

Introduction to optimal control theory

Christiane P. Koch

Laboratoire Aimé Cotton
CNRS, France

The Hebrew University
Jerusalem, Israel

Outline

0. Terminology

1. Intuitive control schemes and their experimental realization

2. Controllability of a quantum system

3. Variational approach to quantum control


4. Experimental quantum control: closed learning loops

5. Coherent / optimal control of cold systems?

0. Terminology


Quantum mechanics \triangleq probabilistic, but *deterministic* theory

present wave function Schrödinger equation future wave function



Quantum mechanics \triangleq probabilistic, but *deterministic* theory

present wave function Schrödinger equation future wave function



Quantum control:

Given an initial wave function at present,
which dynamics (\triangleq which Hamiltonian)
guarantees a particular outcome in the future?

Optimal / Coherent Control

wave properties of atoms/molecules
(Superposition principle)

variation of phase between different, but indistinguishable
quantum pathways

Optimal / Coherent Control

wave properties of atoms/molecules
(Superposition principle)

variation of phase between different, but indistinguishable
quantum pathways



constructive
interference in
desired channel

destructive
interference in all
other channels

Coherent Control

Optimal Control

Coherent Control

- Goal: improve outcome of process

Optimal Control

Coherent Control

- Goal: improve outcome of process
- vary some parameters



simple, intuitive schemes

Optimal Control

Coherent Control

- Goal: improve outcome of process
- vary some parameters



simple, intuitive schemes

Optimal Control

- Goal: obtain maximal control over process

Coherent Control

- Goal: improve outcome of process
- vary some parameters



simple, intuitive schemes

Optimal Control

- Goal: obtain maximal control over process
- tune “all” available parameters



complex outcome → discovery of new schemes (usually not accessible by intuition)

Coherent Control

- Goal: improve outcome of process
- vary some parameters



simple, intuitive schemes

**in time or in frequency
domain**

Optimal Control

- Goal: obtain maximal control over process
- tune “all” available parameters



complex outcome → discovery of
new schemes (usually not
accessible by intuition)

Coherent Control

- Goal: improve outcome of process
- vary some parameters



simple, intuitive schemes

**in time or in frequency
domain**

Optimal Control

- Goal: obtain maximal control over process
- tune “all” available parameters



complex outcome → discovery of
new schemes (usually not
accessible by intuition)

**in time / frequency “phase
space”**

global or local in time

1. Intuitive control schemes & their experimental realization

Control in frequency domain: Brumer-Shapiro scheme

Control in frequency domain: Brumer-Shapiro scheme

**analogous to double slit
experiment**

but IF between quantum pathways

$n \geq 2$ lasers \rightarrow $n \geq 2$ coherent
pathways from initial to
degenerate final states

Control in frequency domain: Brumer-Shapiro scheme

**analogous to double slit
experiment**

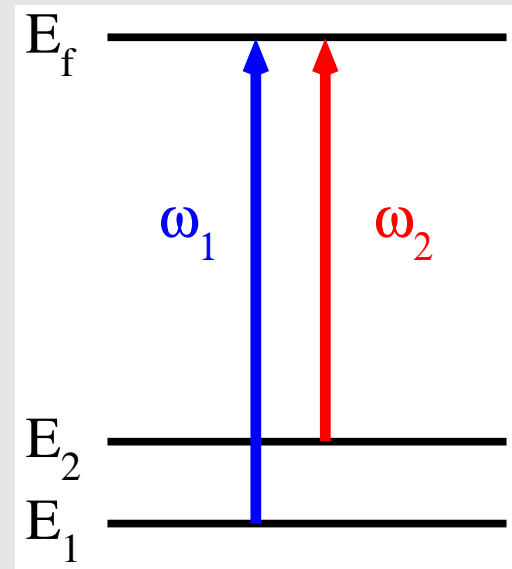
but IF between quantum pathways

$n \geq 2$ lasers \rightarrow $n \geq 2$ coherent
pathways from initial to
degenerate final states

Example: $n = 2$

$$|\Psi(t=0)\rangle = c_1|1\rangle + c_2|2\rangle$$

superposition of 2 eigenstates



Control in frequency domain: Brumer-Shapiro scheme

**analogous to double slit
experiment**

but IF between quantum pathways

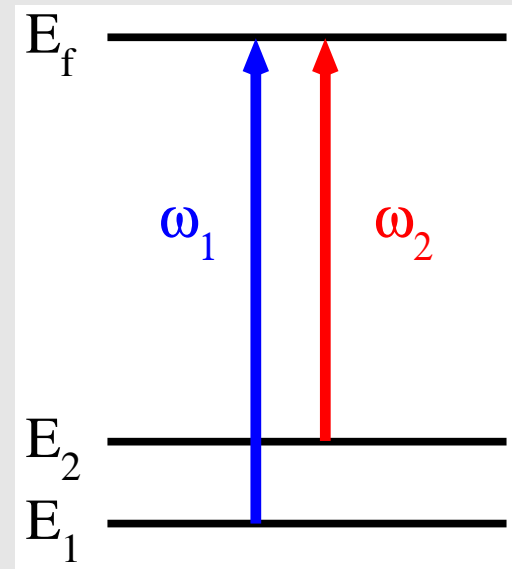
$n \geq 2$ lasers \rightarrow $n \geq 2$ coherent
pathways from initial to
degenerate final states

coefficients of final state super-
position determined by **relative
phase and relative amplitude** of
CW lasers and initial state

