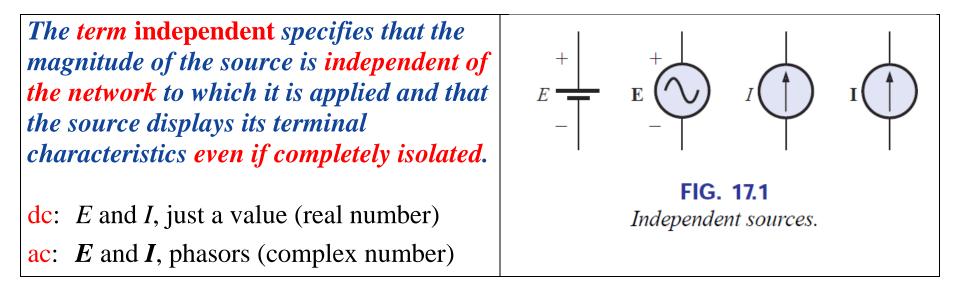
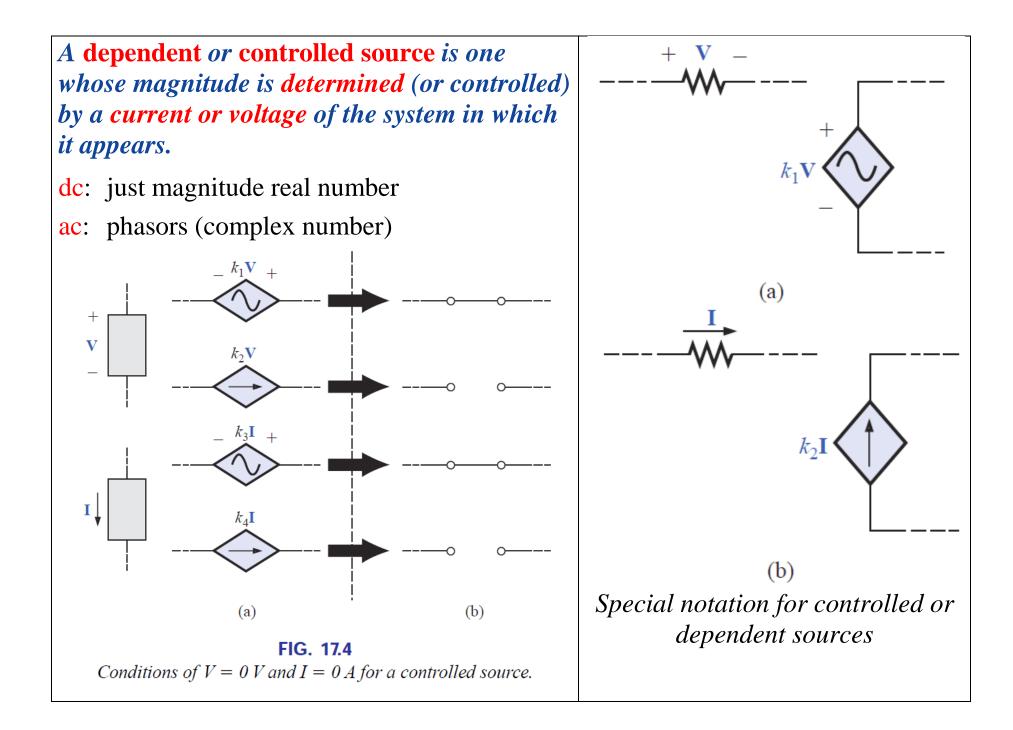
Methods of Analysis and Selected Topics (ac)

17.1 INTRODUCTION

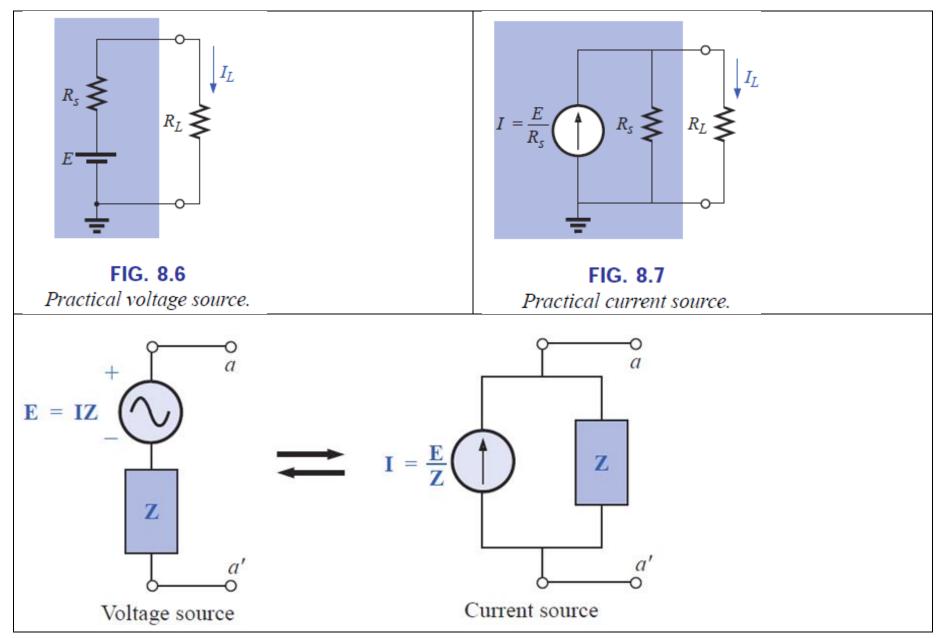
For networks with two or more sources that are not in series or parallel, methods such as *mesh analysis* or *nodal analysis* are employed. Only minor variations are required to the method already described for dc circuit.

17.2 INDEPENDENT VERSUS DEPENDENT SOURCES



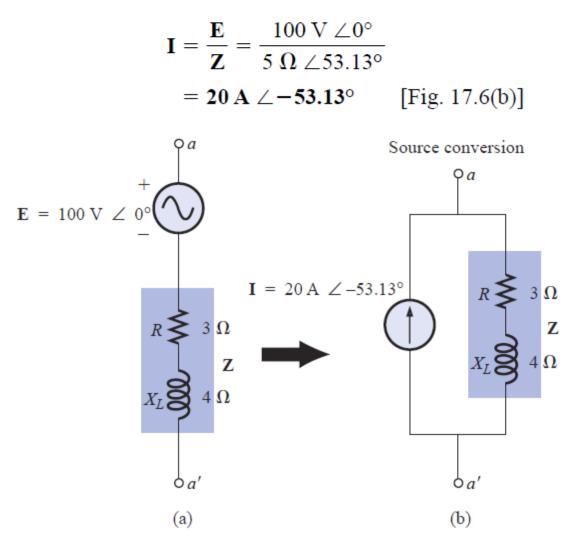


17.3 SOURCE CONVERSIONS

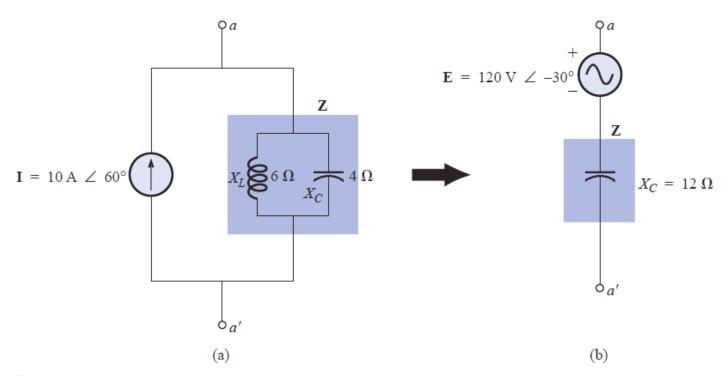


EXAMPLE 17.1 Convert the voltage source of Fig. 17.6(a) to a current source.

Solution:



EXAMPLE 17.2 Convert the current source of Fig. 17.7(a) to a voltage source.



