

Chapter 5: Bayesian Estimation

In the last two Chapters 3 and 4, we assumed the random sample came from some known probability distribution $f(x, \theta)$ and we used the classic method to estimate the unknown parameter θ which was some fixed. In this Chapter, we will estimate θ using the Bayesian method which is define the unknown parameter θ as a random variable and has a distribution depending on previous informations called prior distribution.

Prior and Posterior Distributions

Consider a random variable X that has a distribution of probability that depends upon the symbol θ , where θ is an element of a well-defined set Ω . Let us now introduce a random variable Θ that has a distribution of probability over the set Ω . The probability distribution $h(\theta)$ is called the **prior distribution** of Θ . Moreover, we now denote the probability distribution of X by $f(x|\theta)$ since we think of it as a conditional distribution of X , given $\Theta = \theta$. For clarity in this chapter, we will use the following summary of this model:

$$X|\theta \sim f(x|\theta)$$

$$\Theta \sim h(\theta)$$

Thus, we can write the joint conditional distribution of X , given $\Theta = \theta$, as

$$L(x|\theta) = f(x_1|\theta)f(x_2|\theta) \dots f(x_n|\theta)$$

Thus, the joint distribution of X and Θ is

$$g(x, \theta) = L(x|\theta)h(\theta) \quad (5.1)$$

The marginal distribution of X is given by

$$g_1(x) = \begin{cases} \int_{\theta} g(x, \theta) d\theta, & \text{if } \Theta \text{ is a continuous} \\ \sum_{\theta} g(x, \theta), & \text{if } \Theta \text{ is a discrete} \end{cases}$$

In either case the conditional distribution of Θ , given the sample X , is

$$k(\theta|x) = \frac{g(x, \theta)}{g_1(x)} = \frac{L(x|\theta)h(\theta)}{g_1(x)} \quad (5.2)$$

The distribution defined by this conditional distribution is called the **posterior distribution**. The prior distribution reflects the subjective belief of Θ before the

sample is drawn while the posterior distribution is the conditional distribution of Θ after the sample is drawn. Further discussion on these distributions follows an illustrative example.

Example 5.1:

Consider the model

$$X_i|\theta \sim \text{iid Poisson}(\theta)$$

$$\Theta \sim \Gamma(\alpha, \beta), \alpha \text{ and } \beta \text{ are known}$$

Hence, the random sample is drawn from a Poisson distribution with mean θ and the prior distribution is $\Gamma(\alpha, \beta)$ distribution. Thus, in this case, the joint conditional pdf of X , given $\Theta = \theta$, is

$$L(x|\theta) = \frac{\theta^{x_1} e^{-\theta}}{x_1!} \cdots \frac{\theta^{x_n} e^{-\theta}}{x_n!}, x_i = 0, 1, 2, \dots, i = 1, 2, \dots, n,$$

and the prior pdf is

$$h(\theta) = \frac{\theta^{\alpha-1} e^{-\frac{\theta}{\beta}}}{\Gamma(\alpha) \beta^\alpha}, 0 < \theta < \infty$$

Hence, the joint mixed continuous discrete pdf is given by

$$\begin{aligned} g(x, \theta) &= L(x|\theta)h(\theta) = \left[\frac{\theta^{x_1} e^{-\theta}}{x_1!} \cdots \frac{\theta^{x_n} e^{-\theta}}{x_n!} \right] \left[\frac{\theta^{\alpha-1} e^{-\frac{\theta}{\beta}}}{\Gamma(\alpha) \beta^\alpha} \right] \\ &= \frac{\theta^{\sum_{i=1}^n x_i + \alpha - 1} e^{-\left(\frac{n\beta+1}{\beta}\right)\theta}}{\prod_{i=1}^n x_i! \Gamma(\alpha) \beta^\alpha} \end{aligned}$$