Example: $n = 2$

$$|\Psi(t = 0)\rangle = c_1|1\rangle + c_2|2\rangle$$

superposition of 2 eigenstates



Brumer-Shapiro scheme

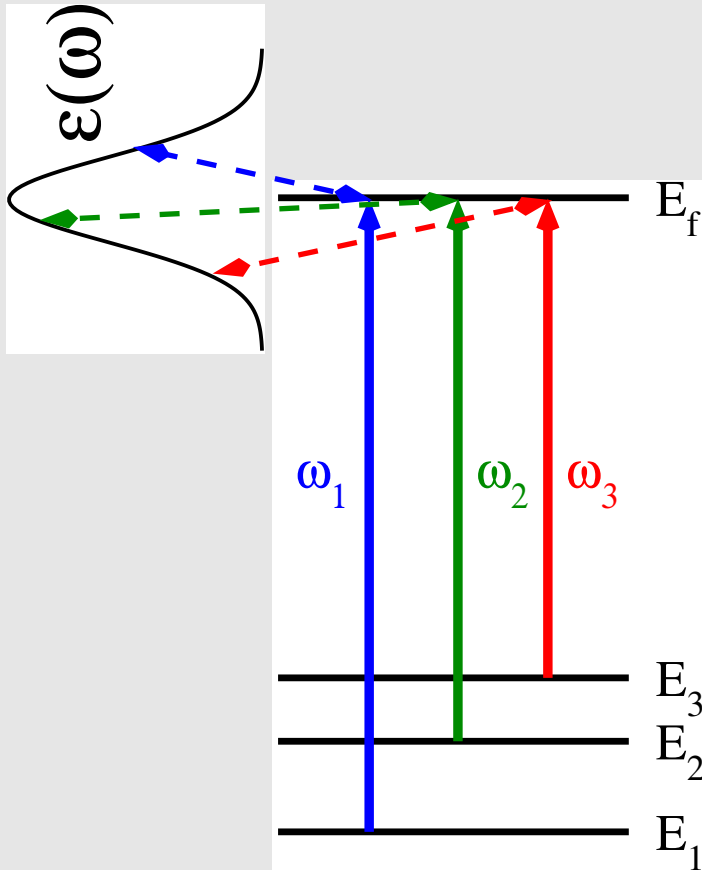
With pulsed lasers

1 photon vs. 3 photon
absorption

Brumer-Shapiro scheme

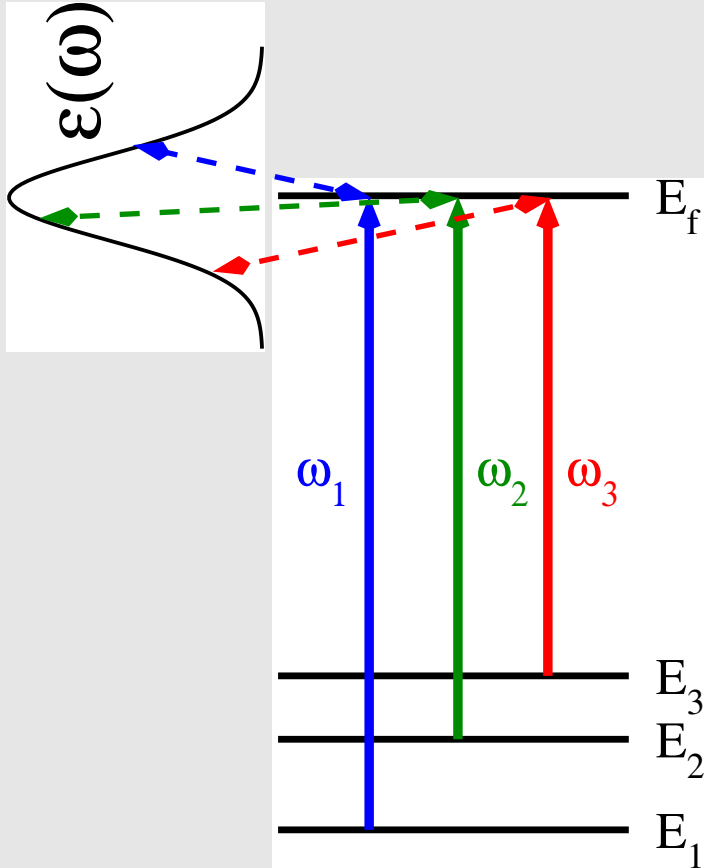
With pulsed lasers

1 photon vs. 3 photon
absorption

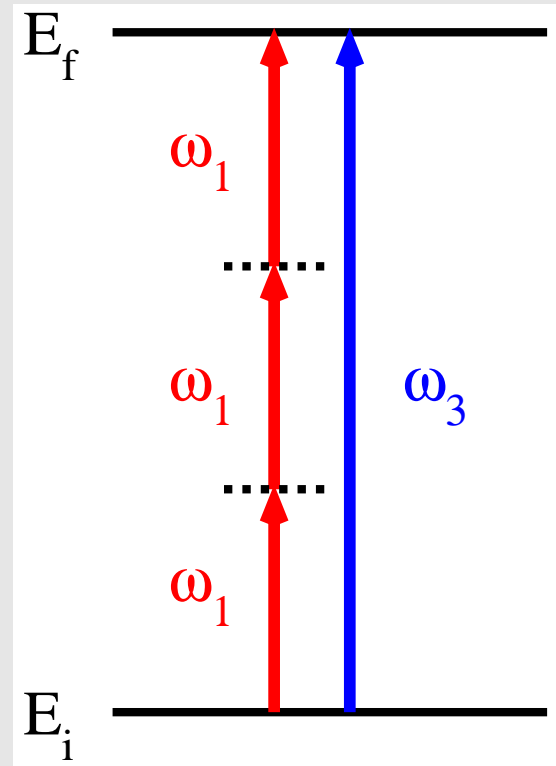


Brumer-Shapiro scheme

With pulsed lasers

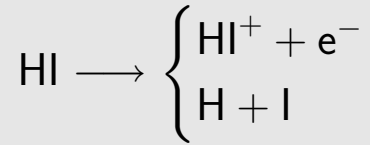


1 photon vs. 3 photon
absorption



1. Control schemes: frequency domain

1 photon vs. 3 photon absorption: selective photodissociation of HI molecule

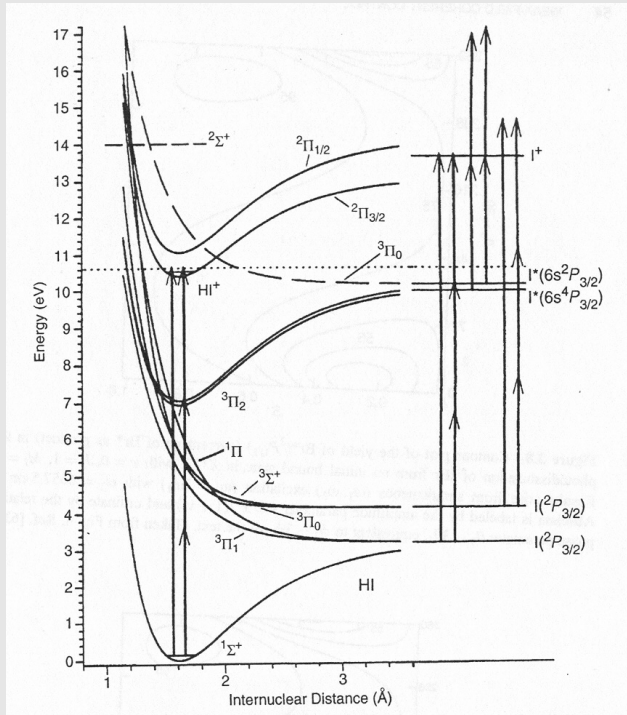
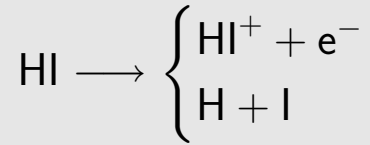


L. Zhu, V. Kleiman, X. Li, S. P. Lu, K. Trentelman, R. J. Gordon

Science **270**, 77 (1995)

1. Control schemes: frequency domain

1 photon vs. 3 photon absorption: selective photodissociation of HI molecule

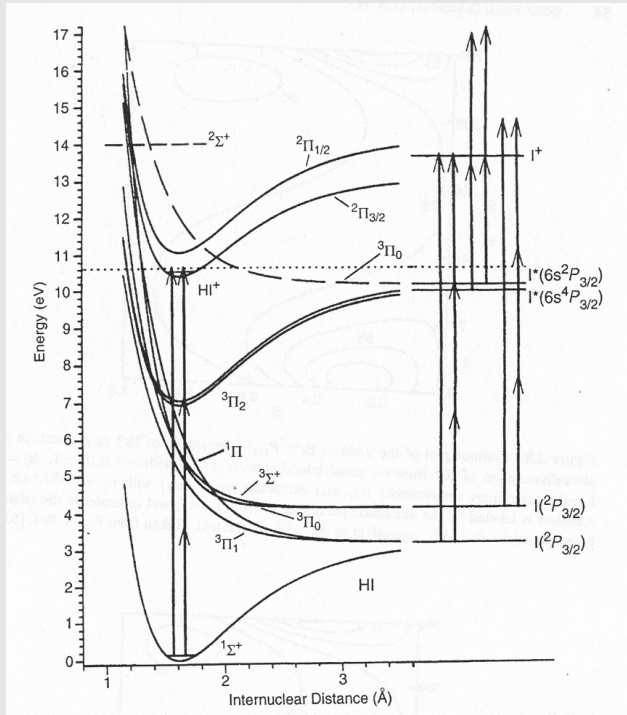
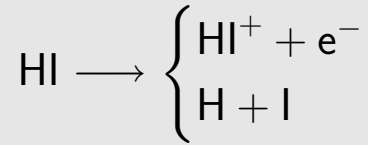


L. Zhu, V. Kleiman, X. Li, S. P. Lu, K. Trentelman, R. J. Gordon

Science **270**, 77 (1995)

1. Control schemes: frequency domain

1 photon vs. 3 photon absorption: selective photodissociation of HI molecule



background gas pressure \rightarrow different
refractive indices

changing pressure \triangleq changing phase differ-
ence between 1-photon & 3-photon fields

L. Zhu, V. Kleiman, X. Li, S. P. Lu, K. Trentelman, R. J. Gordon

Science **270**, 77 (1995)

1. Control schemes: frequency domain

1 photon vs. 3 photon absorption: selective photodissociation of HI molecule

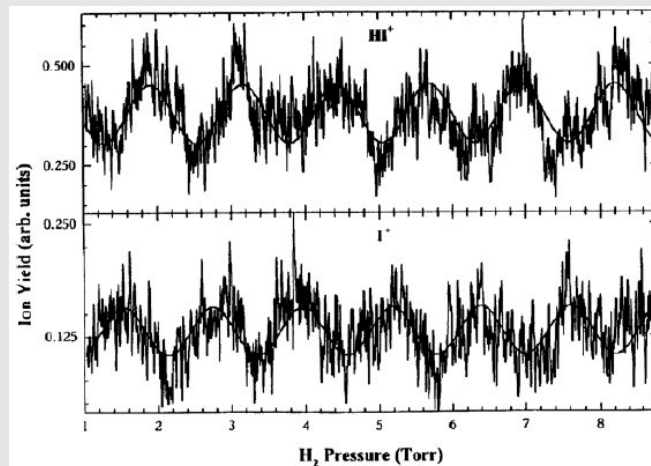
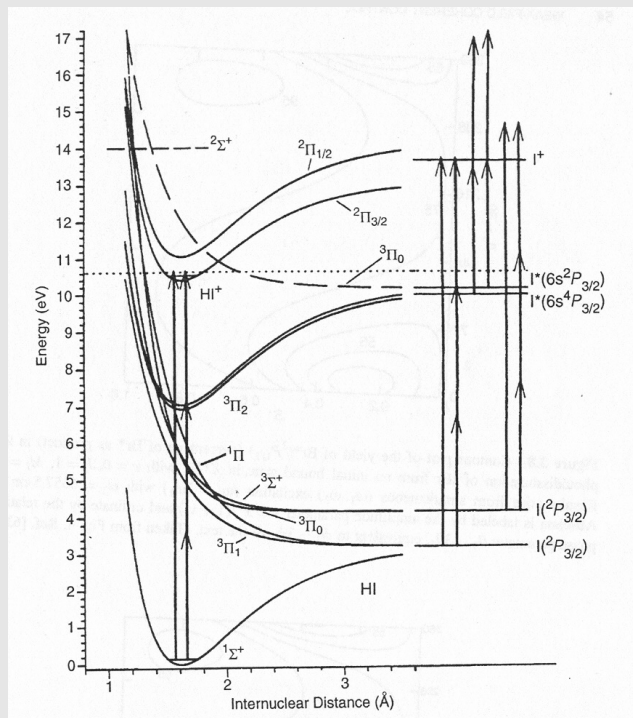
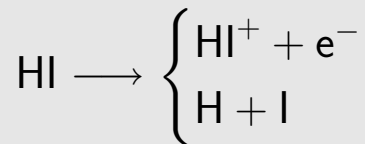


Figure 5. Modulation of the HI^+ and I^+ signals as a function of the difference between the one- and three-photon phases (proportional to the H_2 pressure in the cell used to phase shift the beams).

background gas pressure \rightarrow different refractive indices

changing pressure \triangleq changing phase difference between 1-photon & 3-photon fields

L. Zhu, V. Kleiman, X. Li, S. P. Lu, K. Trentelman, R. J. Gordon

Science **270**, 77 (1995)