Solution:

$$\mathbf{Z} = \frac{\mathbf{Z}_C \mathbf{Z}_L}{\mathbf{Z}_C + \mathbf{Z}_L} = \frac{(X_C \angle -90^\circ)(X_L \angle 90^\circ)}{-j X_C + j X_L}$$
$$= \frac{(4 \ \Omega \angle -90^\circ)(6 \ \Omega \angle 90^\circ)}{-j 4 \ \Omega + j 6 \ \Omega} = \frac{24 \ \Omega \angle 0^\circ}{2 \angle 90^\circ}$$
$$= \mathbf{12} \ \Omega \angle -90^\circ \qquad \text{[Fig. 17.7(b)]}$$
$$\mathbf{E} = \mathbf{I} \mathbf{Z} = (10 \ \mathrm{A} \angle 60^\circ)(12 \ \Omega \angle -90^\circ)$$
$$= \mathbf{120} \ \mathbf{V} \angle -\mathbf{30}^\circ \qquad \text{[Fig. 17.7(b)]}$$

Dependent Source

- Case 1: Controlling variable is external to the network to be converted, procedure identical to the one used for independent source.
- Case 2: Controlling variable is within the network to be converted, procedure will be seen later.

EXAMPLE 17.3 Convert the voltage source of Fig. 17.8(a) to a current source.

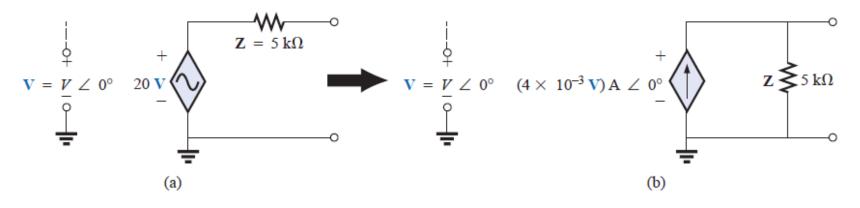


FIG. 17.8 Source conversion with a voltage-controlled voltage source.

Solution:

$$\mathbf{I} = \frac{\mathbf{E}}{\mathbf{Z}} = \frac{(20V) V \angle 0^{\circ}}{5 k\Omega \angle 0^{\circ}}$$
$$= (\mathbf{4} \times \mathbf{10^{-3} V}) \mathbf{A} \angle 0^{\circ} \qquad \text{[Fig. 17.8(b)]}$$

EXAMPLE 17.4 Convert the current source of Fig. 17.9(a) to a voltage source.

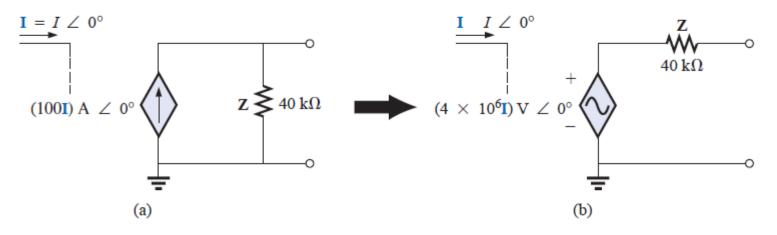


FIG. 17.9 Source conversion with a current-controlled current source.

Solution:

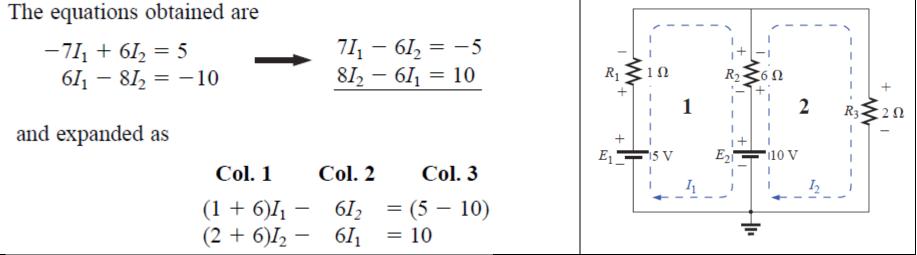
 $\mathbf{E} = \mathbf{I}\mathbf{Z} = [(100\mathbf{I}) \ \mathbf{A} \ \angle 0^{\circ}][40 \ \mathbf{k}\Omega \ \angle 0^{\circ}] \\ = (\mathbf{4} \times \mathbf{10^{6}I}) \ \mathbf{V} \ \angle 0^{\circ} \qquad [Fig. 17.9(b)]$

17.4 MESH ANALYSIS (FORMAT APPROACH)

In the formulation used for dc circuit: we replace

- The resistances by impedances
- The sources value by phasors

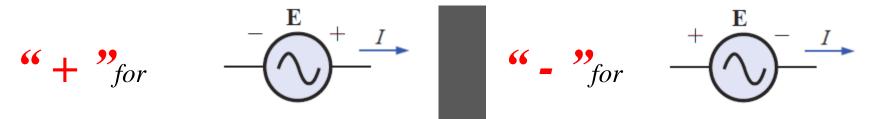
• The equation become complex number equations



- 1. Assign a loop current to each independent, closed loop in a clockwise direction.
- 2. The N^{o} of required equations = N^{o} of independent, closed loops.

Column 1 of each equation is formed by summing the *impedance* values of those *impedances* through which the loop current of interest passes and multiplying the result by that loop current.

- 3. the mutual terms are always subtracted from the first column. A mutual term is simply any impedance element having an additional loop current passing through it. It is possible to have more than one mutual term if the loop current of interest has an element in common with more than one other loop current. Each term is the product of the mutual impedance and the other loop current passing through the same element.
- 4. The column to the right of the *equality sign* is the algebraic sum of the voltage sources in the loop considered.



5. Solve the resulting simultaneous equations for the desired loop currents.

Any current source is first converted to a voltage source (or use the supermesh approach) **EXAMPLE 17.9** Using the format approach to mesh analysis, find the current I_2 in Fig. 17.15.

Solution 1: The network is redrawn in Fig. 17.16:

$$\mathbf{Z}_{1} = R_{1} + j X_{L_{1}} = 1 \ \Omega + j 2 \ \Omega \qquad \mathbf{E}_{1} = 8 \ \nabla \angle 20^{\circ}
\mathbf{Z}_{2} = R_{2} - j X_{C} = 4 \ \Omega - j 8 \ \Omega \qquad \mathbf{E}_{2} = 10 \ \nabla \angle 0^{\circ}
\mathbf{Z}_{3} = +j X_{L_{2}} = +j 6 \ \Omega$$

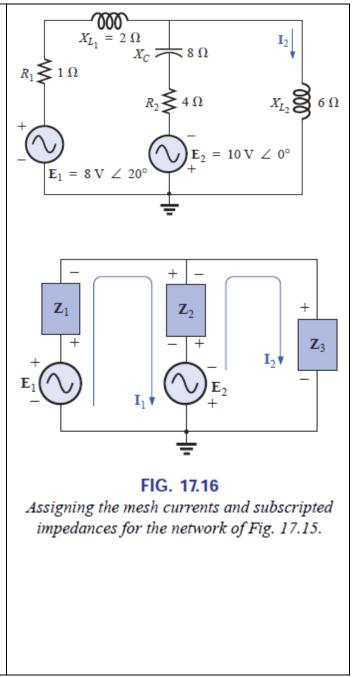
Step 1 is as indicated in Fig. 17.16.

