

بسم الله الرحمن الرحيم



King Saud University College of Science Physics & Astronomy Dept.

PHYS 103 (GENERAL PHYSICS) CHAPTER 3: VECTORS LECTURE NO. 4

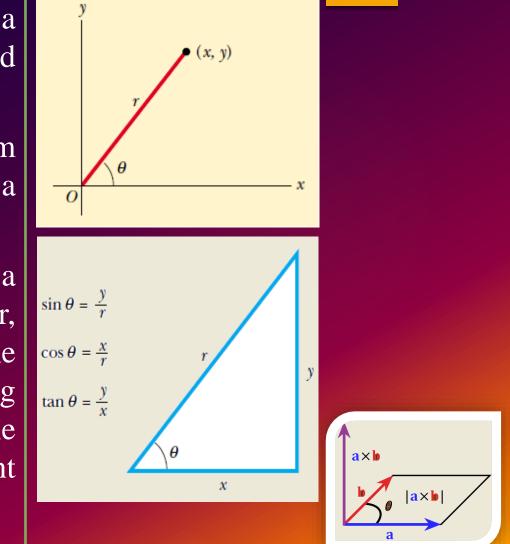
THIS PRESENTATION HAS BEEN PREPARED BY: DR. NASSR S. ALZAYED

Lecture Outline

- Here is a quick list of the subjects that we will cover in this presentation. It is based on Serway, Ed. 6
- ► 3.1 Coordinate Systems (Cartezian & Polar)
- ► 3.2 Vector and Scalar Quantities
- ► 3.3 Some Properties of Vectors (Addition, subtraction, ...)
- ▶ 3.4 Components of a Vector and Unit Vectors
- ► Examples
- Lecture Summary
- Activities (Interactive Flashes)
- ▶ Quizzes

3.1 Coordinate Systems

- Many aspects of physics involve a description of a location in space. This usually is implemented using: *coordinate systems*
- Cartesian coordinate system is one simple system in which horizontal and vertical axes intersect at a point defined as the origin.
- Sometimes it is more convenient to represent a point in a plane by its plane polar coordinates (r, θ), In this *polar coordinate system*, r is the distance from the origin to the point having Cartesian coordinates (x, y), and θ is the angle between a line drawn from the origin to the point and a fixed axis



3.1 Conversion Between Coordinate Systems

we can obtain the Cartesian coordinates from Polar coordinates by using the equations:

$x = r\cos\theta$	(3.1)
$y = r\sin\theta$	(3.2)
$\tan \theta = \frac{y}{x}$	(3.3)
$r = \sqrt{x^2 + y^2}$	(3.4)

- These four expressions relating the coordinates (x, y) to the coordinates (r, θ) apply only when positive θ is an angle measured counterclockwise from the positive x axis.
- If the reference axis for the polar angle θ is chosen to be one other than the positive x axis or if the sense of increasing θ is chosen differently, then the expressions relating the two sets of coordinates will change.

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Example 3.1 Polar Coordinates

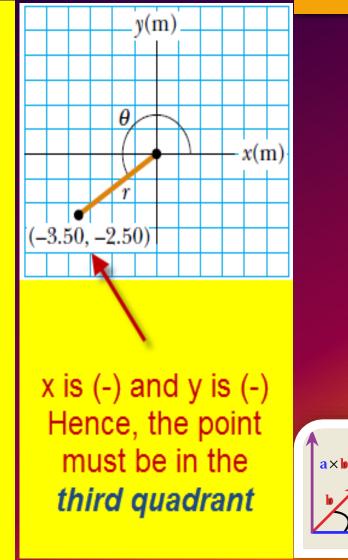
- The Cartesian coordinates of a point in the xy plane are (x, y) = (-3.50, -2.50) m, as shown in the figure. Find the polar, (r, θ), coordinates of this point.
- **Solution:**

$$\therefore r = \sqrt{x^{2} + y^{2}} = \sqrt{(-3.5)^{2} + (-2.5)^{2}} = 4.30 m$$

$$\therefore \tan \theta = \frac{y}{x} = \frac{-2.5}{-3.5} = 0.714$$

$$\therefore \theta = 216^{\circ}$$

Note that you must use the signs of x and y to find that the point lies in the *third quadrant* of the coordinate system. That is, $\theta = 216^{\circ}$ and not 35.5°.