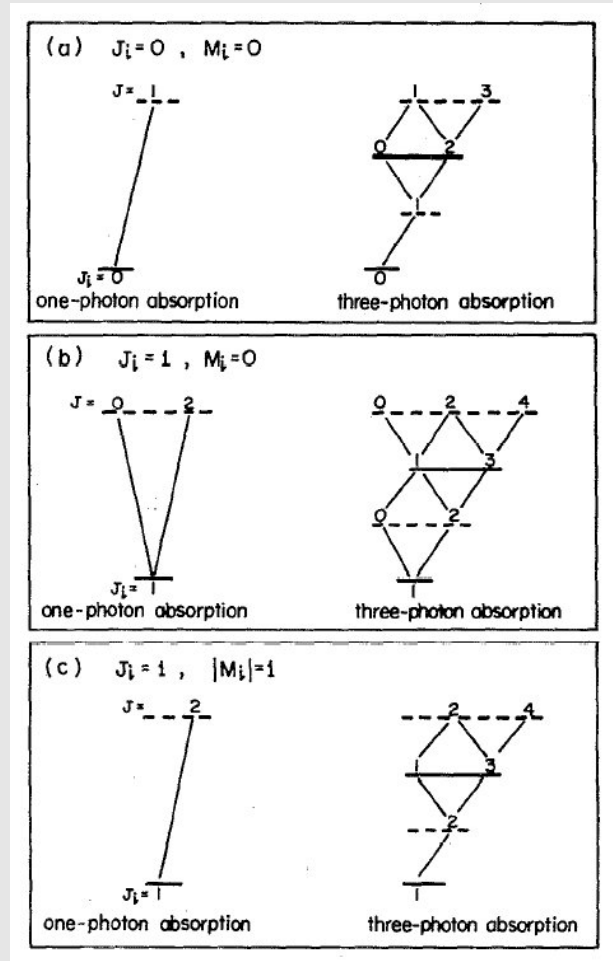
1. Control schemes: frequency domain

1 photon vs. 3 photon absorption

What about rotations?

1 photon vs. 3 photon absorption

What about rotations?

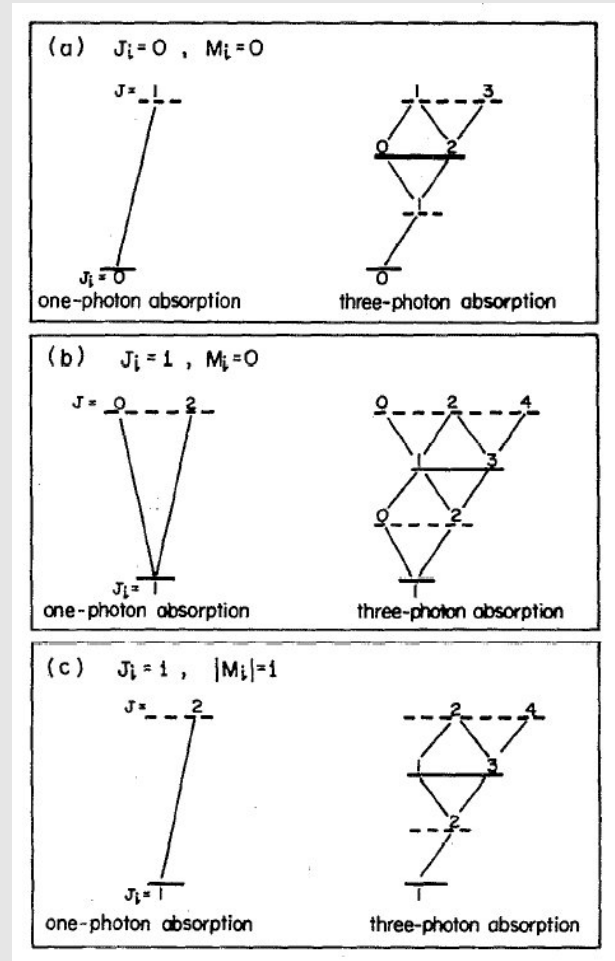


1 photon vs. 3 photon absorption

What about rotations?

- superposition of angular momentum ladders
- *uncontrollable* satellites

M. Shapiro & P. Brumer, *Principles of Quantum Control of Molecular Processes*, Wiley 2003.



Control in the time domain: Tannor-Rice scheme

Control in the time domain: Tannor-Rice scheme

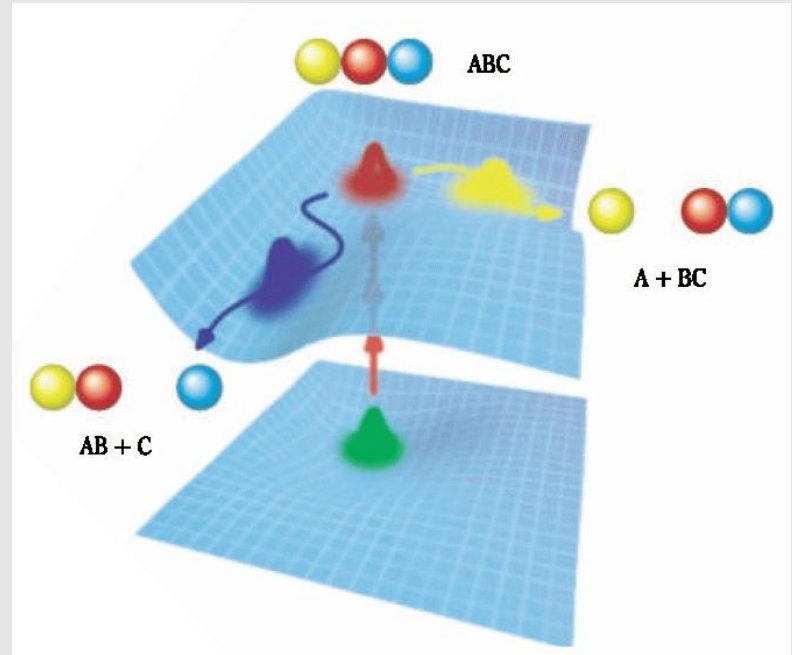
based on localized wave packets

coordinate vs. eigenstate

representation

Control in the time domain: Tannor-Rice scheme

based on localized wave packets
coordinate vs. eigenstate
representation

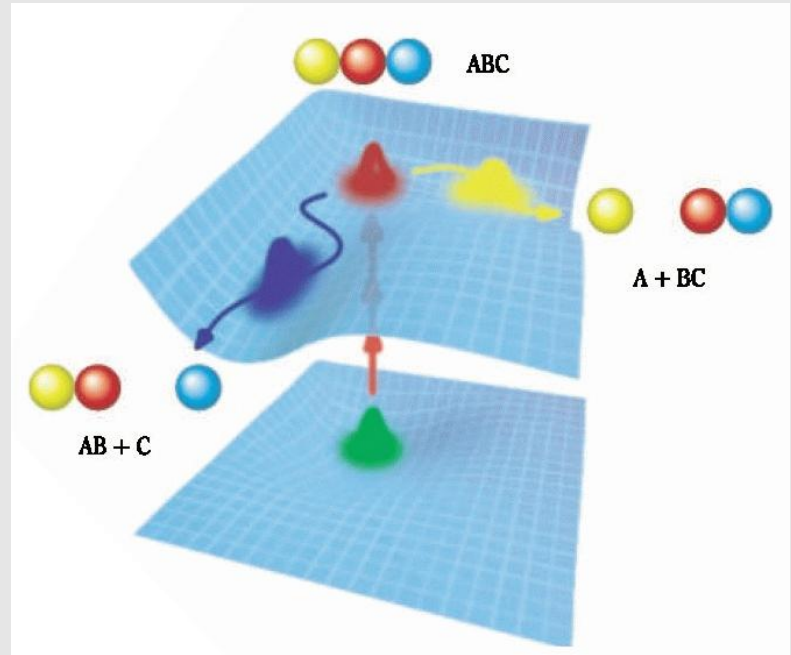


T. Brixner & G. Gerber, Physikal. Blätter April 2001

Control in the time domain: Tannor-Rice scheme

based on localized wave packets
coordinate vs. eigenstate
representation

variation of phase between
quantum paths \triangleq variation of
time delay



T. Brixner & G. Gerber, Physikal. Blätter April 2001

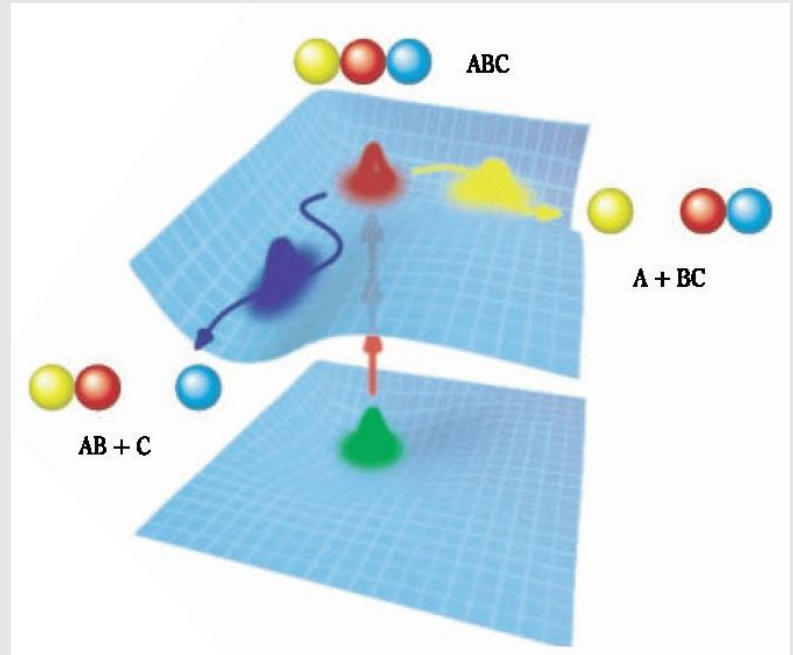
Control in the time domain: Tannor-Rice scheme