Steps 2 to 4:

which are rewritten as

Step 5: Using determinants, we have

$$\mathbf{I}_{2} = \frac{\begin{vmatrix} \mathbf{Z}_{1} + \mathbf{Z}_{2} & \mathbf{E}_{1} + \mathbf{E}_{2} \\ -\mathbf{Z}_{2} & -\mathbf{E}_{2} \end{vmatrix}}{\begin{vmatrix} \mathbf{Z}_{1} + \mathbf{Z}_{2} & -\mathbf{Z}_{2} \\ -\mathbf{Z}_{2} & \mathbf{Z}_{2} + \mathbf{Z}_{3} \end{vmatrix}}$$
$$= \frac{-(\mathbf{Z}_{1} + \mathbf{Z}_{2})\mathbf{E}_{2} + \mathbf{Z}_{2}(\mathbf{E}_{1} + \mathbf{E}_{2})}{(\mathbf{Z}_{1} + \mathbf{Z}_{2})(\mathbf{Z}_{2} + \mathbf{Z}_{3}) - \mathbf{Z}_{2}^{2}}$$
$$= \frac{\mathbf{Z}_{2}\mathbf{E}_{1} - \mathbf{Z}_{1}\mathbf{E}_{2}}{\mathbf{Z}_{1}\mathbf{Z}_{2} + \mathbf{Z}_{1}\mathbf{Z}_{3} + \mathbf{Z}_{2}\mathbf{Z}_{3}}$$



Substituting numerical values yields

$$\begin{split} \mathbf{I}_2 &= \frac{(4\ \Omega - j\ 8\ \Omega)(8\ V \angle 20^\circ) - (1\ \Omega + j\ 2\ \Omega)(10\ V \angle 0^\circ)}{(1\ \Omega + j\ 2\ \Omega)(4\ \Omega - j\ 8\ \Omega) + (1\ \Omega + j\ 2\ \Omega)(+j\ 6\ \Omega) + (4\ \Omega - j\ 8\ \Omega)(+j\ 6\ \Omega)} \\ &= \frac{(4 - j\ 8)(7.52 + j\ 2.74) - (10 + j\ 20)}{20 + (j\ 6 - 12) + (j\ 24 + 48)} \\ &= \frac{(52.0 - j\ 49.20) - (10 + j\ 20)}{56 + j\ 30} = \frac{42.0 - j\ 69.20}{56 + j\ 30} = \frac{80.95\ A\ \angle -58.74^\circ}{63.53\ \angle 28.18^\circ} \\ &= \mathbf{1.27\ A\ \angle -86.92^\circ} \end{split}$$

EXAMPLE 17.10 Write the mesh equations for the network of Fig. 17.18. Do not solve.

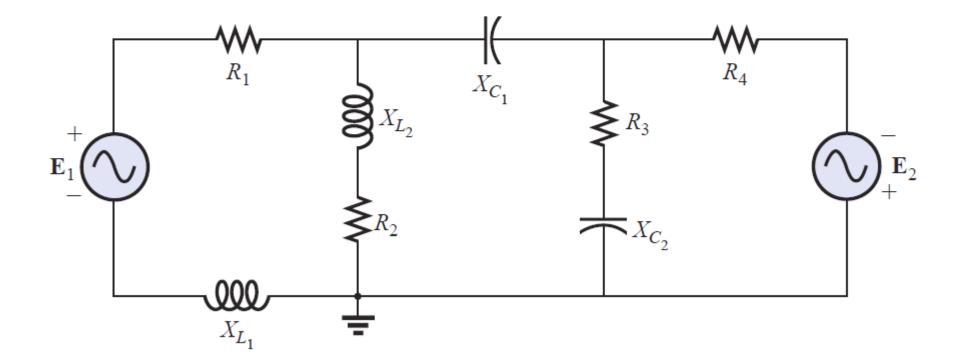


FIG. 17.18 *Example 17.10.*

Solution: The network is redrawn in Fig. 17.19. Again note the reduced complexity and increased clarity provided by the use of subscripted impedances:

$$Z_{1} = R_{1} + j X_{L_{1}} \qquad Z_{4} = R_{3} - j X_{C_{2}}$$

$$Z_{2} = R_{2} + j X_{L_{2}} \qquad Z_{5} = R_{4}$$

$$Z_{3} = X_{C_{1}} \qquad Z_{3} = -j X_{C_{1}}$$

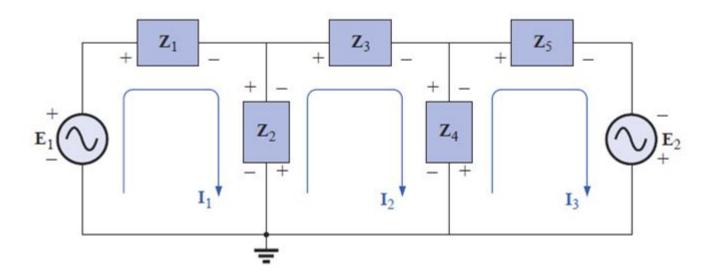
$$I_{1}(Z_{1} + Z_{2}) - I_{2}Z_{2} = E_{1}$$

$$I_{2}(Z_{2} + Z_{3} + Z_{4}) - I_{1}Z_{2} - I_{3}Z_{4} = 0$$

 $\mathbf{I}_3(\mathbf{Z}_4 + \mathbf{Z}_5) - \mathbf{I}_2\mathbf{Z}_4 = \mathbf{E}_2$

and

or
$$\begin{aligned} \mathbf{I}_1(\mathbf{Z}_1 + \mathbf{Z}_2) &- \mathbf{I}_2(\mathbf{Z}_2) &+ 0 &= \mathbf{E}_1 \\ \mathbf{I}_1\mathbf{Z}_2 &- \mathbf{I}_2(\mathbf{Z}_2 + \mathbf{Z}_3 + \mathbf{Z}_4) + \mathbf{I}_3(\mathbf{Z}_4) &= 0 \\ \underline{0 &- \mathbf{I}_2(\mathbf{Z}_4)} &+ \mathbf{I}_3(\mathbf{Z}_4 + \mathbf{Z}_5) = \mathbf{E}_2 \end{aligned}$$



EXAMPLE 17.11 Using the format approach, write the mesh equations for the network of Fig. 17.20.

Solution: The network is redrawn as shown in Fig. 17.21, where

 $\begin{aligned}
 Z_1 &= R_1 + j X_{L_1} & Z_3 = j X_{L_2} \\
 Z_2 &= R_2 & Z_4 = j X_{L_3}
 \end{aligned}$

and

$$I_{1}(Z_{2} + Z_{4}) - I_{2}Z_{2} - I_{3}Z_{4} = E_{1}$$

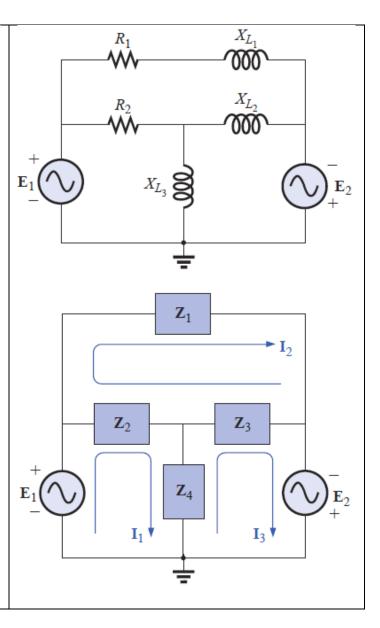
$$I_{2}(Z_{1} + Z_{2} + Z_{3}) - I_{1}Z_{2} - I_{3}Z_{3} = 0$$

$$I_{3}(Z_{3} + Z_{4}) - I_{2}Z_{3} - I_{1}Z_{4} = E_{2}$$

$$I_{1}(Z_{2} + Z_{4}) - I_{2}Z_{2} - I_{3}Z_{4} = 0$$

or $\mathbf{I}_{1}(\mathbf{Z}_{2} + \mathbf{Z}_{4}) - \mathbf{I}_{2}\mathbf{Z}_{2} - \mathbf{I}_{3}\mathbf{Z}_{4} = \mathbf{E}_{1}$ $-\mathbf{I}_{1}\mathbf{Z}_{2} + \mathbf{I}_{2}(\mathbf{Z}_{1} + \mathbf{Z}_{2} + \mathbf{Z}_{3}) - \mathbf{I}_{3}\mathbf{Z}_{3} = 0$ $-\mathbf{I}_{1}\mathbf{Z}_{4} - \mathbf{I}_{2}\mathbf{Z}_{3} + \mathbf{I}_{3}(\mathbf{Z}_{3} + \mathbf{Z}_{4}) = \mathbf{E}_{2}$

Note the symmetry *about* the diagonal axis; that is, note the location of $-\mathbf{Z}_2$, $-\mathbf{Z}_4$, and $-\mathbf{Z}_3$ off the diagonal.