Provided that $x_i = 0, 1, 2, 3, \dots, i = 1, 2, \dots, n$ and $0 < \theta < \infty$. Then, the marginal distribution of the sample, is

$$g_1(x) = \int_0^\infty \frac{\theta^{\sum_{i=1}^n x_i + \alpha - 1} e^{-\left(\frac{n\beta+1}{\beta}\right)\theta}}{\prod_{i=1}^n x_i! \Gamma(\alpha) \beta^\alpha} d\theta = \frac{\Gamma(\sum_{i=1}^n x_i + \alpha)}{\prod_{i=1}^n x_i! \Gamma(\alpha) \beta^\alpha \left(\frac{n\beta+1}{\beta}\right)^{\sum_{i=1}^n x_i + \alpha}}$$

Finally, the posterior pdf of Θ , given $X = x$, is

$$k(\theta|x) = \frac{g(x, \theta)}{g_1(x)} = \frac{\theta^{\sum_{i=1}^n x_i + \alpha - 1} e^{-\left(\frac{\theta}{n\beta + 1}\right)}}{\Gamma\left(\sum_{i=1}^n x_i + \alpha\right) \left(\frac{\beta}{n\beta + 1}\right)^{\sum_{i=1}^n x_i + \alpha}}$$

Provided that $0 < \theta < \infty$. This conditional pdf is one of the gamma type with parameters $\alpha^* = \sum_{i=1}^n x_i + \alpha$ and $\beta^* = \frac{\beta}{n\beta + 1}$. Notice that the posterior pdf reflects both prior information (α, β) and sample information $(\sum_{i=1}^n x_i)$.

$$\theta|X_i \sim \Gamma\left(\sum_{i=1}^n x_i + \alpha, \frac{\beta}{n\beta + 1}\right)$$

Remarks:

1. In Example 5.1 notice that it is not really necessary to determine the marginal pdf $g_1(x)$ to find the posterior pdf $k(\theta|x)$. If we divide $L(x|\theta)h(\theta)$ by $g_1(x)$, we must get the product of a factor, which depend upon x but does not depend upon θ , say $c(x)$, That is,

$$k(\theta|x) = c(x) \theta^{\sum_{i=1}^n x_i + \alpha - 1} e^{-\left(\frac{\theta}{n\beta + 1}\right)}$$

Provided that $0 < \theta < \infty$, and $x_i = 0, 1, 2, 3, \dots, i = 1, 2, \dots, n$. However, $c(x)$ must be that “constant” needed to make $k(\theta|x)$ a pdf, namely

$$c(x) = \frac{1}{\Gamma\left(\sum_{i=1}^n x_i + \alpha\right) \left(\frac{\beta}{n\beta + 1}\right)^{\sum_{i=1}^n x_i + \alpha}}$$

Accordingly, we frequently write that $k(\theta|x)$ is proportional to $L(x|\theta)h(\theta)$; that is, the posterior pdf can be written as

$$k(\theta|x) \propto L(x|\theta)h(\theta) \quad (5.3)$$

Note that in the right-hand member of this expression all factors involving constants and x alone (not θ) can be dropped. For illustration, in solving the problem presented in Example 5.1, we simply write

$$k(\theta|x) \propto \theta^{\sum_{i=1}^n x_i + \alpha - 1} e^{-\left(\frac{\theta}{n\beta + 1}\right)}$$

$0 < \theta < \infty$. Clearly, $k(\theta|x)$ must be gamma pdf with parameter $\alpha^* = \sum_{i=1}^n x_i + \alpha$ and $\beta^* = \frac{\beta}{n\beta + 1}$.

2. There is another observation that can be made at this point. Suppose that there exists a sufficient statistic $T = t(X)$ for the parameter so that

$$L(x|\theta) = f_T(t|\theta) \cdot k(X),$$

where now $f_T(t|\theta)$ is the pdf of T , given $\Theta = \theta$. Then we note that

$$k(\theta|x) \propto f_T(t|\theta) h(\theta) \quad (5.4)$$

5.1 Bayesian Point Estimation

Suppose we want a point estimator of θ . From the Bayesian viewpoint, this really amounts to selecting a decision function δ , so that $\delta(x)$ is a predicted value of θ (an experimental value of the random variable Θ) when both the computed value x and the conditional pdf $k(\theta|x)$ are known. Now, in general, how would we predict an experimental value of any random variable, say W , if we want our prediction to be “reasonably close” to the value to be observed?. Many statisticians would predict the mean, $E(W)$, of the distribution of W ; others would predict a median (perhaps unique) of the distribution of W , and some would have other predictions. However, it seems desirable that the choice of the decision function should depend upon a loss function $\mathcal{L}[\theta, \delta(x)]$. One way in which this dependence upon the loss function can be reflected is to select the decision function δ in such a way that the conditional expectation of the loss is minimum. A **Bayes’ estimate** is a decision function δ that minimizes the expectation of the loss function $E\{\mathcal{L}[\Theta, \delta(x)]|X = x\}$ and then

