

Solution to the first mid-term
exam — Math 244
Semester 452

Q1 a) We have $A^2 = \begin{pmatrix} 9 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 9 \end{pmatrix} = 9I$

Therefore $(\frac{1}{9}A)A = I$. But A^{-1} is the only matrix satisfying $A^{-1}A = I$. We deduce that $A^{-1} = \frac{1}{9}A = \frac{1}{9} \begin{pmatrix} 1 & 2 & 2 \\ 2 & -2 & 1 \\ 2 & 1 & -2 \end{pmatrix}$

Q1 b) We use row elimination method to find at the same time A^{-1} and $\det A$. We have

$$\left[\begin{array}{cccc|cccc} 1 & 1 & -1 & -2 & 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & -2 & 0 & 1 & 0 & 0 \\ -1 & 0 & 1 & 1 & 0 & 0 & 1 & 0 \\ -2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right] \begin{array}{l} R_1 + 2R_4 \\ R_2 + 2R_4 \\ R_3 - R_4 \end{array} \sim \left[\begin{array}{cccc|cccc} -3 & 1 & -1 & 0 & 1 & 0 & 0 & 2 \\ -3 & 1 & 0 & 0 & 0 & 1 & 0 & 2 \\ 1 & 0 & 1 & 0 & 0 & 0 & 1 & -1 \\ -2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$R_1 + R_3 \sim \left[\begin{array}{cccc|cccc} -2 & 1 & 0 & 0 & 1 & 0 & 1 & 1 \\ -3 & 1 & 0 & 0 & 0 & 1 & 0 & 2 \\ 1 & 0 & 1 & 0 & 0 & 0 & 1 & -1 \\ -2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right] \begin{array}{l} R_1 - R_2 \\ \end{array} \sim \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 1 & -1 & 1 & -1 \\ -3 & 1 & 0 & 0 & 0 & 1 & 0 & 2 \\ 1 & 0 & 1 & 0 & 0 & 0 & 1 & -1 \\ -2 & 0 & 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right]$$

$$\begin{array}{l} R_2 + 3R_1 \\ R_3 - R_1 \\ R_4 + 2R_1 \end{array} \sim \left[\begin{array}{cccc|cccc} 1 & 0 & 0 & 0 & 1 & -1 & 1 & -1 \\ 0 & 1 & 0 & 0 & 3 & -2 & 3 & -1 \\ 0 & 0 & 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 2 & -2 & 2 & -1 \end{array} \right] = [I | A^{-1}]$$

Hence $A^{-1} = \begin{bmatrix} 1 & -1 & 1 & -1 \\ 3 & -2 & 3 & -1 \\ -1 & 1 & 0 & 0 \\ 2 & -2 & 2 & -1 \end{bmatrix}$. Moreover, because none of the performed row operations modify the determinant, we

have $\det A = \det I = 1$.

But $A^{-1} = \frac{1}{\det A} \text{Adj} A = \text{Adj} A$, we obtain

$$\text{Adj} A = \begin{bmatrix} 1 & -1 & 1 & -1 \\ 3 & -2 & 3 & -1 \\ -1 & 1 & 0 & 0 \\ 2 & -2 & 2 & -1 \end{bmatrix}.$$

Q1c) We have $A \text{Adj} A = \det A I = 2I$.

Because the size of the matrices here is 3×3 we have

$$\begin{aligned} 8 &= \det(2I) = \det(A \text{Adj} A) = \det A \det(\text{Adj} A) \\ &= 2 \det(\text{Adj} A). \end{aligned}$$

We deduce that $\det(\text{Adj} A) = 4$.

Q2a) The relation $AM = MA$ can be written

$$\begin{pmatrix} 2x+z & 2y+t \\ x-z & y-t \end{pmatrix} = \begin{pmatrix} 2x+y & x-y \\ 2z+t & z-t \end{pmatrix} \text{ which is equivalent}$$

$$\text{to } \begin{cases} z = y \\ x - 3y - t = 0 \\ x - 3z - t = 0 \\ y = z \end{cases} \Leftrightarrow \begin{cases} z = y \\ x = 3y + t \end{cases}$$

This means that y, t can take any values and x, z are deduced from y, t .

This gives $M = \begin{pmatrix} 3y+t & y \\ y & t \end{pmatrix} = y \begin{pmatrix} 3 & 1 \\ 1 & 0 \end{pmatrix} + t \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$
for all $y, t \in \mathbb{R}$.

Q2b) Asking that $(x, y, z) = (1, -2, 3)$ is a solution of the system is equivalent to solving the system

$$\begin{cases} a - 4b + 3c = 6 \\ a - 12b + 3c = -8 \\ 3a - 8b + 3c = -8 \end{cases} \text{ where } a, b, c \text{ becomes the unknowns.}$$

This system is equivalent to: $(E_{q_2} \leftarrow E_{q_2} - E_{q_1}; E_{q_3} \leftarrow E_{q_3} - E_{q_1})$

$$\begin{cases} a - 4b + 3c = 6 \\ -8b = -8 \\ 2a - 4b = -14 \end{cases} \begin{array}{l} \text{Therefore, } b = 1. \\ \text{By substitution in } E_{q_3}: 2a - 4 = -14 \\ \Rightarrow a = -5 \\ \text{By substitution in } E_{q_1}: \dots \\ -5 - 4 + 3c = 6 \\ \Rightarrow c = 5. \end{array}$$

Hence the only values of (a, b, c) so that $(1, -2, 3)$ is a solution of the system are $(-5, 1, 5)$.