Independent Current Sources For independent current sources, the procedure is modified as follows:

- 1. Steps 1 and 2 are the same as those applied for independent sources.
- 2. Step 3 is modified as follows: Treat each current source as an open circuit (recall the *supermesh* designation in Chapter 8), and write the mesh equations for each remaining independent path. Then relate the chosen mesh currents to the dependent sources to ensure that the unknowns of the final equations are limited to the mesh currents.
- 3. Step 4 is as before.

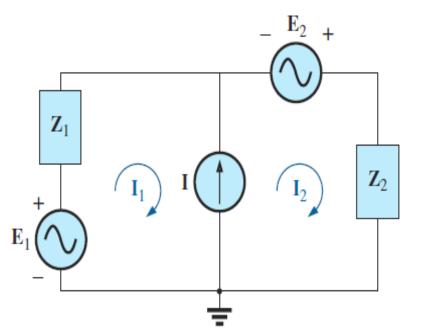
EXAMPLE 17.7 Write the mesh currents for the network in Fig. 17.13 having an independent current source.

Solution:

Steps 1 and 2 are defined in Fig. 17.13. Step 3: $\mathbf{E}_1 - \mathbf{I}_1 \mathbf{Z}_1 + \mathbf{E}_2 - \mathbf{I}_2 \mathbf{Z}_2 = 0$ (only remaining independent path)

with $\mathbf{I}_1 + \mathbf{I} = \mathbf{I}_2$

The result is two equations and two unknowns.

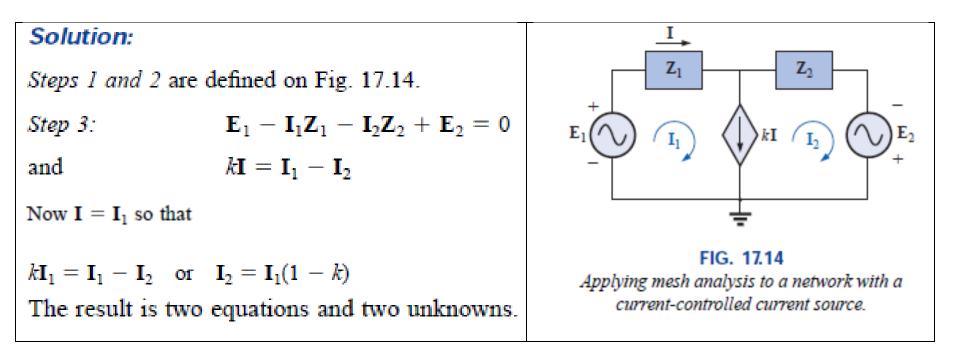


For Dependent Current Sources

The procedure for mesh analysis is modified as follows:

Treat dependent source as independent source when applying Kirchhoff's Voltage Law and Kirchhoff's Current Law except substitute their current with the controlled quantity
 Everything else is the same as before

EXAMPLE 17.8 Write the mesh currents for the network of Fig. 17.14 having a dependent current source.

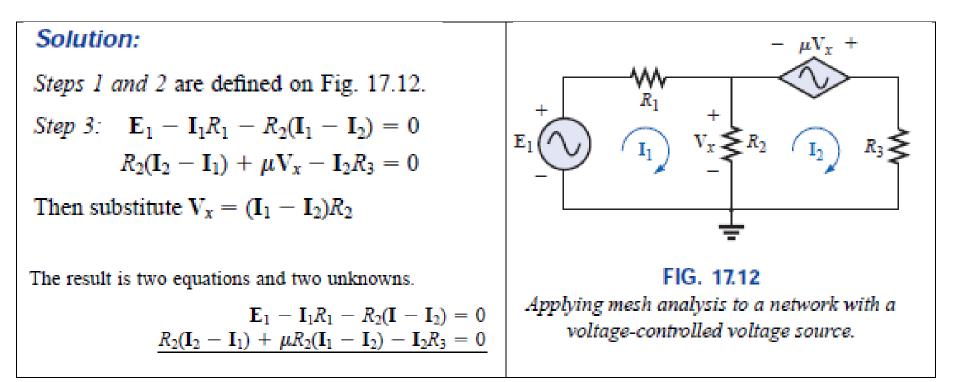


For Dependent Voltage Sources

The procedure for mesh analysis is modified as follows:

 Treat dependent source as independent source when applying Kirchhoff's voltage law except substitute their voltage with the controlled quantity
 Everything else is the same as before

EXAMPLE 17.6 Write the mesh currents for the network of Fig. 17.12 having a dependent voltage source.

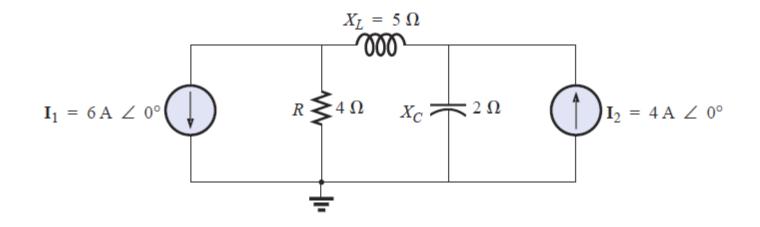


17.5 NODAL ANALYSIS (FORMAT APPROACH)

- 1. Choose a reference node and assign a subscripted voltage label to the (N 1) remaining nodes of the network.
- 2. The number of equations required for a complete solution is equal to the number of subscripted voltages (N-1).
 - a. <u>Column 1</u> of each equation is formed by summing the admittances tied to the node of interest and multiplying the result by that subscripted nodal voltage.
- 3. the mutual terms, (tying two nodes), are subtracted from the first column. It is possible to have more than one mutual term. Each mutual term is the product of the mutual admittance and the other nodal voltage tied to that admittance.
- 4. The column to the right of the equality sign is the algebraic sum of the current sources tied to the node of interest. A current source is assigned a positive sign if it supplies current to a node and a negative sign if it draws current from the node.
- 5. Solve the resulting simultaneous equations for the desired voltages.

Any Voltage Source is first converted to a Current Source (or use the supernode approach)

EXAMPLE 17.16 Using the format approach to nodal analysis, find the voltage across the 4- Ω resistor in Fig. 17.30.



Solution 1: Choosing nodes (Fig. 17.31) and writing the nodal equations, we have

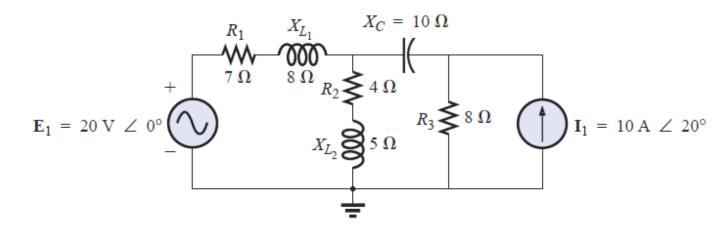
 $Z_1 = R = 4 \Omega$ $Z_2 = j X_L = j 5 \Omega$ $Z_3 = -j X_C = -j 2 \Omega$