based on localized wave packets
coordinate vs. eigenstate
representation

variation of phase between
quantum paths \triangleq variation of
time delay



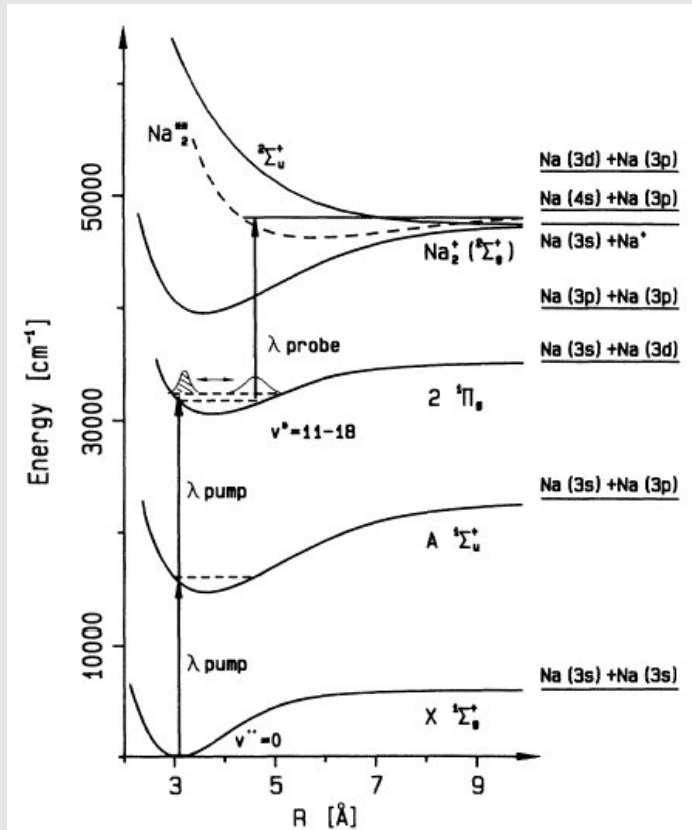
Pump-dump control



T. Brixner & G. Gerber, Physikal. Blätter April 2001

Pump-probe control

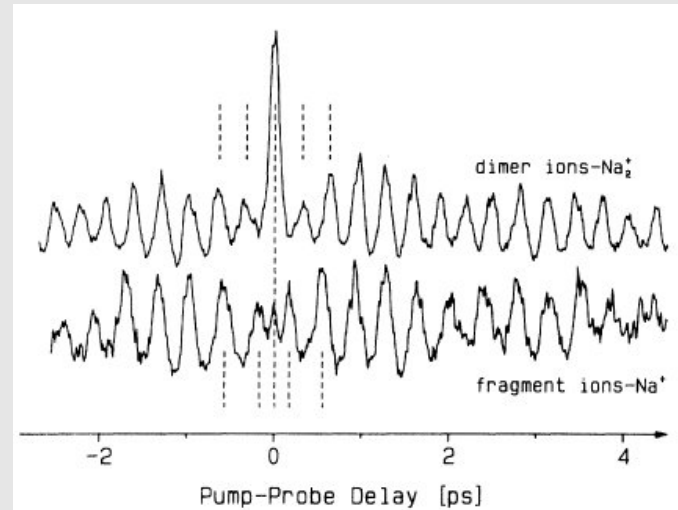
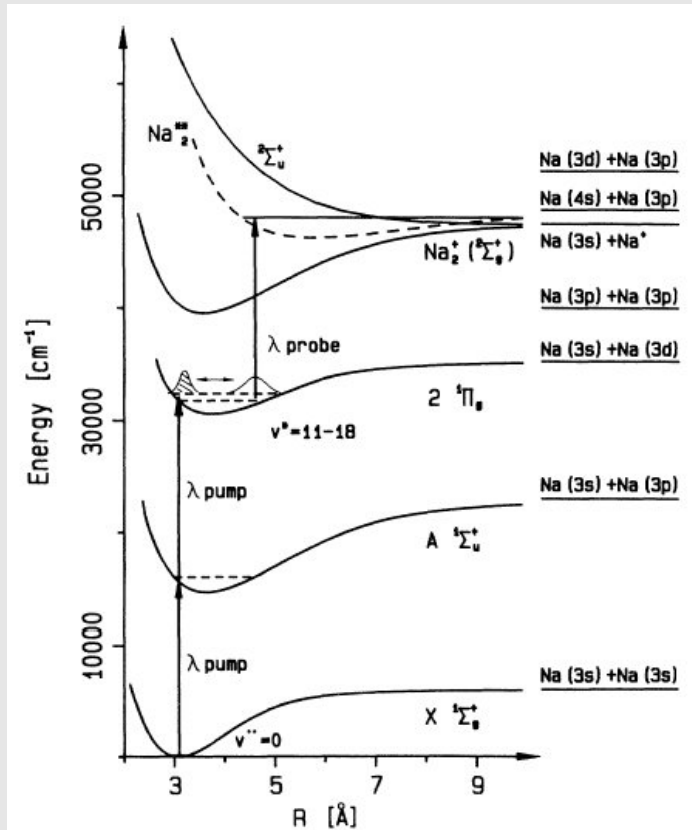
competition between ionization
& dissociative ionization of Na_2



T. Baumert, M. Grosser, R.
Thalweiser, and G. Gerber, *PRL* **67**,
3753 (1991)

Pump-probe control

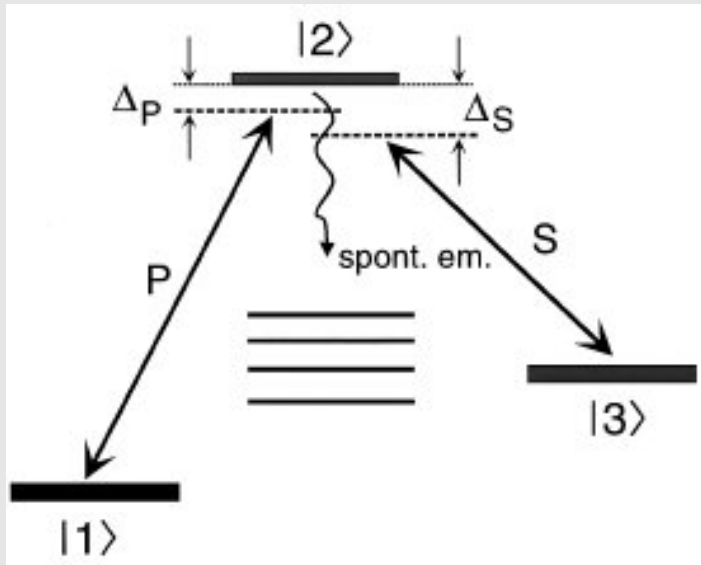
competition between ionization
& dissociative ionization of Na_2



T. Baumert, M. Grosser, R.
Thalweiser, and G. Gerber, *PRL* **67**,
3753 (1991)

1. Control schemes: time domain

Control via STIRAP



Control via STIRAP

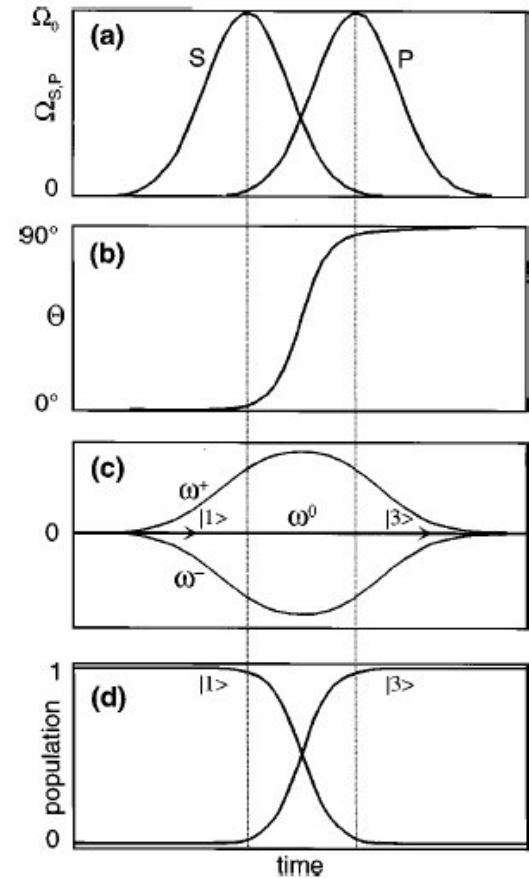
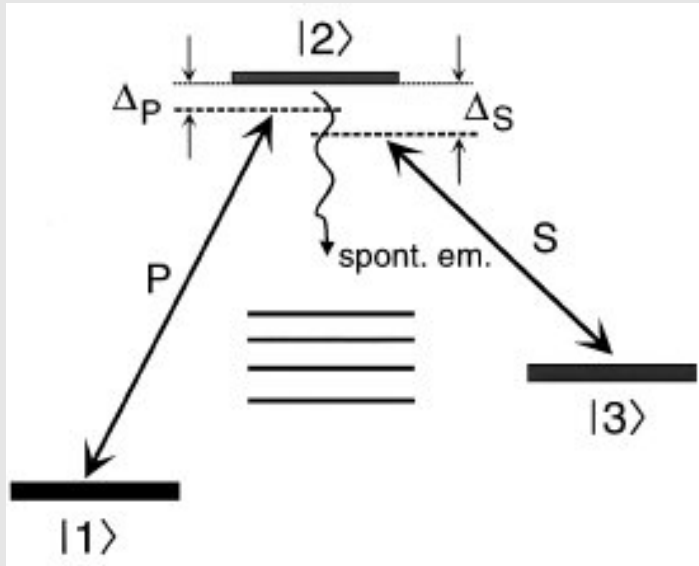
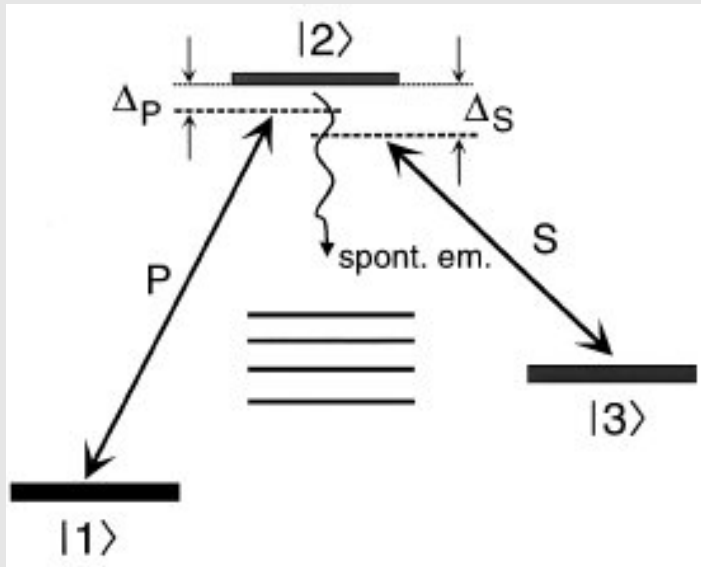