$$\begin{aligned} \delta(x) &= E\{\mathcal{L}[\Theta, \delta(x)]|X = x\} \\ &= \begin{cases} \int_{\theta} \mathcal{L}[\theta, \delta(x)]k(\theta|x) d\theta, & \text{if } \Theta \text{ is a continuous} \\ \sum_{\theta} \mathcal{L}[\theta, \delta(x)]k(\theta|x), & \text{if } \Theta \text{ is a discrete} \end{cases} \end{aligned} \quad (5.5)$$

is called **Bayes’ estimator** of θ .

Some Possible Loss Functions:

1. Squared Error Loss Function:

The squared error loss function is given by

$$\mathcal{L}[\theta, \delta(x)] = [\theta - \delta(x)]^2$$

Then, the Bayes’ estimate is the mean of the conditional distribution of Θ , given $X = x$

$$\delta(x) = E(\Theta|x)$$

2. Absolute Error Loss Function:

The absolute error loss function is given by

$$\mathcal{L}[\theta, \delta(x)] = |\theta - \delta(x)|$$

Then, a median of the conditional distribution of Θ , given $X = x$, is the Bayes' solution

$$\delta(x) = \text{Median of } \Theta$$

where the median, m , is the solution of

$$\int_{-\infty}^m k(\theta|x) d\theta = \frac{1}{2}$$

It is easy to generalize this to estimate a function of θ , for a specified function $\tau(\theta)$. For the loss function $\mathcal{L}[\theta, \delta(x)]$, a **Bayes estimate** of $\tau(\theta)$ is a decision function δ that minimizes

$$E\{\mathcal{L}[\tau(\Theta), \delta(x)] | X = x\} = \int_{-\infty}^{\infty} \mathcal{L}[\tau(\theta), \delta(x)] k(\theta|x) d\theta \quad (5.6)$$

The random variable $\delta(X)$ is called **Bayes' estimator** of $\tau(\theta)$.

Example 5.2:

Consider the model

$$X_i | \theta \sim \text{iid Binomial}(1, \theta)$$

$$\Theta \sim \text{Beta}(\alpha, \beta), \alpha \text{ and } \beta \text{ are known}$$

That is, the prior pdf is

$$h(\theta) = \frac{\Gamma(\alpha + \beta)}{\Gamma(\alpha)\Gamma(\beta)} \theta^{\alpha-1} (1 - \theta)^{\beta-1}, 0 < \theta < 1$$

when α and β are assigned positive constants. We seek a decision function δ that is a Bayes' solution. The sufficient statistic is $Y = \sum_{i=1}^n X_i$, which has a *Binomial* (n, θ) distribution. Thus, the conditional pdf of Y given $\Theta = \theta$ is

$$g(y|\theta) = \binom{n}{y} \theta^y (1 - \theta)^{n-y} \quad y = 0, 1, \dots, n$$

Thus by Equation (5.4), the conditional posterior pdf of Θ , given $Y = y$ at positive probability density, is

$$k(\theta|y) \propto \theta^y (1 - \theta)^{n-y} \theta^{\alpha-1} (1 - \theta)^{\beta-1}, 0 < \theta < 1$$