 \mathbf{V}_1 \mathbf{V}_2 \mathbf{Z}_2 \mathbf{Z}_1 \mathbf{Z}_3 I_1 I_2 **T**Reference Using determinants yields $V_1(Y_1 + Y_2) - V_2(Y_2) = -I_1$ $V_2(Y_3 + Y_2) - V_1(Y_2) = +I_2$ $\mathbf{V}_{1} = \frac{\begin{vmatrix} -\mathbf{I}_{1} & -\mathbf{Y}_{2} \\ +\mathbf{I}_{2} & \mathbf{Y}_{3} + \mathbf{Y}_{2} \end{vmatrix}}{\begin{vmatrix} \mathbf{Y}_{1} + \mathbf{Y}_{2} & -\mathbf{Y}_{2} \\ -\mathbf{Y}_{2} & \mathbf{Y}_{3} + \mathbf{Y}_{2} \end{vmatrix}}$ or $\mathbf{V}_1(\mathbf{Y}_1 + \mathbf{Y}_2) - \mathbf{V}_2(\mathbf{Y}_2) = -\mathbf{I}_1$ $-\mathbf{V}_{1}(\mathbf{Y}_{2}) + \mathbf{V}_{2}(\mathbf{Y}_{3} + \mathbf{Y}_{2}) = +\mathbf{I}_{2}$ $= \frac{-(\mathbf{Y}_3 + \mathbf{Y}_2)\mathbf{I}_1 + \mathbf{I}_2\mathbf{Y}_2}{(\mathbf{Y}_1 + \mathbf{Y}_2)(\mathbf{Y}_3 + \mathbf{Y}_2) - \mathbf{Y}_2^2}$ $\mathbf{Y}_1 = \frac{1}{\mathbf{Z}_1}$ $\mathbf{Y}_2 = \frac{1}{\mathbf{Z}_2}$ $\mathbf{Y}_3 = \frac{1}{\mathbf{Z}_2}$ $=\frac{-(\mathbf{Y}_{3}+\mathbf{Y}_{2})\mathbf{I}_{1}+\mathbf{I}_{2}\mathbf{Y}_{2}}{\mathbf{Y}_{1}\mathbf{Y}_{3}+\mathbf{Y}_{2}\mathbf{Y}_{3}+\mathbf{Y}_{1}\mathbf{Y}_{2}}$

Substituting numerical values, we have

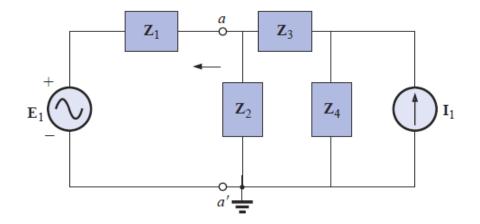
$$\begin{aligned} \mathbf{V}_{1} &= \frac{-[(1/-j\ 2\ \Omega) + (1/j\ 5\ \Omega)]6\ A\ \angle 0^{\circ} + 4\ A\ \angle 0^{\circ}(1/j\ 5\ \Omega)}{(1/4\ \Omega)(1/-j\ 2\ \Omega) + (1/j\ 5\ \Omega)(1/-j\ 2\ \Omega) + (1/4\ \Omega)(1/j\ 5\ \Omega)} \\ &= \frac{-(+j\ 0.5\ -j\ 0.2)6\ \angle 0^{\circ} + 4\ \angle 0^{\circ}(-j\ 0.2)}{(1/-j\ 8) + (1/10) + (1/j\ 20)} \\ &= \frac{(-0.3\ \angle 90^{\circ})(6\ \angle 0^{\circ}) + (4\ \angle 0^{\circ})(0.2\ \angle -90^{\circ})}{j\ 0.125\ +\ 0.1\ -j\ 0.05} \\ &= \frac{-1.8\ \angle 90^{\circ} + 0.8\ \angle -90^{\circ}}{0.1\ +j\ 0.075} \\ &= \frac{2.6\ V\ \angle -90^{\circ}}{0.125\ \angle 36.87^{\circ}} \\ \mathbf{V}_{1} &= \mathbf{20.80}\ \mathbf{V} \angle -\mathbf{126.87^{\circ}} \end{aligned}$$

EXAMPLE 17.17 Using the format approach, write the nodal equations for the network of Fig. 17.33.

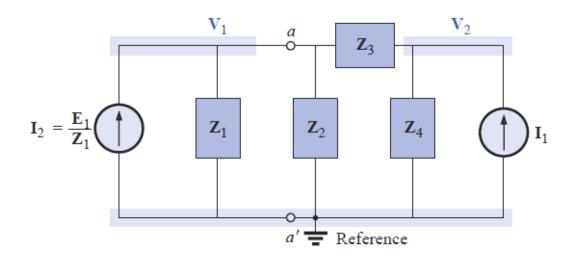


Solution: The circuit is redrawn in Fig. 17.34, where

$$\begin{aligned}
 Z_1 &= R_1 + j X_{L_1} = 7 \ \Omega + j \ 8 \ \Omega &= L_1 = 20 \ V \angle 0^\circ \\
 Z_2 &= R_2 + j X_{L_2} = 4 \ \Omega + j \ 5 \ \Omega &= I_1 = 10 \ A \angle 20^\circ \\
 Z_3 &= -j X_C = -j \ 10 \ \Omega &= I_2 \\
 Z_4 &= R_3 = 8 \ \Omega
 \end{aligned}$$



Converting the voltage source to a current source and choosing nodes, we obtain Fig. 17.35. Note the "neat" appearance of the network using the subscripted impedances. Working directly with Fig. 17.33 would be more difficult and could produce errors.



Write the nodal equations:

$$\mathbf{Y}_{1}(\mathbf{Y}_{1} + \mathbf{Y}_{2} + \mathbf{Y}_{3}) - \mathbf{V}_{2}(\mathbf{Y}_{3}) = +\mathbf{I}_{2}$$
$$\mathbf{V}_{2}(\mathbf{Y}_{3} + \mathbf{Y}_{4}) - \mathbf{V}_{1}(\mathbf{Y}_{3}) = +\mathbf{I}_{1}$$
$$\mathbf{Y}_{1} = \frac{1}{\mathbf{Z}_{1}} \qquad \mathbf{Y}_{2} = \frac{1}{\mathbf{Z}_{2}} \qquad \mathbf{Y}_{3} = \frac{1}{\mathbf{Z}_{3}} \qquad \mathbf{Y}_{4} = \frac{1}{\mathbf{Z}_{4}}$$

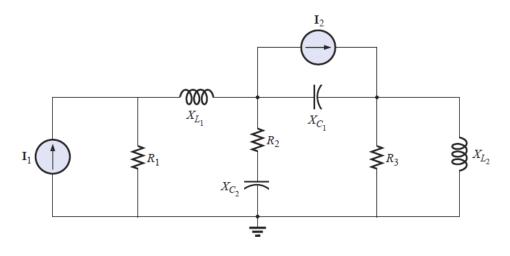
which are rewritten as

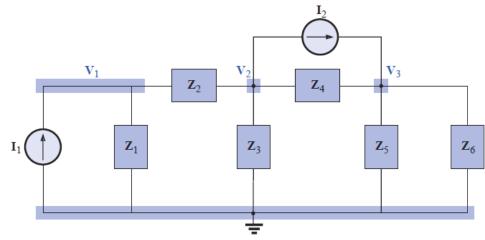
$$\mathbf{V}_{1}(\mathbf{Y}_{1} + \mathbf{Y}_{2} + \mathbf{Y}_{3}) - \mathbf{V}_{2}(\mathbf{Y}_{3}) = +\mathbf{I}_{2} \\
 -\mathbf{V}_{1}(\mathbf{Y}_{3}) + \mathbf{V}_{2}(\mathbf{Y}_{3} + \mathbf{Y}_{4}) = +\mathbf{I}_{1}$$

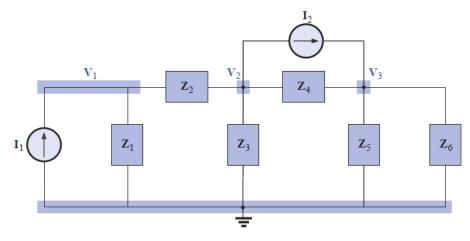
EXAMPLE 17.18 Write the nodal equations for the network of Fig. 17.36. Do not solve.

