

Exercises:

Let (N_t) be a Poisson r.v. with parameter λt that is.

$$N_t \hookrightarrow \mathcal{P}(\lambda t).$$

Let $(u_k)_{k \geq 1}$ i.i.d. $E[u_1] = \mu$ and $\text{Var}(u_1) = \sigma^2$.

N_t is \perp $(u_1, u_2, u_3, \dots, u_n, \dots)$.

$$R_t = u_1 + u_2 + u_3 + \dots + u_{N_t} = \sum_{k=1}^{N_t} u_k.$$

Find $E[R_t | N_t]$? $\text{Var}(R_t | N_t)$? $E[X|Y]$?

Solution: $g(y) = E[X|Y=y]; y \in S_Y$ $\overset{||}{g(y)}$

First compute $E[R_t | N_t = n]$?

We have: $E[R_t | N_t = n] = E\left[\sum_{k=1}^{N_t} u_k \mid N_t = n\right]$

$$\boxed{E[E[Y|X]] = E[Y]} = E\left[\sum_{k=1}^n u_k \mid N_t = n\right]$$

$$= \sum_{k=1}^n E[u_k | N_t = n]$$

$$\boxed{E[E[X|Y]] = E[X]} = \sum_{k=1}^n E[u_k] \quad (u_k \perp N_t \text{ for all } k \geq 1)$$

$$= \sum_{k=1}^n \mu = \mu n = g(n).$$

Then $E[R_t | N_t] = g(N_t) = \mu N_t$ \otimes

Deduce $E[R_t]$? Take the expectation in both sides of

$$\otimes \quad E[\underbrace{E[R_t | N_t]}_{|| E[R_t]}] = E[\mu N_t] = \mu E[N_t]$$

Therefore: $E[R_t] = \mu E[N_t] = \mu t$

$$\text{Var}(R_t | N_t = n) = E[R_t^2 | N_t = n] - \mu^2 n^2$$

$$= E\left[\left(\sum_{k=1}^{N_t} u_k\right)^2 \mid N_t = n\right] - \mu^2 n^2$$

$$= \boxed{E\left[\left(\sum_{k=1}^n u_k\right)^2 \mid N_t = n\right] - \mu^2 n^2}$$

We can also

$$\begin{aligned} \text{Var}(R_t | N_t = n) &= \text{Var}\left(\sum_{k=1}^{N_t} u_k \mid N_t = n\right) \\ &= \text{Var}\left(\sum_{k=1}^n u_k \mid N_t = n\right) \end{aligned}$$

$$\sqrt{E\left[\left(\sum_{k=1}^n u_k\right)^2\right] - \mu^2 n^2}$$

$$= E\left[\left(\sum_{k=1}^n u_k\right)^2\right] - \left(E\left[\sum_{k=1}^n u_k\right]\right)^2 = E[X^2] - (E[X])^2$$

$$= \text{Var}\left(\sum_{k=1}^n u_k\right) = \sum_{k=1}^n \text{Var}(u_k) \quad (u_k)_{k \geq 1} \perp$$

$$= \sum_{k=1}^n \sigma^2 = n \sigma^2$$

Then

$$\text{Var}(R_t | N_t) = N_t \sigma^2$$

We need $\text{Var}(R_t)$?

$$\textcircled{+} \left(E[\text{Var}(X|Y)] + \text{Var}(E[X|Y]) \right)$$

$$Z = E[X|Y] \text{ r.v.}$$

$$E[Z], \text{Var}(Z)$$

$$R = \text{Var}(X|Y)$$

$$E[R] \text{ and } \text{Var}(R)$$

$$\text{Var}(X|Y) = E[X^2|Y] - (E[X|Y])^2$$

$$\textcircled{1} E[\text{Var}(X|Y)] = E[X^2] - E[(E[X|Y])^2]$$

$$\text{Var}(E[X|Y]) = E[(E[X|Y])^2] - \left(\frac{E[E[X|Y]]}{z}\right)^2$$

$$\text{Var}(z) = E[z^2] - (E[z])^2$$

$$\textcircled{2} \text{Var}(E[X|Y]) = E[(E[X|Y])^2] - (E[X])^2$$

$$\textcircled{1+2} \boxed{\text{Var}(X) = E[\text{Var}(X|Y)] + \text{Var}(E[X|Y])}$$

This is called the conditional variance relationship.

Application to $X = R_t$ and $Y = N_t$.

$$\text{Var}(R_t) = E[\text{Var}(R_t|N_t)] + \text{Var}(E[R_t|N_t])$$

$$= E[\sigma^2 N_t] + \text{Var}(\mu N_t)$$

$$= \sigma^2 E[N_t] + \mu^2 \text{Var}(N_t) = \sigma^2 \Delta t + \mu^2 \Delta t$$

$$= \Delta t (\sigma^2 + \mu^2)$$

$U_1 \hookrightarrow \mathcal{B}(\frac{1}{2})$. Find $E[e^{zR_t} | N_t=n]$?