FIG. 3. Time evolution of (a) the Rabi frequencies of the pump and Stokes laser (see Fig. 1); (b) the mixing angle [see Eq. (9)]; (c) the dressed-state eigenvalues [see Eq. (10)]; and (d) the population of the initial level (starting at unity) and the final level (reaching unity).

Control via STIRAP



Counterintuitive pulse sequence: S precedes, but overlaps P

↓
coherent population trapping

K. Bergmann, H. Theuer, and B. W. Shore, *Rev. Mod. Phys.* **70**, 1003 (1998)

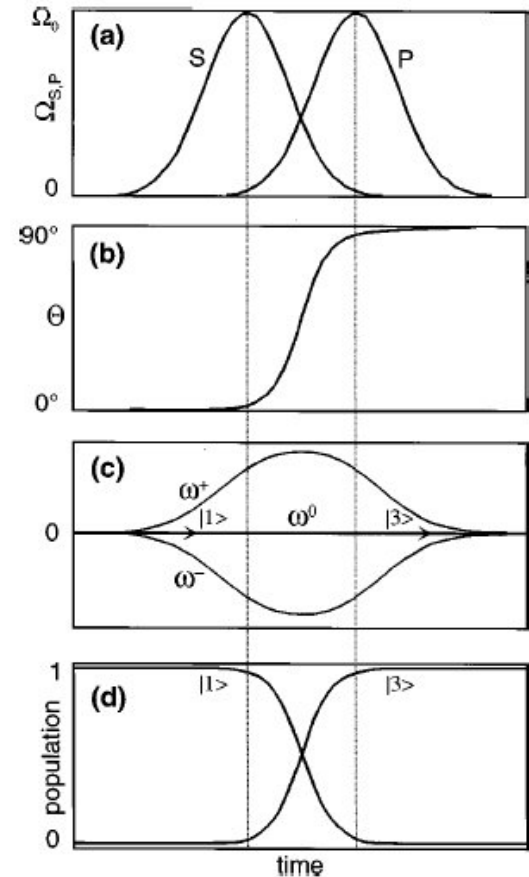


FIG. 3. Time evolution of (a) the Rabi frequencies of the pump and Stokes laser (see Fig. 1); (b) the mixing angle [see Eq. (9)]; (c) the dressed-state eigenvalues [see Eq. (10)]; and (d) the population of the initial level (starting at unity) and the final level (reaching unity).

Limitations of intuitive control schemes

Limitations of intuitive control schemes

- required intensities might be unrealistic (STIRAP)

Limitations of intuitive control schemes

- required intensities might be unrealistic (STIRAP)
- no way to avoid *uncontrollable* satellites
(frequency domain control)

Limitations of intuitive control schemes

- required intensities might be unrealistic (STIRAP)
- no way to avoid *uncontrollable* satellites
(frequency domain control)
- system might be too complex to “guess” a simple control scheme

Limitations of intuitive control schemes

- required intensities might be unrealistic (STIRAP)
- no way to avoid *uncontrollable* satellites
(frequency domain control)
- system might be too complex to “guess” a simple control scheme
- take advantage not only of temporal spacing between pulses but also of the pulse “shapes”

Limitations of intuitive control schemes

- required intensities might be unrealistic (STIRAP)
- no way to avoid *uncontrollable* satellites
(frequency domain control)
- system might be too complex to “guess” a simple control scheme
- take advantage not only of temporal spacing between pulses but also of the pulse “**shapes**”



Optimal Control
Theory



learning loop
experiments

Limitations of intuitive control schemes

- required intensities might be unrealistic (STIRAP)
- no way to avoid *uncontrollable* satellites
(frequency domain control)
- system might be too complex to “guess” a simple control scheme
- take advantage not only of temporal spacing between pulses but also of the pulse “shapes”



Optimal Control
Theory



learning loop
experiments

2. Controllability of a quantum system

Theorem of controllability

Theorem of controllability

$$i\hbar \frac{d}{dt} \psi(t) = \left[\hat{\mathbf{H}}_0 + \sum_l \varepsilon_l(t) \hat{\mathbf{V}}_l \right] \psi(t)$$

Theorem of controllability

$$i\hbar \frac{d}{dt} \psi(t) = \left[\hat{\mathbf{H}}_0 + \sum_l \varepsilon_l(t) \hat{\mathbf{V}}_l \right] \psi(t)$$

- $\hat{\mathbf{H}}_0$ has a *finite* spectrum
- state-to-state transitions



It is always possible to **completely control** evolution from initial to target state

V. Ramakrishna, M. V. Salapaka, M. Dahleh,
H. Rabitz, A. Peirce, *PRA* **51**, 960 (1995)

Theorem of controllability

$$i\hbar \frac{d}{dt} \psi(t) = \left[\hat{\mathbf{H}}_0 + \sum_l \varepsilon_l(t) \hat{\mathbf{V}}_l \right] \psi(t)$$

- $\hat{\mathbf{H}}_0$ has a *finite* spectrum
- state-to-state transitions



It is always possible to **completely control** evolution from initial to target state

V. Ramakrishna, M. V. Salapaka, M. Dahleh,
H. Rabitz, A. Peirce, *PRA* **51**, 960 (1995)

Controllability retained for system **w/ infinitely** many states
by adjusting an external field (ion trap)

s.t. system separated into finite and infinite subsystem

C. Rangan, A. M. Bloch, C. Monroe, P. H. Bucksbaum,
PRL **92**, 113004 (2004)

Optimal control theory

Optimal control theory

time/frequency "phase space" picture

$$t = 0$$

$$|\varphi_i\rangle$$



$$t = T$$

$$|\varphi_f\rangle$$

Inverse problem:

Given the target and the equations of motion,
calculate the field

Optimal control theory

time/frequency "phase space" picture

$$t = 0$$

$$|\varphi_i\rangle$$



$$t = T$$

$$|\varphi_f\rangle$$

Inverse problem:

Given the target and the equations of motion,
calculate the field

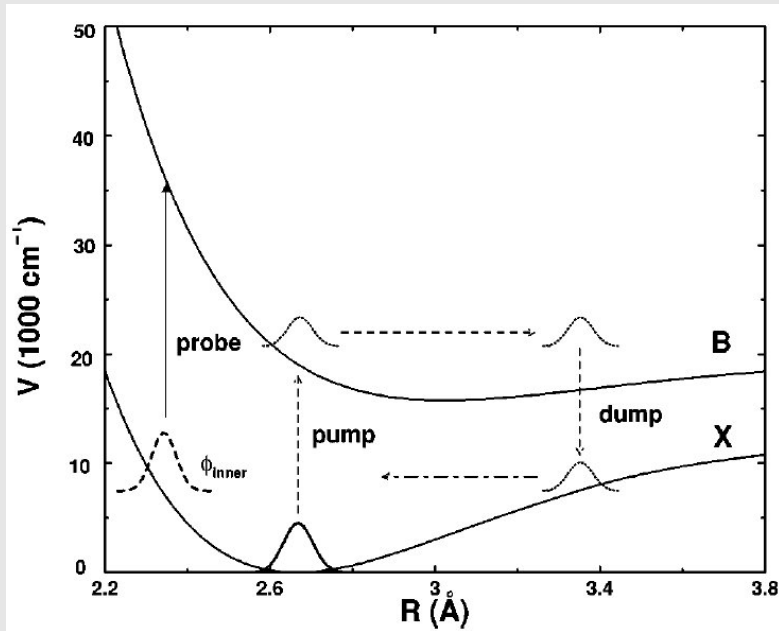
local in time

impose 2 conditions (for phase
and amplitude) \rightarrow derive
equations for field

global in time

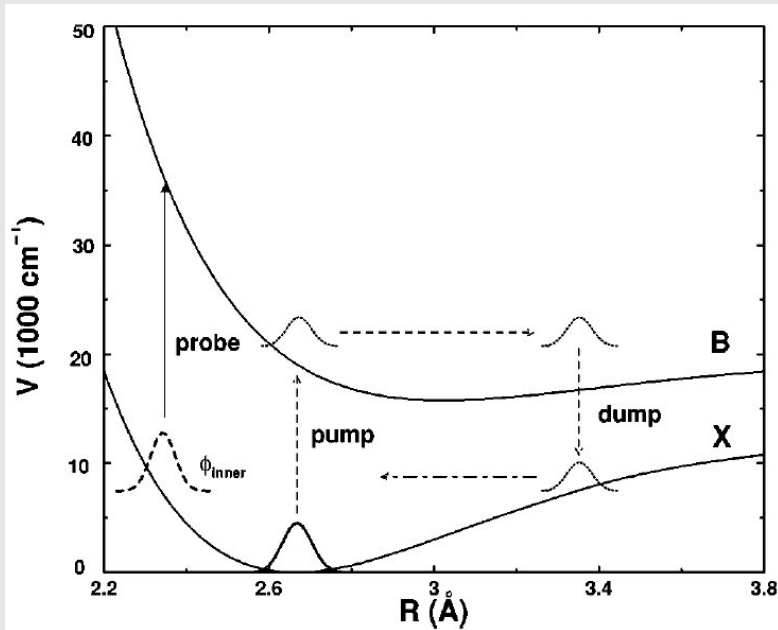
information from dynamics
throughout time interval to reach
desired target at final T

