



**Faculty of Engineering**  
**Mechanical Engineering Department**

# **Linear Algebra and Vector Analysis**

## **MATH 1120**

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- Matrix Equations

# Matrix Equations

- We saw in Example 6 in Section 7.2 that a system of linear equations can be written as a single matrix equation.

# Matrix Equations

- For example, the system

is equivalent to the matrix equation

$$\begin{cases} x - 2y - 4z = 7 \\ 2x - 3y - 6z = 5 \\ -3x + 6y + 15z = 0 \end{cases}$$

$$\begin{bmatrix} 1 & -2 & -4 \\ 2 & -3 & -6 \\ -3 & 6 & 15 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 7 \\ 5 \\ 0 \end{bmatrix}$$

# Coefficient Matrix

- If we let

$$A = \begin{bmatrix} 1 & -2 & -4 \\ 2 & -3 & -6 \\ -3 & 6 & 15 \end{bmatrix} \quad X = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \quad B = \begin{bmatrix} 7 \\ 5 \\ 0 \end{bmatrix}$$

this matrix equation can be written as:

$$AX = B$$

- The matrix  $A$  is called the coefficient matrix.

# Matrix Equations

- We solve this matrix equation by multiplying each side by the inverse of  $A$ —provided the inverse exists.

- $$AX = B$$
$$A^{-1}(AX) = A^{-1}B$$
$$(A^{-1}A)X = A^{-1}B \quad \text{Associative Property}$$
$$I_3X = A^{-1}B \quad \text{Property of Inverses}$$
$$X = A^{-1}B$$

# Matrix Equations

- In Example 4, we showed that:

$$A^{-1} = \begin{bmatrix} -3 & 2 & 0 \\ -4 & 1 & -\frac{2}{3} \\ 1 & 0 & \frac{1}{3} \end{bmatrix}$$

# Matrix Equations

- So, from  $X = A^{-1}B$ , we have:

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -3 & 2 & 0 \\ -4 & 1 & -\frac{2}{3} \\ 1 & 0 & \frac{1}{3} \end{bmatrix} \begin{bmatrix} 7 \\ 5 \\ 0 \end{bmatrix} = \begin{bmatrix} -11 \\ -23 \\ 7 \end{bmatrix}$$

- Thus,  $x = -11$ ,  $y = -23$ ,  $z = 7$   
is the solution of the original system.



# Matrix Equations

- We have proved that the matrix equation

$$AX = B$$

can be solved by the following method.

# Solving a Matrix Equation

- Let:
  - $A$  be a square  $n \times n$  matrix that has an inverse  $A^{-1}$ .
  - $X$  be a variable matrix, with  $n$  rows.
  - $B$  be a known matrix, with  $n$  rows.
- Then, the solution of the matrix equation

$$AX = B$$

is given by:

$$X = A^{-1}B$$

## E.g. 6—Solving a System Using a Matrix Inverse

$$\begin{cases} 2x - 5y = 15 \\ 3x - 6y = 36 \end{cases}$$

- (a) Write the system of equations as a matrix equation.
  
- (b) Solve the system by solving the matrix equation.

# E.g. 6—Using a Matrix Inverse

## Example (a)

- We write the system as a matrix equation of the form  $AX = B$ :

$$\begin{bmatrix} 2 & -5 \\ 3 & -6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 15 \\ 36 \end{bmatrix}$$

# E.g. 6—Using a Matrix Inverse

## Example (b)

- Using the rule for finding the inverse of a 2 x 2 matrix, we get:

$$\begin{aligned} A^{-1} &= \begin{bmatrix} 2 & -5 \\ 3 & -6 \end{bmatrix}^{-1} = \frac{1}{2(-6) - (-5)3} \begin{bmatrix} -6 & -(-5) \\ -3 & 2 \end{bmatrix} \\ &= \frac{1}{3} \begin{bmatrix} -6 & 5 \\ -3 & 2 \end{bmatrix} \\ &= \begin{bmatrix} -2 & \frac{5}{3} \\ -1 & \frac{2}{3} \end{bmatrix} \end{aligned}$$

# E.g. 6—Using a Matrix Inverse

## Example (b)

- Multiplying each side of the matrix equation by the inverse matrix, we get:

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -2 & \frac{5}{3} \\ -1 & \frac{2}{3} \end{bmatrix} \begin{bmatrix} 15 \\ 36 \end{bmatrix} = \begin{bmatrix} 30 \\ 9 \end{bmatrix}$$

– Thus,  $x = 30$  and  $y = 9$ .

- Modeling with Matrix Equations

# Applications

- Suppose we need to solve several systems of equations with the same coefficient matrix.
  - Then, converting the systems to matrix equations provides an efficient way to obtain the solutions.
  - We only need to find the inverse of the coefficient matrix once.