That is

$$k(\theta|y) = \frac{\Gamma(\alpha + \beta + n)}{\Gamma(\alpha + y)\Gamma(\beta + n - y)} \theta^{\alpha+y-1} (1 - \theta)^{\beta+n-y-1}, 0 < \theta < 1$$

and $y = 0, 1, \dots, n$. Hence, the posterior pdf is a beta density function with parameters $(\alpha + y, \beta + n - y)$. We take squared error loss, i.e., $\mathcal{L}[\theta, \delta(y)] = [\theta - \delta(y)]^2$, as the loss function. Then, the Bayesian point estimate of θ is the mean of this beta pdf which is

$$\delta(y) = \frac{\alpha + y}{\alpha + \beta + n}$$

5.2 Bayesian Interval Estimation

For fixed α , we can find two functions $u(x)$ and $v(x)$ so that the conditional probability

$$P(u(x) < \Theta < v(x) | X = x) = \int_{u(x)}^{v(x)} k(\theta|x) d\theta = 1 - \alpha$$

which is defined to be $100(1 - \alpha)\%$ Bayesian interval estimates of θ . This interval is often called **credible interval**, so as not to confuse them with confidence interval.

Example 5.3:

Recall Example 5.1 where X_1, X_2, \dots, X_n is a random sample from a Poisson distribution with mean θ and a $\Gamma(\alpha, \beta)$ prior, with α and β known, is considered. As given, the posterior pdf is a $\Gamma\left(y + \alpha, \frac{\beta}{n\beta + 1}\right)$ pdf, where $y = \sum_{i=1}^n x_i$, i.e.

$$\theta|X_i \sim \Gamma\left(y + \alpha, \frac{\beta}{n\beta + 1}\right)$$

Find:

- Bayes' point estimator of Θ using the squared error loss function.
- Bayes' point estimator of Θ using the absolute error loss function.
- $(1 - \xi)100\%$ credible interval for Θ .
- a and c when, $\alpha = 2, \beta = 4, n = 12, y = 8, \xi = 0.05$.

Solution:

- a) If we use the squared error loss function, the Bayes' point estimate of Θ is the mean of the posterior

$$\delta(y) = \frac{\beta(y + \alpha)}{n\beta + 1}$$

- b) If we use the absolute error loss function, the Bayes' point estimate of Θ is the median of the posterior or it is the solution, m , of the following equation:

$$\int_0^m \frac{(n\beta + 1)^{y+\alpha} \theta^{y+\alpha-1} e^{-\frac{(n\beta+1)\theta}{\beta}}}{\Gamma(y + \alpha)\beta^{y+\alpha}} d\theta = \frac{1}{2}$$

- c) To obtain a credible interval, from that the posterior distribution of Θ we get that

$$\frac{2(n\beta + 1)}{\beta} \Theta \sim \Gamma(y + \alpha, 2) \Leftrightarrow \frac{2(n\beta + 1)}{\beta} \Theta \sim \chi^2_{2(y+\alpha)}$$

Based on this, the following interval is a $(1 - \xi)100\%$ credible interval for Θ

$$P\left(\chi^2_{(1-\frac{\xi}{2}, 2(y+\alpha))} < \frac{2(n\beta+1)}{\beta} \Theta < \chi^2_{(\frac{\xi}{2}, 2(y+\alpha))}\right) = 1 - \alpha$$

or
$$\Theta \in \left(\frac{\beta}{2(n\beta+1)} \chi^2_{(1-\frac{\xi}{2}, 2(y+\alpha))}, \frac{\beta}{2(n\beta+1)} \chi^2_{(\frac{\xi}{2}, 2(y+\alpha))}\right)$$

where $\chi^2_{(1-\frac{\xi}{2}, 2(y+\alpha))}$ and $\chi^2_{(\frac{\xi}{2}, 2(y+\alpha))}$ are the lower and upper χ^2 quantiles for a χ^2 distribution with $2(y + \alpha)$ degrees of freedom.

- d) If $\alpha = 2, \beta = 4, n = 12, y = 8, \xi = 0.05$, then the point estimator is

$$\delta(y) = \frac{4(8 + 2)}{48 + 1} = 0.8163$$

and the 95% credible interval for Θ is

$$\Theta \in \left(\frac{4}{2(48 + 1)} \chi^2_{(0.975, 20)}, \frac{4}{2(48 + 1)} \chi^2_{(0.025, 20)}\right)$$

From χ^2 distribution Table: $\chi^2_{(0.025, 20)} = 34.17$, $\chi^2_{(0.975, 20)} = 9.59$, thus

$$\Theta \in (0.3914, 1.3947)$$