Optimal control theory: Example



Z. Shen, V. Engel, R. Xu, J. Cheng,
Y.-J. Yan, *J. Chem. Phys.* **117**, 16142
(2002)

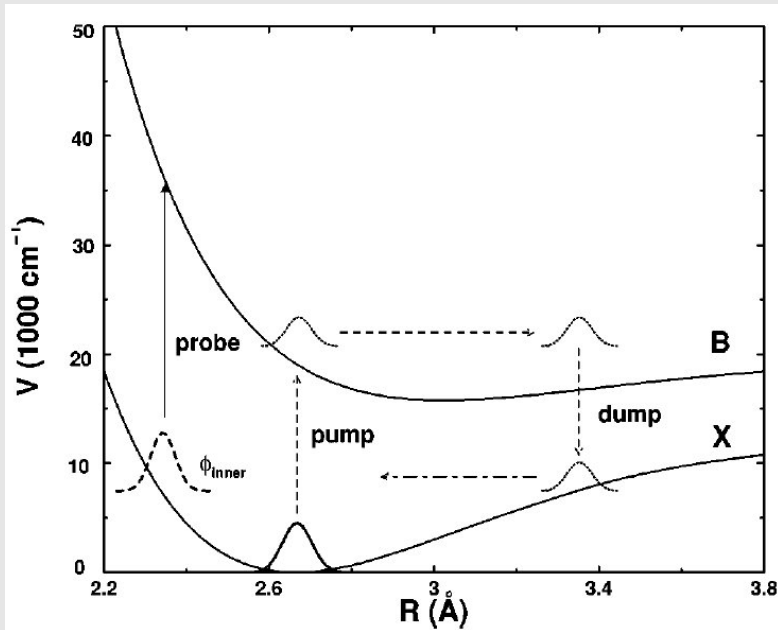
Optimal control theory: Example



Z. Shen, V. Engel, R. Xu, J. Cheng,
Y.-J. Yan, *J. Chem. Phys.* **117**, 16142
(2002)

- **initial state:** ground state of I_2 electronic ground state
- **objective:** Gaussian focussed at the inner turning point
- **equations describing the evolution of the system:** Schrödinger equation of the I_2 molecule coupled to a laser field

Optimal control theory: Example




Z. Shen, V. Engel, R. Xu, J. Cheng,
Y.-J. Yan, *J. Chem. Phys.* **117**, 16142
(2002)

- **initial state:** ground state of I_2 electronic ground state
- **objective:** Gaussian focussed at the inner turning point
- **equations describing the evolution of the system:** Schrödinger equation of the I_2 molecule coupled to a laser field

find the time-dependent pulses which lead to the objective

3. Variational approach to quantum control

OCT: Variational calculus

You can always find a better field  Find it by variation

Define the objective:

$$\text{GOAL} \equiv \|\langle \varphi_i | \hat{\mathbf{U}}^+(T, 0; \boldsymbol{\varepsilon}) | \varphi_f \rangle\|^2 = F$$

as a *functional* of the field $\boldsymbol{\varepsilon}$

OCT: Variational calculus

You can always find a better field \rightarrow Find it by variation

Define the objective:

$$\text{GOAL} \equiv \|\langle \varphi_i | \hat{\mathbf{U}}^+(T, 0; \boldsymbol{\varepsilon}) | \varphi_f \rangle\|^2 = F$$

as a *functional* of the field $\boldsymbol{\varepsilon}$

Goal depends just on final time T

\leadsto new functional J

$$J = F + \int_0^T g(\boldsymbol{\varepsilon}, \varphi) dt$$

with additional constraints to use information from the dynamics (i.e. intermediate times)

Methods to obtain the optimal field

Rabitz' approach

Krotov method

Methods to obtain the optimal field

Rabitz' approach

- “guess” the right functional
- do the variations to obtain eqs. of motion and eq. for the field
- “guess” the correct time discretization s.t. method converges

Krotov method

W. Zhu, J. Botina, H. Rabitz

J. Chem. Phys. **108**, 1953 (1998)

Methods to obtain the optimal field

Rabitz' approach

- “guess” the right functional
- do the variations to obtain eqs. of motion and eq. for the field
- “guess” the correct time discretization s.t. method converges

W. Zhu, J. Botina, H. Rabitz
J. Chem. Phys. **108**, 1953 (1998)

Krotov method

- ingredients: original objective + constraint(s) on the field + EoM of the bare system
- construct auxil. functional with auxil. potential to guarantee monotonic convergence
- derive the field eq. from the minimization of the aux. functional

Sklarz & Tannor, *PRA* **66**, 053619 (2002)
Palao & Kosloff, *PRA* **68**, 062308 (2003)

How to obtain the equation for the optimized field

W. Zhu, J. Botina, H. Rabitz, *J. Chem. Phys.* **108**, 1953 (1998):

$$J = F - 2\Re\left\{\langle\varphi(T)|\varphi_f\rangle\int_0^T dt \underbrace{\left\langle\psi(t)\left|\frac{\partial}{\partial t} + \frac{i}{\hbar}\hat{\mathbf{H}}(\epsilon)\right|\varphi(t)\right\rangle}_{\text{}}\right\} - \alpha\int_0^T \frac{\epsilon^2(t)}{S(t)}$$

How to obtain the equation for the optimized field

W. Zhu, J. Botina, H. Rabitz, *J. Chem. Phys.* **108**, 1953 (1998):

$$J = F - 2\Re\left\{\langle\varphi(T)|\varphi_f\rangle \int_0^T dt \underbrace{\left\langle\psi(t)\left|\frac{\partial}{\partial t} + \frac{i}{\hbar}\hat{\mathbf{H}}(\epsilon)\right|\varphi(t)\right\rangle}_{\text{Schrödinger eq.}}\right\} - \alpha \int_0^T \frac{\epsilon^2(t)}{S(t)}$$

↓
original objective
 $|\langle\varphi(T)|\varphi_f\rangle|^2$

↓
minim. pulse energy,
enforce pulse shape $S(t)$

How to obtain the equation for the optimized field

W. Zhu, J. Botina, H. Rabitz, *J. Chem. Phys.* **108**, 1953 (1998):

$$J = F - 2\Re\left\{\langle\varphi(T)|\varphi_f\rangle \int_0^T dt \underbrace{\left\langle\psi(t)\left|\frac{\partial}{\partial t} + \frac{i}{\hbar}\hat{\mathbf{H}}(\boldsymbol{\epsilon})\right|\varphi(t)\right\rangle}_{\text{Schrödinger eq.}}\right\} - \alpha \int_0^T \frac{\boldsymbol{\epsilon}^2(t)}{S(t)}$$

↓
original objective
 $|\langle\varphi(T)|\varphi_f\rangle|^2$

↓
minim. pulse energy,
enforce pulse shape $S(t)$

Variation w.r.t. $|\varphi(t)\rangle$, Lagrange multiplier $\langle\psi(t)|$, $\boldsymbol{\epsilon}(t)$
keeping only linear terms

Remember: variation of function $f(x)$ w.r.t. x

$$\delta f = \frac{\partial f}{\partial x} \delta x$$

extremum for $\delta f = 0$

Remember: variation of function $f(x)$ w.r.t. x

$$\delta f = \frac{\partial f}{\partial x} \delta x$$

extremum for $\delta f = 0$

$$\begin{aligned} \frac{\partial}{\partial t} |\varphi(t)\rangle &= \frac{i}{\hbar} [\hat{\mathbf{H}}_0 - \hat{\mu} \epsilon(t)] |\varphi(t)\rangle \quad \text{with} \quad |\varphi(0)\rangle = |\varphi_i\rangle \\ \frac{\partial}{\partial t} |\psi(t)\rangle &= \frac{i}{\hbar} [\hat{\mathbf{H}}_0 - \hat{\mu} \epsilon(t)] |\psi(t)\rangle \quad \text{with} \quad |\psi(T)\rangle = |\varphi_f\rangle \end{aligned}$$

$$\epsilon(t) = -\frac{S(t)}{\alpha} \Im \left\{ \langle \varphi(T) | \varphi_f \rangle \langle \psi(t) | \hat{\mu} | \varphi(t) \rangle \right\}$$

nonlinear set of equations!