Solution: Choose nodes (Fig. 17.37):

$$Z_1 = R_1$$
 $Z_2 = j X_{L_1}$
 $Z_3 = R_2 - j X_{C_2}$
 $Z_4 = -j X_{C_1}$
 $Z_5 = R_3$
 $Z_6 = j X_{L_2}$







and write the nodal equations:

$$V_1(Y_1 + Y_2) - V_2(Y_2) = +I_1$$

$$V_2(Y_2 + Y_3 + Y_4) - V_1(Y_2) - V_3(Y_4) = -I_2$$

$$V_3(Y_4 + Y_5 + Y_6) - V_2(Y_4) = +I_2$$

which are rewritten as

$$\begin{aligned}
 \mathbf{V}_{1}(\mathbf{Y}_{1} + \mathbf{Y}_{2}) &= \mathbf{V}_{2}(\mathbf{Y}_{2}) &+ 0 &= +\mathbf{I}_{1} \\
 -\mathbf{V}_{1}(\mathbf{Y}_{2}) &+ \mathbf{V}_{2}(\mathbf{Y}_{2} + \mathbf{Y}_{3} + \mathbf{Y}_{4}) &= -\mathbf{V}_{3}(\mathbf{Y}_{4}) &= -\mathbf{I}_{2} \\
 0 &- \mathbf{V}_{2}(\mathbf{Y}_{4}) &+ \mathbf{V}_{3}(\mathbf{Y}_{4} + \mathbf{Y}_{5} + \mathbf{Y}_{6}) &= +\mathbf{I}_{2} \\
 \mathbf{Y}_{1} &= \frac{1}{R_{1}} & \mathbf{Y}_{2} &= \frac{1}{j X_{L_{1}}} & \mathbf{Y}_{3} &= \frac{1}{R_{2} - j X_{C_{2}}} \\
 \mathbf{Y}_{4} &= \frac{1}{-j X_{C_{1}}} & \mathbf{Y}_{5} &= \frac{1}{R_{3}} & \mathbf{Y}_{6} &= \frac{1}{j X_{L_{2}}}
 \end{aligned}$$

Dependent Voltage Sources between Defined Nodes

The procedure for nodal analysis is modified as follows:

 Treat dependent source as independent source when applying Kirchhoff's Current Law except substitute their voltage with the controlled quantity
 Everything else is the same as before

EXAMPLE 17.15 Write the nodal equations for the network of Fig. 17.29 having a dependent voltage source between two defined nodes.

Solution:

Steps 1 and 2 are defined in Fig. 17.29.

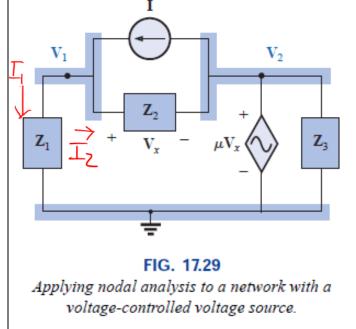
Step 3: Replacing the dependent source μV_x with a short-circuit equivalent will result in the following equation when Kirchhoff's current law is applied at node V_1 :

$$\mathbf{I} = \mathbf{I}_1 + \mathbf{I}_2$$
$$\frac{\mathbf{V}_1}{\mathbf{Z}_1} + \frac{(\mathbf{V}_1 - \mathbf{V}_2)}{\mathbf{Z}_2} - \mathbf{I} = \mathbf{0}$$

and

$$\mathbf{V}_2 = \boldsymbol{\mu} \mathbf{V}_x = \boldsymbol{\mu} [\mathbf{V}_1 - \mathbf{V}_2]$$

 $\mathbf{V}_2 = \frac{\mu}{1+\mu} \mathbf{V}_1$



or

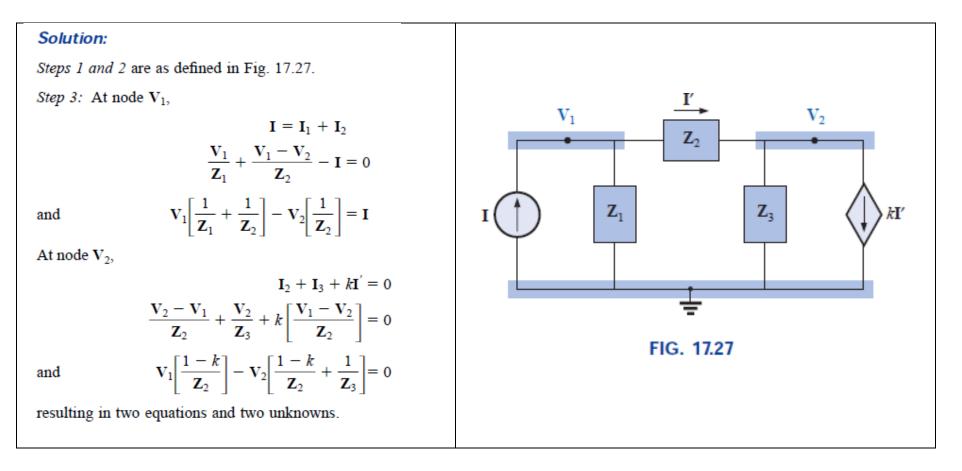
Dependent Current Sources

The procedure for nodal analysis is modified as follows:

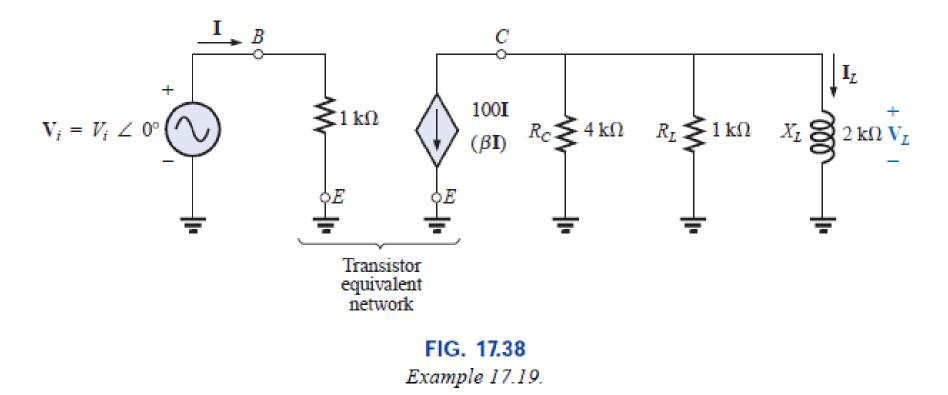
 Treat dependent source as independent source when applying Kirchhoff's Current Law except substitute their current with the controlled quantity
 Everything else is the same as before

EXAMPLE 17.13 Write the nodal equations for the network of Fig.

17.27 having a dependent current source.



EXAMPLE 17.19 Apply nodal analysis to the network of Fig. 17.38. Determine the voltage V_L .



Solution: In this case there is no need for a source conversion. The network is redrawn in Fig. 17.39 with the chosen nodal voltage and subscripted impedances.

Apply the format approach:

$$\mathbf{Y}_{1} = \frac{1}{\mathbf{Z}_{1}} = \frac{1}{4 \text{ k}\Omega} = 0.25 \text{ mS } \angle 0^{\circ} = G_{1} \angle 0^{\circ}$$
$$\mathbf{Y}_{2} = \frac{1}{\mathbf{Z}_{2}} = \frac{1}{1 \text{ k}\Omega} = 1 \text{ mS } \angle 0^{\circ} = G_{2} \angle 0^{\circ}$$
$$\mathbf{Y}_{3} = \frac{1}{\mathbf{Z}_{3}} = \frac{1}{2 \text{ k}\Omega \angle 90^{\circ}} = 0.5 \text{ mS } \angle -90^{\circ}$$
$$= -j \ 0.5 \text{ mS} = -j \ B_{L}$$
$$\mathbf{V}_{1}: \quad (\mathbf{Y}_{1} + \mathbf{Y}_{2} + \mathbf{Y}_{3}) \mathbf{V}_{1} = -100\mathbf{I}$$

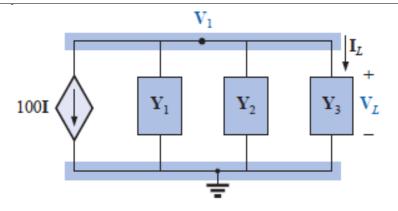


FIG. 17.39 Assigning the nodal voltage and subscripted impedances for the network of Fig. 17.38.