$z \in \mathbb{R}$

$$E[e^{zR_t} | N_t=n] = E[e^{z \sum_{k=1}^n U_k} | N_t=n]$$

$$= E[e^{z \sum_{k=1}^n U_k}]$$

because $(U_k) \perp\!\!\!\perp N_t$

$$= E[e^{zU_1} e^{zU_2} \dots e^{zU_n}]$$

$\sum_{k=1}^n U_k \perp\!\!\!\perp N_t$

$$= E[e^{zU_1}] E[e^{zU_2}] \dots E[e^{zU_n}]$$

$$= (E[e^{zU_1}])^n$$

$$E[e^{zR_t} | N_t = n] = (M_{u_1}(z))^n \quad \forall n \geq 0.$$

$$M_{u_1}(z) = E[e^{zu_1}] = e^{z \times 1} \frac{1}{2} + e^{z \times 0} \frac{1}{2} = \frac{e^z + 1}{2}.$$

$$E[e^{zR_t} | N_t = n] = \left(\frac{e^z + 1}{2}\right)^n.$$

z real number.

Then:

$$E[e^{zR_t} | N_t] = \left(\frac{e^z + 1}{2}\right)^{N_t}.$$

$$M_X(z) = E[e^{zX}], \quad z \in \mathbb{R}.$$

$$F(x, y) = \int_{-\infty}^x \int_{-\infty}^y f(u, v) du dv.$$

$$E[e^{zR_t}] = M_{R_t}(z) = E[E[e^{zR_t} | N_t]]$$

$$= E\left[\left(\frac{e^z + 1}{2}\right)^{N_t}\right]$$

$$= \sum_{n=0}^{\infty} \left(\frac{e^z + 1}{2}\right)^n e^{-\lambda t} \frac{(\lambda t)^n}{n!}$$

$$= e^{-\lambda t} \sum_{n=0}^{\infty} \left(\frac{\lambda t (e^z + 1)}{2}\right)^n \frac{1}{n!}$$

$$= e^{-\lambda t} e^{\lambda t \left(\frac{e^z + 1}{2}\right)}.$$

Discrete time Markov chains.

Definitions and properties:

Let (Ω, \mathcal{F}, P) be a probability space.

Def: A sequence of r.v. $(X_n, n \geq 0)$ on a state space S is a discrete-time Markov chain if:

- $\forall n \geq 0, X_n \in S$ that: $S_{X_n} = S \quad \forall n \geq 0$
- $\forall n \geq 1$ and for all $i_0, i_1, \dots, i_{n-1}, i_n \in S$, we have.

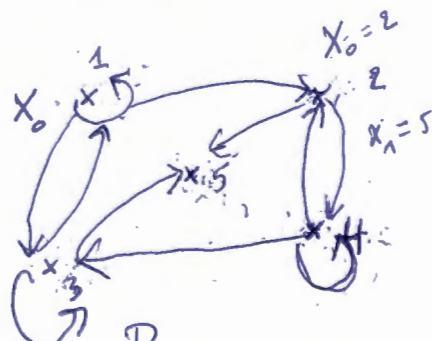
$$P(X_n = i_n | X_0 = i_0, X_1 = i_1, \dots, X_{n-1} = i_{n-1}) = P(X_n = i_n | X_{n-1} = i_{n-1})$$

If $(X_n)_{n \geq 0}$ is a Markov chain; we denote by $P(n, n+1)$ the matrix defined by $P_{ij}(n, n+1) = P(X_{n+1} = j | X_n = i)$.

$P(n, n+1)$ is called the transition matrix of the M.C. $(X_n)_{n \geq 0}$ called also the one-step transition matrix.

Def: If $P(n, n+1)$ does not depend on n , (X_n) is called time homogeneous Markov chain; that is for all $i, j \in S$ we have: $P(X_{n+k} = j | X_k = i) = P(X_n = j | X_0 = i)$ for all $n, k \in \mathbb{N}$.

$$\begin{pmatrix} \frac{1}{3} & \frac{1}{3} & \frac{1}{3} & 0 & 0 \\ 0 & 0 & 0 & \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & 0 & \frac{1}{4} & 0 & \frac{1}{4} \\ 0 & \frac{1}{5} & \frac{3}{5} & \frac{1}{5} & 0 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$



$$\begin{aligned} P_{11} &= \frac{1}{3} \\ P_{55} &= P(X_n = 5 | X_{n-1} = 5) \\ S &= \{1, 2, 3, 4, 5\} \\ P_{54} &= 0 \\ P_{53} &= 0 \end{aligned}$$

We say that 5 is an absorbing state.

$$P_{ij} \quad X_0 = 5 \quad P_{34}$$

Example: $E = \{1, 2, 3\}$. $P(n, n+1) = \begin{pmatrix} \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \\ \frac{1}{3} & 0 & \frac{2}{3} \\ \frac{1}{2} & 0 & \frac{1}{2} \end{pmatrix} = P$

Find $P_{22} = 0 = P(X_{n+1}=2 | X_n=2)$

$P_{ij} = P(X_{n+1}=j | X_n=i)$

Compute: $P(X_3=2 | X_4=1)$

$P_{12} = P(X_{n+1}=2 | X_n=1)$

$$P(X_3=2 | X_4=1) = \frac{P(X_3=2, X_4=1)}{P(X_4=1)}$$

$$= \frac{P(X_4=1 | X_3=2) P(X_3=2)}{P(X_4=1)} = P_{21(3,4)} \cdot \frac{P(X_3=2)}{P(X_4=1)}$$

let $\alpha_0 = (\alpha_0(i), i \in E)$ row vector be the initial distribution of X_0 that $\alpha_0(i) = P(X_0=i)$ for all $i \in E$.