3.2 Vector and Scalar Quantities

- A scalar quantity is completely specified by a single value with an appropriate unit and has no direction.
- A vector quantity is completely specified by a number and appropriate units plus a direction.

Below examples of scalar and vector quantities	
scalar quantities	vector quantities
Temperature	Velocity
Density	Acceleration
Distance	Force
Mass	Displacement
Speed	Torque
Volume	Weight

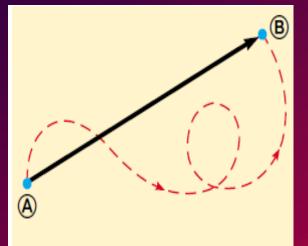
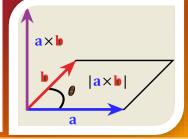
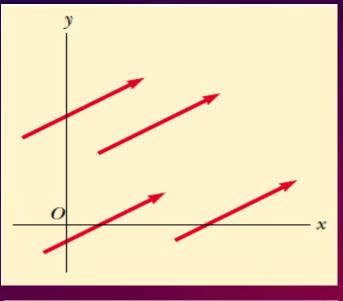


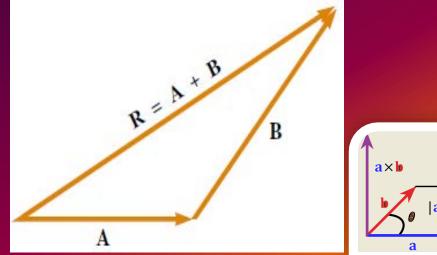
Figure 3.4 As a particle moves from (A) to (B) along an arbitrary path represented by the broken line, its displacement is a vector quantity shown by the arrow drawn from (A) to (B).



3.3 Some Properties of Vectors (1)

- Equality of Two Vectors: A = B if A = B and if A and B point in the same direction along parallel lines
- Adding Vectors: To add vector B to vector A, first draw vector A on graph paper, and then draw vector B to the same scale with its tail starting from the tip of A, as shown in Figure. The resultant vector R = A + B is the vector drawn from the tail of A to the tip of B.
- It is also possible to add vectors using Unit vectors. We shall discuss this feature later in this lecturer.





3.3 Some Properties of Vectors (2)

- \triangleright commutative law of addition : $\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$
- ► associative law of addition: A + (B + C) = (A + B) + C
- Negative of a Vector: The negative of the vector A is defined as the vector that when added to A gives zero for the vector sum. That is:
- A + (-A) = 0. The vectors A and -A have the same magnitude but point in *opposite directions*
- Subtracting Vectors: We define the operation A B as vector -B added to vector A: A B = A + (-B)
- Multiplying a Vector by a Scalar: mA has same direction of A with mA in magnitude. -mA has opposite direction of A with mA in magnitude.
- For example, the vector 5A is five times as long as A and points in the same direction as A

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3.4 Components of a Vector and Unit Vectors

Consider a vector A lying in the xy plane and making an arbitrary angle θ with the positive x axis, as shown in Figure. This vector can be expressed as the sum of two other vectors A_x and A_y. A_x and A_y are the VECTOR COMPONENTS of The vector A A_x and A_y are the COMPONENTS of The vector A

$A_{x} = A \cos \theta$	(3.8)
$A_{} = A \sin \theta$	(3.9)

