} s \\ 0 \\ t \end{bmatrix} = s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix},$$

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s and tonot both zero.

 $A \neq$

Properties of Eigenvalues and Eigenvectors

Definition: The trace of a matrix A, designated by tr(A), is the sum of the elements on the main diagonal.

Property 1: The sum of the eigenvalues of a matrix equals the trace of the matrix.

Property 2: A matrix is singular if and only if it has a zero eigenvalue.

Property 3: The eigenvalues of an upper (or lower) triangular matrix are the elements on the main diagonal.

Property 4: If λ is an eigenvalue of A and A is invertible, then $1/\lambda$ is an eigenvalue of matrix A⁻¹.

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Continue...

Property 5: If λ is an eigenvalue of A then $k\lambda$ is an eigenvalue of kA where k is any arbitrary scalar.

Property 6: If λ is an eigenvalue of A then λ^k is an eigenvalue of A^k for any positive integer k.

Property 8: If λ is an eigenvalue of A then λ is an eigenvalue of A^{T} .

Property 9: The product of the eigenvalues (counting multiplicity) of a matrix equals the determinant of the matrix.