Q3a) We use Gauss-Jordan elimination method:

$$\left[\begin{array}{cccc|c} 2 & -1 & -4 & 3 & 1 \\ 3 & -2 & -5 & 4 & 1 \\ 3 & -3 & -2 & 0 & 1 \end{array} \right] \begin{array}{l} R_2 - R_1 \\ R_3 - R_1 \end{array} \sim \left[\begin{array}{cccc|c} 2 & -1 & -4 & 3 & 1 \\ 1 & -1 & -1 & 1 & 0 \\ 1 & -2 & 2 & -3 & 0 \end{array} \right] \begin{array}{l} R_1 \leftrightarrow R_2 \\ \sim R_2 \end{array}$$

$$\begin{array}{l} R_2 - 2R_1 \\ R_3 - R_1 \end{array} \sim \left[\begin{array}{cccc|c} 1 & -1 & -1 & 1 & 0 \\ 0 & 1 & -2 & 1 & 1 \\ 0 & -1 & 3 & -4 & 0 \end{array} \right] \begin{array}{l} R_3 + R_2 \end{array} \sim \left[\begin{array}{cccc|c} 1 & -1 & -1 & 1 & 0 \\ 0 & 1 & -2 & 1 & 1 \\ 0 & 0 & 1 & -3 & 1 \end{array} \right] \begin{array}{l} R_1 + R_3 \\ R_2 + 2R_3 \end{array} \sim$$

$$\sim \left[\begin{array}{cccc|c} 1 & -1 & 0 & -2 & 1 \\ 0 & 1 & 0 & -5 & 3 \\ 0 & 0 & 1 & -3 & 1 \end{array} \right] \begin{array}{l} R_1 + R_2 \end{array} \sim \left[\begin{array}{cccc|c} 1 & 0 & 0 & -7 & 4 \\ 0 & 1 & 0 & -5 & 3 \\ 0 & 0 & 1 & -3 & 1 \end{array} \right] \begin{array}{l} \text{This matrix} \\ \text{is in a reduced} \\ \text{row echelon} \\ \text{form.} \end{array}$$

We introduce a parameter $z = t$. The system becomes:

$$\left[\begin{array}{cccc|c} 1 & 0 & 0 & -7 & 4 \\ 0 & 1 & 0 & -5 & 3 \\ 0 & 0 & 1 & -3 & 1 \end{array} \right] \begin{array}{l} R_1 + 7R_4 \\ R_2 + 5R_4 \\ R_3 + 3R_4 \end{array} \sim \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 4+7t \\ 0 & 1 & 0 & 0 & 3+5t \\ 0 & 0 & 1 & 0 & 1+3t \\ 0 & 0 & 0 & 1 & t \end{array} \right]$$

Therefore, the system has infinitely many solutions
 $(4+7t, 3+5t, 1+3t, t)$; $t \in \mathbb{R}$.

Q3b) we have

$$[A|0] = \left[\begin{array}{cccc|c} 0 & 2 & 2 & 4 & 0 \\ 1 & 0 & -1 & -3 & 0 \\ 2 & 3 & 1 & 1 & 0 \\ -2 & 1 & 3 & -2 & 0 \end{array} \right] \begin{array}{l} R_1 \leftrightarrow R_2 \\ \sim \\ R_4 + R_3 \end{array} \left[\begin{array}{cccc|c} 1 & 0 & -1 & -3 & 0 \\ 0 & 2 & 2 & 4 & 0 \\ 2 & 3 & 1 & 1 & 0 \\ 0 & 4 & 4 & -1 & 0 \end{array} \right] \begin{array}{l} \frac{1}{2}R_2 \\ R_3 - 2R_1 \\ R_4 - 2R_2 \end{array}$$

$$\sim \left[\begin{array}{cccc|c} 1 & 0 & -1 & -3 & 0 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 3 & 3 & 4 & 0 \\ 0 & 0 & 0 & -9 & 0 \end{array} \right] \begin{array}{l} R_3 - 3R_2 \\ -\frac{1}{9}R_4 \end{array} \sim \left[\begin{array}{cccc|c} 1 & 0 & -1 & -3 & 0 \\ 0 & 1 & 1 & 2 & 0 \\ 0 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right] \begin{array}{l} R_1 + 3R_4 \\ R_2 - 2R_4 \\ R_3 + 2R_4 \end{array}$$

$$\sim \left[\begin{array}{cccc|c} 1 & 0 & -1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \end{array} \right] \begin{array}{l} R_3 \leftrightarrow R_4 \\ \sim \end{array} \left[\begin{array}{cccc|c} 1 & 0 & -1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

We introduce a parameter $y = t$. This gives

$$\left[\begin{array}{cccc|c} 1 & 0 & -1 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & t \\ 0 & 0 & 0 & 1 & 0 \end{array} \right] \begin{array}{l} R_1 + R_3 \\ R_2 - R_3 \end{array} \sim \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & t \\ 0 & 1 & 0 & 0 & -t \\ 0 & 0 & 1 & 0 & t \\ 0 & 0 & 0 & 1 & 0 \end{array} \right]$$

Hence, the system has infinitely many solutions $(t, -t, t, 0)$, $t \in \mathbb{R}$.