Iterative scheme: Step 1

solve first

$$\frac{\partial}{\partial t} |\psi(t)\rangle^{(0)} = \frac{i}{\hbar} \left[\hat{\mathbf{H}}_0 - \hat{\mu} \tilde{\varepsilon}(t) \right] |\psi(t)\rangle^{(0)}$$

Iterative scheme: Step 1

solve first

$$\frac{\partial}{\partial t} |\psi(t)\rangle^{(0)} = \frac{i}{\hbar} \left[\hat{\mathbf{H}}_0 - \hat{\mu} \tilde{\epsilon}(t) \right] |\psi(t)\rangle^{(0)}$$

then

$$\frac{\partial}{\partial t} |\varphi(t)\rangle^{(1)} = \frac{i}{\hbar} \left[\hat{\mathbf{H}}_0 - \hat{\mu} \epsilon^{(0)}(t) \right] |\varphi(t)\rangle^{(1)}$$

with

$$\epsilon^{(0)}(t) = -\frac{S(t)}{\alpha} \Im \left\{ {}^{(1)}\langle \varphi(t) | \psi(t) \rangle^{(0)} {}^{(0)}\langle \psi(t) | \hat{\mu} | \varphi(t) \rangle^{(1)} \right\}$$

where we have used $\langle \varphi(T) | \varphi_f \rangle = \langle \varphi(t) | \psi(t) \rangle$

Iterative scheme: Step 2

now solve

$$\frac{\partial}{\partial t} |\psi(t)\rangle^{(1)} = \frac{i}{\hbar} \left[\hat{\mathbf{H}}_0 - \hat{\mu} \epsilon^{(1)}(t) \right] |\psi(t)\rangle^{(1)}$$

then

$$\frac{\partial}{\partial t} |\varphi(t)\rangle^{(2)} = \frac{i}{\hbar} \left[\hat{\mathbf{H}}_0 - \hat{\mu} \epsilon^{(2)}(t) \right] |\varphi(t)\rangle^{(2)}$$

with

$$\begin{aligned} \epsilon^{(1)}(t) &= -\frac{S(t)}{\alpha} \Im \left\{ {}^{(1)}\langle \varphi(t) | \psi(t) \rangle^{(1)} {}^{(1)}\langle \psi(t) | \hat{\mu} | \varphi(t) \rangle^{(1)} \right\} \\ \epsilon^{(2)}(t) &= -\frac{S(t)}{\alpha} \Im \left\{ {}^{(2)}\langle \varphi(t) | \psi(t) \rangle^{(1)} {}^{(1)}\langle \psi(t) | \hat{\mu} | \varphi(t) \rangle^{(2)} \right\} \end{aligned}$$

Iterative scheme

$$\tilde{\epsilon}(t) \rightarrow |\psi(t)\rangle^{(0)} \rightarrow \epsilon^{(0)}(t), |\varphi(t)\rangle^{(1)} \longrightarrow \epsilon^{(1)}(t), |\psi(t)\rangle^{(1)} \rightarrow \epsilon^{(2)}(t), |\varphi(t)\rangle^{(2)} \longrightarrow \dots$$

Iterative scheme

$$\tilde{\epsilon}(t) \rightarrow |\psi(t)\rangle^{(0)} \rightarrow \epsilon^{(0)}(t), |\varphi(t)\rangle^{(1)} \longrightarrow \epsilon^{(1)}(t), |\psi(t)\rangle^{(1)} \rightarrow \epsilon^{(2)}(t), |\varphi(t)\rangle^{(2)} \longrightarrow \dots$$

$$\epsilon^{(0)}(t) = -\frac{S(t)}{\alpha} \Im \left\{ {}^{(1)}\langle \varphi(t) | \psi(t) \rangle^{(0)} {}^{(0)}\langle \psi(t) | \hat{\mu} | \varphi(t) \rangle^{(1)} \right\}$$

$$\epsilon^{(1)}(t) = -\frac{S(t)}{\alpha} \Im \left\{ {}^{(1)}\langle \varphi(t) | \psi(t) \rangle^{(1)} {}^{(1)}\langle \psi(t) | \hat{\mu} | \varphi(t) \rangle^{(1)} \right\}$$

$$\epsilon^{(2)}(t) = -\frac{S(t)}{\alpha} \Im \left\{ {}^{(2)}\langle \varphi(t) | \psi(t) \rangle^{(1)} {}^{(1)}\langle \psi(t) | \hat{\mu} | \varphi(t) \rangle^{(2)} \right\}$$

How does the optimization work?

How does the optimization work?

Rabitz' approach

$$\epsilon(t) = -\frac{S(t)}{\alpha} \Im \left\{ \langle \varphi(T) | \varphi_f \rangle \langle \psi(t) | \hat{\mu} | \varphi(t) \rangle \right\}$$

Krotov method

$$\epsilon(t) = -\frac{S(t)}{\alpha} \Im \left\{ \langle \varphi_i | \hat{\mathbf{U}}^+(T, 0; \epsilon^0) | \varphi_f \rangle \langle \varphi_f | \hat{\mathbf{U}}^+(t, T; \epsilon^0) \hat{\mu} \hat{\mathbf{U}}(t, 0; \epsilon^1) | \varphi_i \rangle \right\}$$

How does the optimization work?

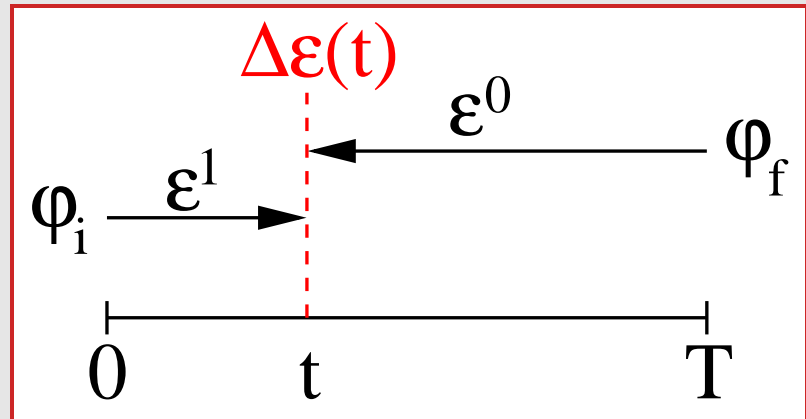
Rabitz' approach

$$\epsilon(t) = -\frac{S(t)}{\alpha} \Im \left\{ \langle \varphi(T) | \varphi_f \rangle \langle \psi(t) | \hat{\mu} | \varphi(t) \rangle \right\}$$

Krotov method

$$\epsilon(t) = -\frac{S(t)}{\alpha} \Im \left\{ \langle \varphi_i | \hat{\mathbf{U}}^+(T, 0; \epsilon^0) | \varphi_f \rangle \langle \varphi_f | \hat{\mathbf{U}}^+(t, T; \epsilon^0) \hat{\mu} \hat{\mathbf{U}}(t, 0; \epsilon^1) | \varphi_i \rangle \right\}$$

Interference between
past and future
events



How does the optimization work?

1. set the parameters of the algorithm:
optimization time T , weight of constraint α , shape function $S(t)$
2. choose a physically sensible guess field
3. run the iterative scheme
4. **analyze the optimal field**

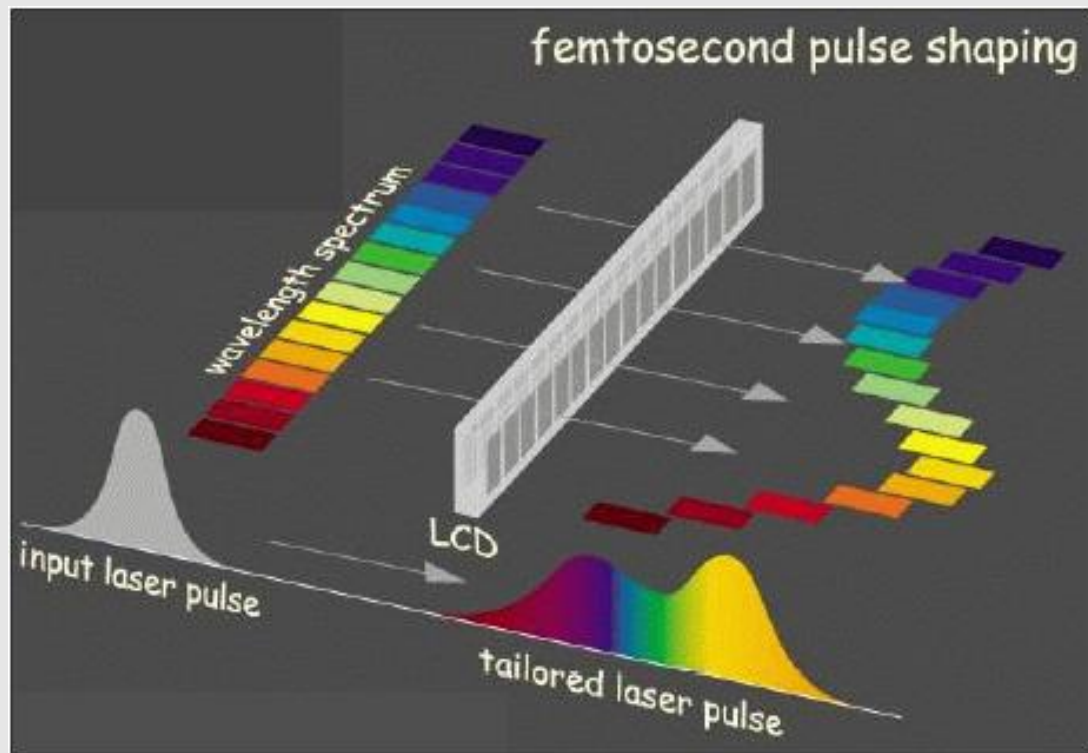
4. Experimental quantum control: Closed learning loops