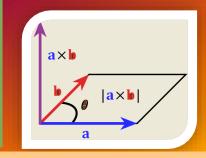
$$\tan \theta = \frac{A_y}{A_y}$$

$$A = \sqrt{A_x^2 + A_y^2}$$

 $\begin{array}{c|c} \mathbf{A} \\ \mathbf{A} \\ \mathbf{\theta} \\ \mathbf{A}_{x} \end{array} \mathbf{A}_{y} \\ \mathbf{A}_{x} \\ \mathbf{A}_{x} \\ \mathbf{A}_{y} \\ \mathbf{A}_{x} \\ \mathbf{A}_{y} \\ \mathbf{A$

(3.10)

(3.11)



3.4 Unit Vectors

A unit vector is a dimensionless vector having a magnitude of exactly 1.

on x: we use: \hat{i}

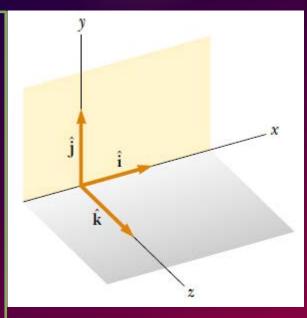
on y: we use: \hat{j}

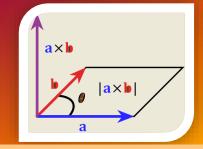
on z: we use: \hat{k}

 $\left|\hat{i}\right| = \left|\hat{j}\right| = \left|\hat{k}\right| = 1$

We express a vector using unit vetors as: $A = A_x \hat{i} + A_y \hat{j}$

Vector addition is easier with unit vectors: $R = A + B = R_x \hat{i} + R_y \hat{j}$ $\therefore R = (A_x \hat{i} + A_y \hat{j}) + (B_x \hat{i} + B_y \hat{j})$ $\Rightarrow R = (A_x + B_x)\hat{i} + (A_y + B_y)\hat{j}$ $\therefore R_x = A_x + B_x \qquad R_y = A_y + B_y$





3.4 Unit Vectors

To find magnitude of the Resultant vector R and the angle it makes with +tive x-axis; we just do same as we did before:

$$R = \sqrt{R_x^2 + R_y^2} = \sqrt{(A_x + B_x)^2 + (A_y + B_y)^2}$$
(3.16)
$$\tan \theta = \frac{R_y}{R_x} = \frac{A_x + B_x}{A_y + B_y}$$
(3.17)

in 3D:

$$A = A_x \hat{i} + A_y \hat{j} + A_z \hat{k}$$
(3.18)

$$B = B_{x}\hat{i} + B_{y}\hat{j} + B_{z}\hat{k}$$
(3.19)

The sum of A and B is:

$$R = (A_x + B_x)\hat{i} + (A_y + B_y)\hat{j} + (A_z + B_z)\hat{k}$$
(3.20)

magnetude of the R:

$$R = \sqrt{R_x^2 + R_y^2 + R_z^2} = \sqrt{(A_x + B_x)^2 + (A_y + B_y)^2 + (A_z + B_z)^2}$$

Example 3.3 The Sum of Two Vectors

To Find the sum of two vectors A and B lying in the xy plane and given by:

 $A = (2.0\hat{i} + 2.0\hat{j})m$ and $B = (2.0\hat{i} - 4.0\hat{j})m$ Solution:

$$\therefore R = A + B = (2.0\hat{i} + 2.0\hat{j}) + (2.0\hat{i} - 4.0\hat{j}) = (4.0\hat{i} - 2.0\hat{j}) \text{ m}$$

$$\rightarrow |\mathbf{R}| = \sqrt{R_x^2 + R_y^2} = \sqrt{(4)^2 + (-2)^2} = 4.5 \text{ m}$$

$$\theta = \tan^{-1} \frac{-2}{4} = \tan^{-1} (-0.5) = -27^{\circ}$$

But because R is in the 4^{th.} quadrant; this angle is not the actual angle based on our convention. We need to add 360° to this angle:

 $\therefore \theta = -27^{\circ} + 360^{\circ} = 333^{\circ}$

Example 3.3 The Resultant Displacement

A particle undergoes three consecutive displacements:

$$d_1 = (15\hat{i} + 30\hat{j} + 12\hat{k}) \text{ cm}, d_2 = (23\hat{i} - 14\hat{j} - 5\hat{k}) \text{ cm}$$

and $d_2 = (-13\hat{i} + 15\hat{j}) \text{ cm}$

Find the components of the resultant displacement and its magnitude. Solution:

$$\therefore R = d_1 + d_2 + d_3$$

$$\therefore R = (15\hat{i} + 30\hat{j} + 12\hat{k}) + (23\hat{i} - 14\hat{j} - 5\hat{k}) + (-13\hat{i} + 15\hat{j})$$

$$\Rightarrow R = (25\hat{i} + 31\hat{j} + 7\hat{k}) \text{ cm}$$

$$|\mathbf{R}| = \sqrt{R_x^2 + R_y^2 + R_z^2} = \sqrt{(25)^2 + (31)^2 + (7)^2} = 40cm$$

Example 3.5 Taking a hike (a)

A hiker begins a trip by first walking 25.0 km southeast from her car. She stops and sets up her tent for the night. On the second day, she walks 40.0 km in a direction 60.0° north of east, at which point she discovers a forest ranger's tower.
 (a) Determine the components of the hiker's displacement for each day.

Components of her first day:

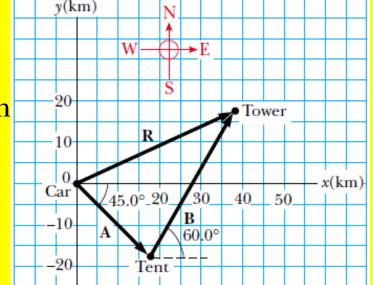
$$A_x = A \cos(-45^\circ) = 25 \cos(-45^\circ) = 17.7 \text{ km}$$

$$A_y = A \sin(-45^\circ) = 25 \sin(-45^\circ) = -17.7 \text{ km}$$

Components of her 2nd day:

$$B_x = B \cos(60^\circ) = 25 \cos(60^\circ) = 20 \text{ km}$$

$$B_{y} = B \sin(60^{\circ}) = 25 \sin(60^{\circ}) = 34.6 \text{ km}$$



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Please note that: $cos(315^{\circ}) = cos(-45^{\circ})$ *and sin(315^{\circ}) = sin(-45^{\circ})* 315° is the angle between +x and the vector A (counterclockwise)

Example 3.5 Taking a hike (b)

 (b) Determine the components of the hiker's resultant displacement R for the trip. Find an expression for R in terms of unit vectors.

Solution:

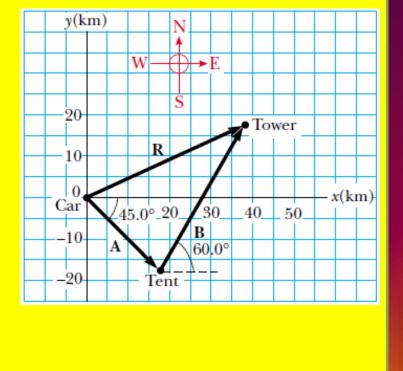
- \therefore R=A+B
- $\therefore R_x = A_x + B_x = 17.7 + 20 = 37.7 \, km$
 - $R_y = A_y + B_y = -17.7 + 34.6 = 16.9 \, km$

using unit vector notation:

$$R = (37.7\hat{i} + 16.9\hat{j}) km$$

$$\therefore |R| = \sqrt{(37.7)^2 + (169)^2} = 41.3 km$$

$$\theta = \tan^{-1} \frac{16.9}{37.7} = 24.1^{\circ}$$



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Lecture Summary

- Scalar quantities: are those that have only a numerical value and no associated direction.
- Vector quantities: have both magnitude and direction and obey the laws of vector addition.
- *The magnitude of a vector* is always a positive number.
- When two or more vectors are added together, all of them must have the same units and all of them must be the same type of quantity.
- We can add two vectors A and B graphically. In this method, the resultant vector R = A + B runs from the tail of A to the tip of B.
- A 2nd method involves components of the vectors. \mathbf{A}_x of the vector \mathbf{A} is equal to the projection of \mathbf{A} along the x axis of a coordinate system, where $\mathbf{A}_x = \mathbf{A} \cos \theta$. \mathbf{A}_y of \mathbf{A} is the projection of \mathbf{A} along the y axis, where $\mathbf{A}_y = \mathbf{A} \sin \theta$

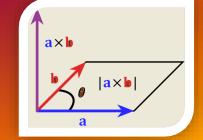
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a×b

|a×lı

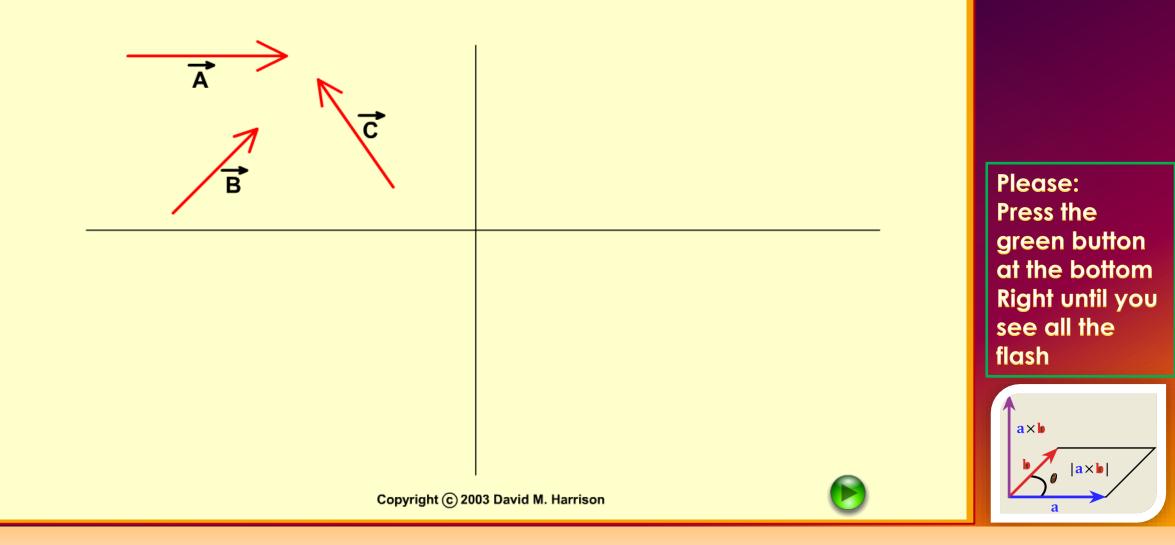
Lecture Summary (continued)

- Be sure you can determine which trigonometric functions you should use in all situations, especially when θ is defined as something other than the counterclockwise angle from the positive x axis.
- ► If a vector **A** has an x component \mathbf{A}_x and a y component \mathbf{A}_y , the vector can be expressed in unit–vector form as $A = A_x \hat{i} + A_y \hat{j}$
- We can find the resultant of two or more vectors by resolving all vectors into their x and y components, adding their resultant x and y components, and then using the Pythagorean theorem to find the magnitude of the resultant vector. We can find the angle that the resultant vector makes with respect to the x axis by using a suitable trigonometric function.