and
$$\mathbf{V}_{1} = \frac{-100\mathbf{I}}{\mathbf{Y}_{1} + \mathbf{Y}_{2} + \mathbf{Y}_{3}}$$
$$= \frac{-100\mathbf{I}}{0.25 \text{ mS} + 1 \text{ mS} - j \ 0.5 \text{ mS}}$$
$$= \frac{-100 \times 10^{3}\mathbf{I}}{1.25 - j \ 0.5} = \frac{-100 \times 10^{3}\mathbf{I}}{1.3463 \angle -21.80^{\circ}}$$
$$= -74.28 \times 10^{3}\mathbf{I} \angle 21.80^{\circ}$$
$$= -74.28 \times 10^{3} \left(\frac{\mathbf{V}_{i}}{1 \ \mathbf{k}\Omega}\right) \angle 21.80^{\circ}$$
$$\mathbf{V}_{1} = \mathbf{V}_{L} = -(74.28\mathbf{V}_{i}) \ \mathbf{V} \angle 21.80^{\circ}$$

17.6 BRIDGE NETWORKS (ac)

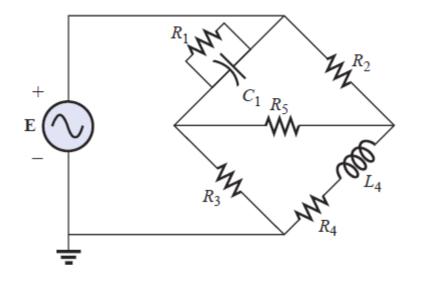
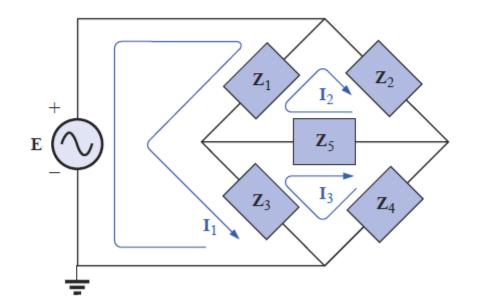


FIG. 17.40 Maxwell bridge.

MESH ANALYSIS

Apply **mesh analysis** to the network of Fig. 17.40. The network is redrawn in Fig. 17.41, where

$$\mathbf{Z}_{1} = \frac{1}{\mathbf{Y}_{1}} = \frac{1}{G_{1} + j B_{C}} = \frac{G_{1}}{G_{1}^{2} + B_{C}^{2}} - j \frac{B_{C}}{G_{1}^{2} + B_{C}^{2}}$$
$$\mathbf{Z}_{2} = R_{2} \qquad \mathbf{Z}_{3} = R_{3} \qquad \mathbf{Z}_{4} = R_{4} + j X_{L} \qquad \mathbf{Z}_{5} = R_{5}$$



Applying the format approach:

$$(\mathbf{Z}_1 + \mathbf{Z}_3)\mathbf{I}_1 - (\mathbf{Z}_1)\mathbf{I}_2 - (\mathbf{Z}_3)\mathbf{I}_3 = \mathbf{E}$$

$$(\mathbf{Z}_1 + \mathbf{Z}_2 + \mathbf{Z}_5)\mathbf{I}_2 - (\mathbf{Z}_1)\mathbf{I}_1 - (\mathbf{Z}_5)\mathbf{I}_3 = 0$$

$$(\mathbf{Z}_3 + \mathbf{Z}_4 + \mathbf{Z}_5)\mathbf{I}_3 - (\mathbf{Z}_3)\mathbf{I}_1 - (\mathbf{Z}_5)\mathbf{I}_2 = 0$$

which are rewritten as

$$\mathbf{I}_{1}(\mathbf{Z}_{1} + \mathbf{Z}_{3}) - \mathbf{I}_{2}\mathbf{Z}_{1} - \mathbf{I}_{3}\mathbf{Z}_{3} = \mathbf{E} - \mathbf{I}_{1}\mathbf{Z}_{1} + \mathbf{I}_{2}(\mathbf{Z}_{1} + \mathbf{Z}_{2} + \mathbf{Z}_{5}) - \mathbf{I}_{3}\mathbf{Z}_{5} = 0 - \mathbf{I}_{1}\mathbf{Z}_{3} - \mathbf{I}_{2}\mathbf{Z}_{5} + \mathbf{I}_{3}(\mathbf{Z}_{3} + \mathbf{Z}_{4} + \mathbf{Z}_{5}) = 0$$

Note the symmetry about the diagonal of the above equations. For balance, $\mathbf{I}_{\mathbf{Z}_5} = 0$ A, and

$$\mathbf{I}_{\mathbf{Z}_5} = \mathbf{I}_2 - \mathbf{I}_3 = \mathbf{0}$$

From the above equations,

$$\mathbf{I}_{2} = \frac{\begin{vmatrix} \mathbf{Z}_{1} + \mathbf{Z}_{3} & \mathbf{E} & -\mathbf{Z}_{3} \\ -\mathbf{Z}_{1} & 0 & -\mathbf{Z}_{5} \\ -\mathbf{Z}_{3} & 0 & (\mathbf{Z}_{3} + \mathbf{Z}_{4} + \mathbf{Z}_{5}) \end{vmatrix}}{\begin{vmatrix} \mathbf{Z}_{1} + \mathbf{Z}_{3} & -\mathbf{Z}_{1} & -\mathbf{Z}_{3} \\ -\mathbf{Z}_{1} & (\mathbf{Z}_{1} + \mathbf{Z}_{2} + \mathbf{Z}_{5}) & -\mathbf{Z}_{5} \\ -\mathbf{Z}_{3} & -\mathbf{Z}_{5} & (\mathbf{Z}_{3} + \mathbf{Z}_{4} + \mathbf{Z}_{5}) \end{vmatrix}}$$
$$= \frac{\mathbf{E}(\mathbf{Z}_{1}\mathbf{Z}_{3} + \mathbf{Z}_{1}\mathbf{Z}_{4} + \mathbf{Z}_{1}\mathbf{Z}_{5} + \mathbf{Z}_{3}\mathbf{Z}_{5})}{\Delta}$$

where Δ signifies the determinant of the denominator (or coefficients). Similarly,

$$\mathbf{I}_3 = \frac{\mathbf{E}(\mathbf{Z}_1\mathbf{Z}_3 + \mathbf{Z}_3\mathbf{Z}_2 + \mathbf{Z}_1\mathbf{Z}_5 + \mathbf{Z}_3\mathbf{Z}_5)}{\Delta}$$
$$\mathbf{I}_{\mathbf{Z}_5} = \mathbf{I}_2 - \mathbf{I}_3 = \frac{\mathbf{E}(\mathbf{Z}_1\mathbf{Z}_4 - \mathbf{Z}_3\mathbf{Z}_2)}{\Delta}$$

and

For $\mathbf{I}_{\mathbf{Z}_5} = 0$, the following must be satisfied (for a finite Δ not equal to zero):

$$\mathbf{Z}_{1}\mathbf{Z}_{4} = \mathbf{Z}_{3}\mathbf{Z}_{2} \qquad \mathbf{I}_{\mathbf{Z}_{5}} = 0 \tag{17.3}$$

NODAL ANALYSIS

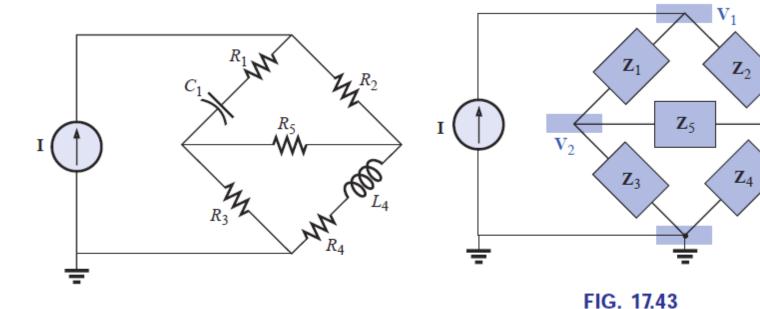


FIG. 17.42 Hay bridge.