The versatility of light

frequency domain
pulse shaping using
AOM's or LCD's

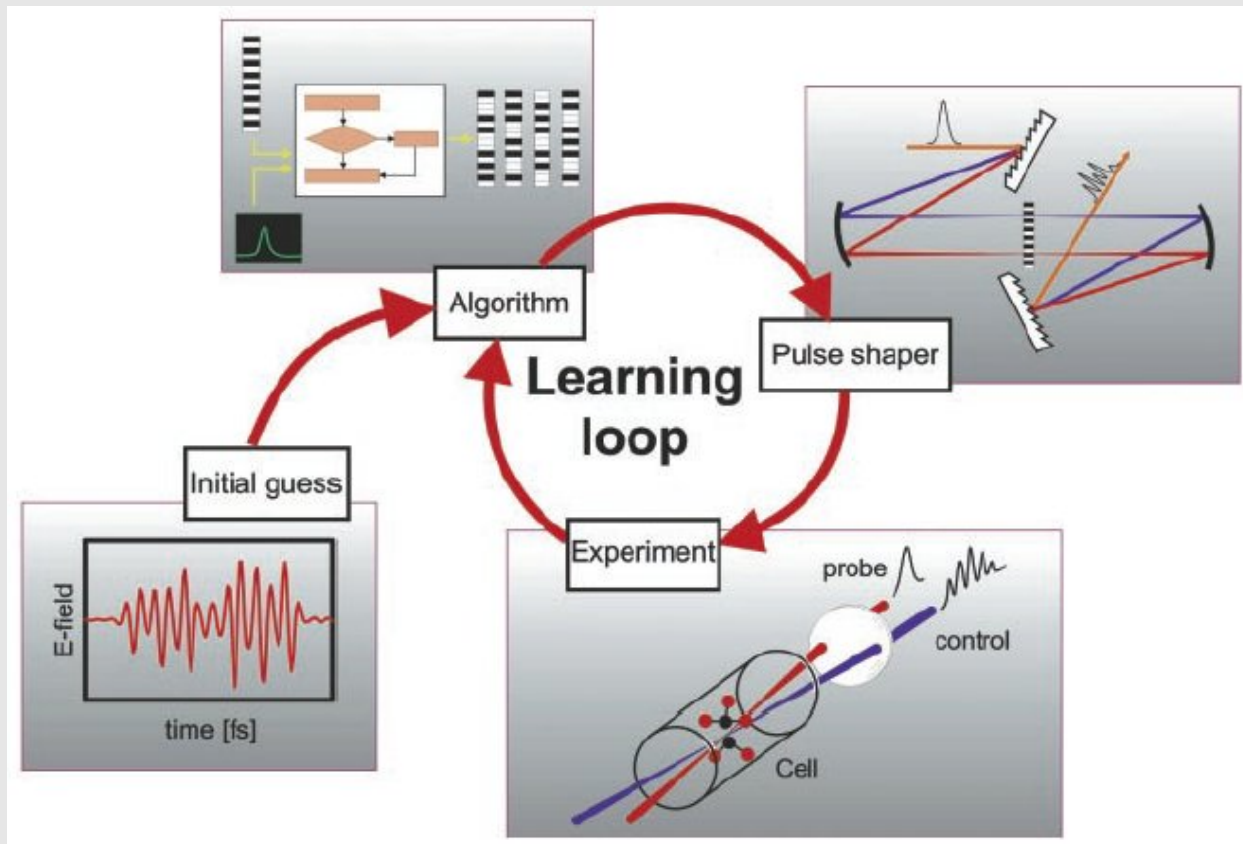
for both amplitude
and phase

available in VIS,
near-IR



T. Brixner & G. Gerber, *ChemPhysChem*, **4**, 418 (2003)

Control experiments



H. Rabitz, R. de Vivie-Riedle, M. Motzkus, K. Kompa
Science, **288**, 824 (2000)

Control experiments

“Teaching lasers to
control molecules”

R. S. Judson, H.

Rabitz

PRL **68**, 1500

(1992)

Control experiments

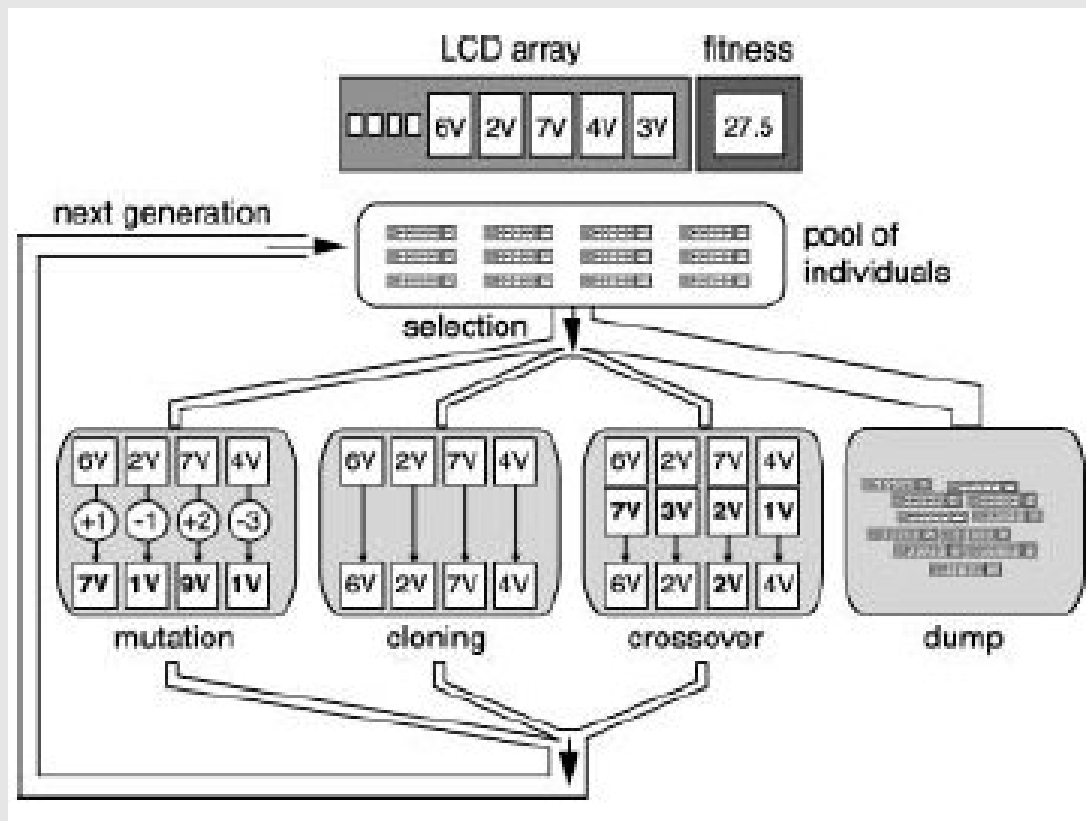
“Teaching lasers to
control molecules”

R. S. Judson, H.

Rabitz

PRL **68**, 1500

(1992)



T. Brixner & G. Gerber, *ChemPhysChem* **4**, 418 (2003)

Theory vs. Experiment

Theory

uses information about many different pathways contained in Schrödinger eq.



very efficient,
but optimal pulses extremely complex
(additional experimental constraints
destroy convergence in currently available
algorithms)

Theory vs. Experiment

Theory

uses information about many different pathways contained in Schrödinger eq.



very efficient,
but optimal pulses extremely complex
(additional experimental constraints
destroy convergence in currently available
algorithms)

Experiment

pulse shapers steered by evolutionary algorithm (closed learning loops)



many repetitions,
no insight
(combination with ultracold
experiments may be difficult)

Theory vs. Experiment

Theory

uses information about many different pathways contained in Schrödinger eq.

Experiment

pulse shapers steered by evolutionary algorithm (closed learning loops)



very efficient,
but optimal pulses extremely complex
(additional experimental constraints
destroy convergence in currently available
algorithms)



many repetitions,
no insight
(combination with ultracold
experiments may be difficult)

—► **Comparison between theory and experiment necessary,
but not straightforward!**

Theory can provide estimate of **feasibility**, i.e. experimentally required
spectral width and intensity

5. Coherent / optimal control of cold systems?

Theoretical proposals

Cold systems ideally suited for coherent processes

Theoretical proposals

Cold systems ideally suited for coherent processes

- controlled cold chemistry
→ S. Jørgensen, R. Kosloff
 - STIRAP to convert atomic to molecular BEC
→ P. D. Drummond, K. V. Kheruntsyan, D. J. Heinzen & R. H. Wynar, *PRA* **65**, 063619 (2002)
 - coherent photoassociation ?
(BEC → J. Javanainen, M. Mackie, *PRA* **59**, R3186 (1999))
-

Theoretical proposals: Optimal control

Cold systems ideally suited for coherent processes

Theoretical proposals: Optimal control

Cold systems ideally suited for coherent processes

- controlled scattering (for quantum computing with qubits) → T. Calarco U. Dorner, P. Julienne, C. Williams, P. Zoller, quant-ph/0403197
 - quantum computing with molecules → C. M. Tesch & R. de Vivie-Riedle, *PRL* **89**, 157901 (2002) , J. P. Palao & R. Kosloff, *PRL* **89**, 188301 (2002)
 - coherent stabilization of ultracold molecules → C. P. Koch, J. P. Palao, R. Kosloff & F. Masnou-Seeuws, *PRA* in press
-

Control experiments with cold systems?

Control experiments with cold systems?

so far none!

Control experiments with cold systems?

so far none!

- STIRAP in optical lattice not (yet?) successful
- control community \neq cold community
- learning loops may not be feasible for cold experiments

Control experiments with cold systems?

so far none!

- STIRAP in optical lattice not (yet?) successful
- control community \neq cold community
- learning loops may not be feasible for cold experiments



- better “overlap” between theory and experiment
→ **mask function**

T. Hornung, M. Motzkus, R. de Vivie-Riedle, *J. Chem. Phys.*
115, 3105 (2001)

- combine “**cold**” and “**hot**” experiments ?

Summary

- **It is possible to take advantage of quantum coherences !**
(constructive IF in desired channel, destructive IF in all other channels)
- A few **intuitive** schemes to control quantum processes exist (limited applicability).
- **Optimal** control can be employed for a general solution of the control problem.
- It relies on the theorem of **controllability**.
- Specific solutions can be found using the **variational principle** and **iterative search schemes**.