$0 \leq \alpha_0(i) \leq 1$ and $\sum_{i \in E} \alpha_0(i) = 1$.

In general we denote by α_n the row vector giving the distribution of X_n for any $n \geq 0$ that

$\alpha_n(i) = P(X_n=i); i \in E$.

Theorem: The stochastic process $(X_n)_{n \in \mathbb{N}}$ on the state space E is a Markov chain with initial distribution α_0 and transition matrix $P(n, n+1)$ if and only if:

for all $n \geq 1$, and for all $i_0, i_1, \dots, i_n \in E$, we have:

$$P(X_n=i_n, \dots, X_0=i_0) = \alpha_0(i_0) \prod_{k=1}^n P_{i_{k-1}i_k}(n, n+1)$$

$$= \alpha_0(i_0) P_{i_0i_1} P_{i_1i_2} \dots P_{i_{n-1}i_n}$$

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$P(n, n+1)$ is called the one-step transition matrix.
 More generally we denote $P(m, n) = P(X_n = j | X_m = i)$,
 the ~~probability that~~ transition probability from
 state i at time m to state j at time n . $\boxed{n > m}$

$I(m, n) = \left(P_{ij}(m, n) \right)_{i, j \in E}$ is called the transition
 matrix from m to n , also called $(n-m)$ -step transition matrix:

Properties: ① $P(m, n) = P(m, m+1)P(m+1, m+2) \dots P(n-1, n)$

② $P(m, n) = P(m, l)P(l, n); m \leq l < n$

$$\textcircled{1} \Rightarrow P_{ij}(m, n) = \sum_{i_1 \in E} \dots \sum_{i_{n-1} \in E} P_{i i_1}(m, m+1) P_{i_1 i_2}(m+1, m+2) \dots P_{i_{n-1} j}(n-1, n).$$

$$\boxed{\alpha_n = \alpha_{n-1} P(n-1, n)} \quad \forall n \geq 1.$$

In particular: $\alpha_1 = \alpha_0 P(0, 1)$, $\alpha_2 = \alpha_1 P(1, 2)$.

$$\text{Hence } \boxed{\alpha_n = \alpha_0 P(0, 1) P(1, 2) \dots P(n-1, n)}$$

If the M.C is homogeneous the $P(0, 1) = P(1, 2) = \dots = P(n-1, n) = P$.

Therefore:

$$\boxed{\alpha_n = \alpha_0 P^n}$$

let us go back to the example,

$$\alpha_3 = \alpha_2 P(2,3) = \alpha_1 P(1,2) P(2,3) = \alpha_0 P(0,1) P(1,2) P(2,3) \\ = \alpha_0 P^3 = (\alpha_3(1), \alpha_3(2), \alpha_3(3))$$

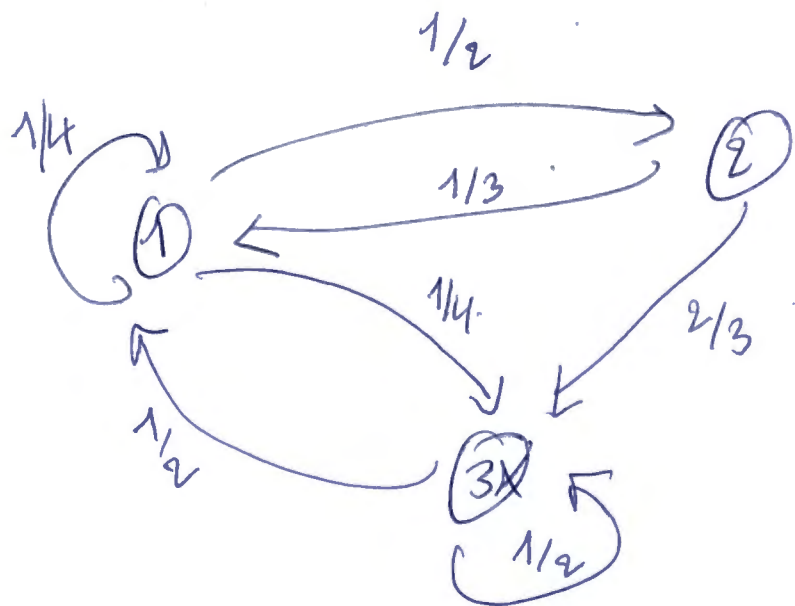
the same for α_4 . (take $\alpha_0 = (\frac{1}{2}, \frac{1}{2}, 0)$)

$$\alpha_4 = \alpha_3 P$$

$$P^3 = P P P = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$(\alpha_0(1), \alpha_0(2), \alpha_0(3)) \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = (0, 0, 0)$$

let us now plot the state diagram of the M.C.



This is called the state transition diagram.