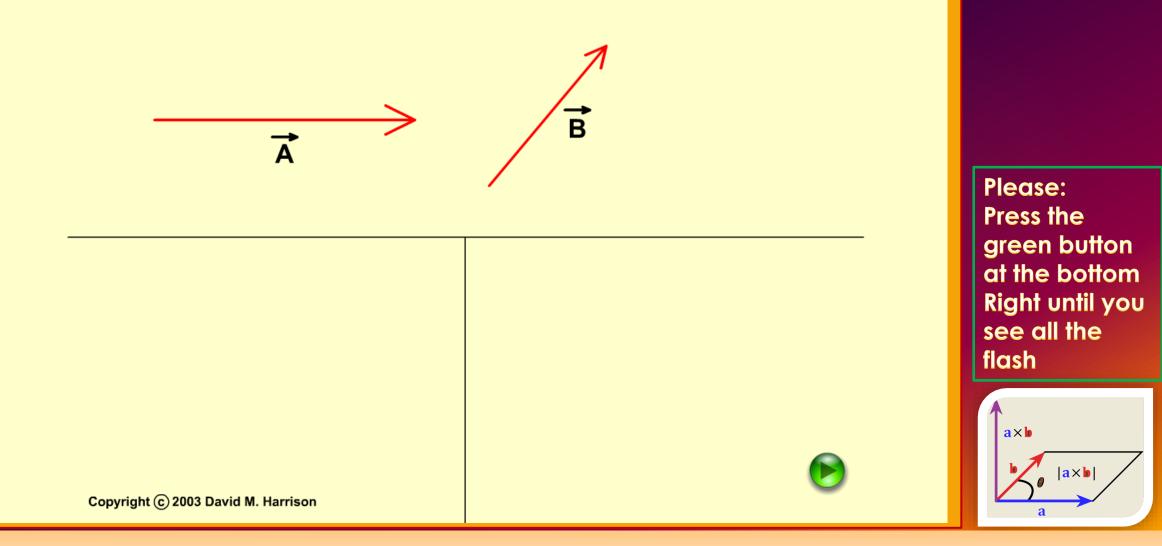
Adding 3 Vectors (Activity)

Adding 3 Vectors



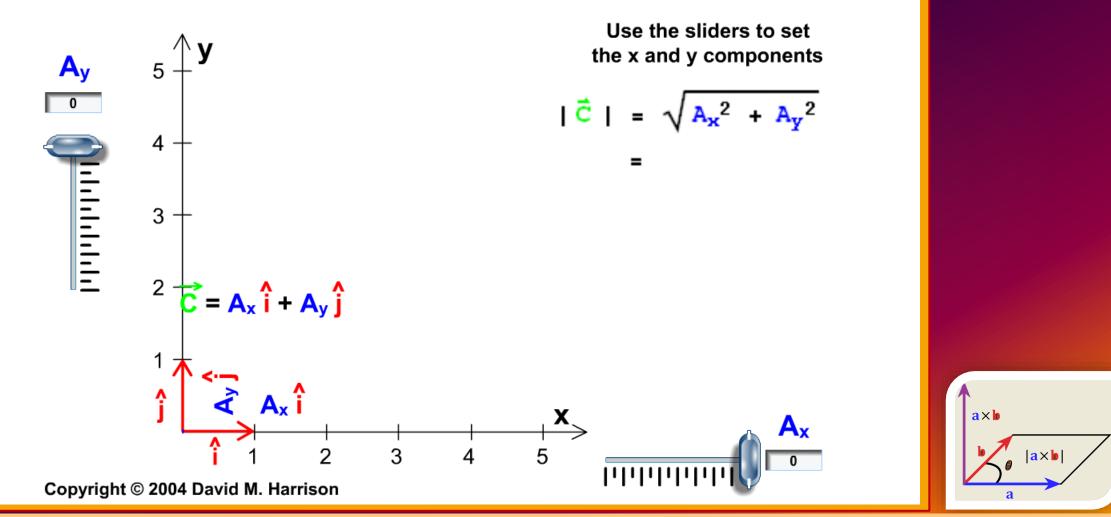
Vector Subtraction(Activity)

Subtracting 2 Vectors



Unit Vectors (Activity)

Unit Vectors





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