Assigning the nodal voltages and subscripted impedances for the network of Fig. 17.42.

 V_3

$$\mathbf{Y}_{1} = \frac{1}{\mathbf{Z}_{1}} = \frac{1}{R_{1} - j X_{C}} \qquad \mathbf{Y}_{2} = \frac{1}{\mathbf{Z}_{2}} = \frac{1}{R_{2}}$$
$$\mathbf{Y}_{3} = \frac{1}{\mathbf{Z}_{3}} = \frac{1}{R_{3}} \qquad \mathbf{Y}_{4} = \frac{1}{\mathbf{Z}_{4}} = \frac{1}{R_{4} + j X_{L}} \qquad \mathbf{Y}_{5} = \frac{1}{R_{5}}$$

and

 $(\mathbf{Y}_1 + \mathbf{Y}_2)\mathbf{V}_1 - (\mathbf{Y}_1)\mathbf{V}_2 - (\mathbf{Y}_2)\mathbf{V}_3 = \mathbf{I}$ $(\mathbf{Y}_1 + \mathbf{Y}_3 + \mathbf{Y}_5)\mathbf{V}_2 - (\mathbf{Y}_1)\mathbf{V}_1 - (\mathbf{Y}_5)\mathbf{V}_3 = \mathbf{0}$ $(\mathbf{Y}_2 + \mathbf{Y}_4 + \mathbf{Y}_5)\mathbf{V}_3 - (\mathbf{Y}_2)\mathbf{V}_1 - (\mathbf{Y}_5)\mathbf{V}_2 = \mathbf{0}$ which are rewritten as

$$\begin{array}{rcl} \mathbf{V}_{1}(\mathbf{Y}_{1}+\mathbf{Y}_{2})-\mathbf{V}_{2}\mathbf{Y}_{1}&-\mathbf{V}_{3}\mathbf{Y}_{2}&=\mathbf{I}\\ -\mathbf{V}_{1}\mathbf{Y}_{1}&+\mathbf{V}_{2}(\mathbf{Y}_{1}+\mathbf{Y}_{3}+\mathbf{Y}_{5})-\mathbf{V}_{3}\mathbf{Y}_{5}&=0\\ -\mathbf{V}_{1}\mathbf{Y}_{2}&-\mathbf{V}_{2}\mathbf{Y}_{5}&+\mathbf{V}_{3}(\mathbf{Y}_{2}+\mathbf{Y}_{4}+\mathbf{Y}_{5})=0 \end{array}$$

Again, note the symmetry about the diagonal axis. For balance, $\mathbf{V}_{\mathbf{Z}_5} = 0$ V, and

$$\mathbf{V}_{\mathbf{Z}_5} = \mathbf{V}_2 - \mathbf{V}_3 = \mathbf{0}$$

From the above equations,

$$\mathbf{V}_{2} = \frac{\begin{vmatrix} \mathbf{Y}_{1} + \mathbf{Y}_{2} & \mathbf{I} & -\mathbf{Y}_{2} \\ -\mathbf{Y}_{1} & 0 & -\mathbf{Y}_{5} \\ -\mathbf{Y}_{2} & 0 & (\mathbf{Y}_{2} + \mathbf{Y}_{4} + \mathbf{Y}_{5}) \end{vmatrix}}{\begin{vmatrix} \mathbf{Y}_{1} + \mathbf{Y}_{2} & -\mathbf{Y}_{1} & -\mathbf{Y}_{2} \\ -\mathbf{Y}_{1} & (\mathbf{Y}_{1} + \mathbf{Y}_{3} + \mathbf{Y}_{5}) & -\mathbf{Y}_{5} \\ -\mathbf{Y}_{2} & -\mathbf{Y}_{5} & (\mathbf{Y}_{2} + \mathbf{Y}_{4} + \mathbf{Y}_{5}) \end{vmatrix}}$$
$$= \frac{\mathbf{I}(\mathbf{Y}_{1}\mathbf{Y}_{3} + \mathbf{Y}_{1}\mathbf{Y}_{4} + \mathbf{Y}_{1}\mathbf{Y}_{5} + \mathbf{Y}_{3}\mathbf{Y}_{5})}{\Delta}$$

Similarly,

$$\mathbf{V}_3 = \frac{\mathbf{I}(\mathbf{Y}_1\mathbf{Y}_3 + \mathbf{Y}_3\mathbf{Y}_2 + \mathbf{Y}_1\mathbf{Y}_5 + \mathbf{Y}_3\mathbf{Y}_5)}{\Delta}$$

Note the similarities between the above equations and those obtained for mesh analysis. Then

$$\mathbf{V}_{\mathbf{Z}_5} = \mathbf{V}_2 - \mathbf{V}_3 = \frac{\mathbf{I}(\mathbf{Y}_1\mathbf{Y}_4 - \mathbf{Y}_3\mathbf{Y}_2)}{\Delta}$$

For $V_{Z_5} = 0$, the following must be satisfied for a finite Δ not equal to zero:

$$Y_1 Y_4 = Y_3 Y_2$$
 $V_{Z_5} = 0$ (17.4)

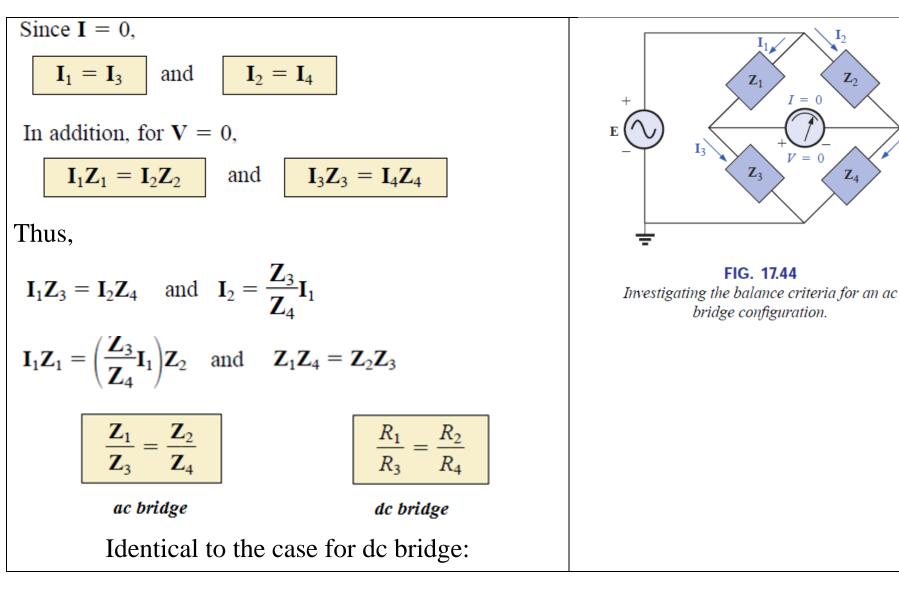
However, substituting $\mathbf{Y}_1 = 1/\mathbf{Z}_1$, $\mathbf{Y}_2 = 1/\mathbf{Z}_2$, $\mathbf{Y}_3 = 1/\mathbf{Z}_3$, and $\mathbf{Y}_4 = 1/\mathbf{Z}_4$, we have

$$\frac{1}{\mathbf{Z}_1\mathbf{Z}_4} = \frac{1}{\mathbf{Z}_3\mathbf{Z}_2}$$

or $\mathbf{Z}_1 \mathbf{Z}_4 = \mathbf{Z}_3 \mathbf{Z}_2$ $\mathbf{V}_{\mathbf{Z}_5} = 0$

BALANCE CRITERIA

 $\boldsymbol{I} = 0$ and $\boldsymbol{V} = 0$



I_4

17.7 Δ -Y, Y- Δ CONVERSIONS

